Chapter 7.2 Laminar Boundary Layers
Boundary Layer Theory

## Introduction:

Boundary layer flows: External flows around streamlined bodies at high Re have viscous (shear and no-slip) effects confined close to the body surfaces and its wake but are nearly inviscid far from the body.
Applications of BL theory: aerodynamics (airplanes, rockets, projectiles), hydrodynamics (ships, submarines, torpedoes), transportation (automobiles, trucks, cycles), wind engineering (buildings, bridges, water towers), and ocean engineering (buoys, breakwaters, cables).

Flat-Plate Momentum Integral Analysis \& Laminar approximate solution

Consider flow of a viscous fluid at high Re past a flat plate, i.e., flat plate fixed in a uniform stream of velocity $U \hat{i}$.


Boundary-layer thickness arbitrarily defined by y $=\delta_{99 \%}$ (where, $\delta_{99 \%}$ is the value of y at $\mathbf{u}=0.99 \mathrm{U}$ ). Streamlines outside $\delta_{99 \%}$ will deflect an amount $\delta^{*}$ (the displacement thickness). Thus, the streamlines move outward from $y=H$ at $x=0$ to $y=Y=\delta=H+\delta^{*}$ at $x=x_{1}$.

## Conservation of mass:

$$
\int_{c s} \rho \underline{V} \bullet \underline{n} d A=\mathbf{0}=-\int_{0}^{H} \rho U d y+\int_{0}^{H+\delta^{*}} \rho u d y
$$

Assuming incompressible flow (constant density), this relation simplifies to

$$
U H=\int_{0}^{Y} u d y=\int_{0}^{Y}(U+u-U) d y=U Y+\int_{0}^{Y}(u-U) d y
$$

Note: $Y=H+\delta^{*}$, we get the definition of displacement thickness:

$$
\delta^{*}=\int_{0}^{Y}\left(1-\frac{u}{U}\right) d y
$$

$\delta^{*}$ ( a function of x only) is an important measure of effect of BL on external flow. To see this more clearly, consider an alternate derivation based on an equivalent discharge/flow rate argument:

$\underbrace{\int_{\delta^{*}}^{\delta} U d y}=\int_{0}^{\delta} u d y$
Inviscid flow about $\delta^{*}$ body
Flowrate between $\delta^{*}$ and $\delta$ of inviscid flow=actual flowrate, i.e., inviscid flow rate about displacement body $=$ equivalent viscous flow rate about actual body

$$
\begin{aligned}
& \int_{0}^{\delta} U d y-\int_{0}^{\delta^{*}} U d y=\int_{0}^{\delta} u d y \Rightarrow \delta^{*}=\int_{0}^{\delta}\left(1-\frac{u}{U}\right) d y \\
& \text { w/o BL - displacement effect=actual discharge }
\end{aligned}
$$

For 3D flow, in addition it must also be explicitly required that $\delta^{*}$ is a stream surface of the inviscid flow continued from outside of the BL.

## Conservation of x-momentum:

$\sum F_{x}=-D=\int_{C S} \rho u \underline{V} \bullet \underline{n} d A=-\int_{0}^{H} \rho U(U d y)+\int_{0}^{Y} \rho u(u d y)$
$\operatorname{Drag}=D=\rho U^{2} H-\int_{0}^{Y} \rho u^{2} d y=$ Fluid force on plate $=-$ Plate force on CV (fluid)
Again, assuming constant density and using continuity: $H=\int_{0}^{Y} \frac{u}{U} d y$
$D=\rho U^{2} \int_{0}^{Y} u / U d y-\int_{0}^{Y} u^{2} d y=\int_{0}^{x} \tau_{w} d x$
$\frac{D}{\rho U^{2}}=\theta=\int_{0}^{Y} \frac{u}{U}\left(1-\frac{u}{U}\right) d y$
where, $\theta$ is the momentum thickness (a function of $\mathbf{x}$ only), an important measure of the drag.

$$
\begin{aligned}
& C_{D}=\frac{2 D}{\rho U^{2} x}=\frac{2 \theta}{x}=\frac{1}{x} \int_{0}^{x} C_{f} d x \quad \text { Per unit span } \\
& C_{f}=\frac{\tau_{w}}{\frac{1}{2} \rho U^{2}} \Rightarrow C_{f}=\frac{d}{d x}\left(x C_{D}\right)=2 \frac{d \theta}{d x} \\
& \begin{array}{ll}
\frac{d \theta}{d x}=\frac{C_{f}}{2} & \begin{array}{l}
\text { Special case 2D } \\
\text { momentum integral }
\end{array} \\
\text { equation for } \mathrm{p}_{\mathrm{x}}=0
\end{array}
\end{aligned}
$$



Simple velocity profile approximations:
$u=U\left(2 y / \delta-y^{2} / \delta^{2}\right)$
$\mathrm{u}(0)=0 \quad$ no slip
$\left.\begin{array}{l}\mathrm{u}(\delta)=\mathrm{U} \\ \mathrm{u}_{\mathrm{y}}(\delta)=0\end{array}\right\}$ matching with outer flow
Use velocity profile to get $\mathrm{C}_{\mathrm{f}}(\delta)$ and $\theta(\delta)$ and then integrate momentum integral equation to get $\delta\left(\operatorname{Re}_{\mathrm{x}}\right)$

$$
\begin{aligned}
& \delta^{*}=\delta / 3 \\
& \theta=2 \delta / 15 \\
& \mathrm{H}=\delta^{*} / \theta=5 / 2 \\
& \tau_{w}=\left.\mu \frac{\partial u}{\partial y}\right|_{y=0}=\mu 2 U / \delta \\
& \Rightarrow C_{f}=\frac{2 \mu U / \delta}{1 / 2 \rho U^{2}}=2 \frac{d \theta}{d x}=2 \frac{d}{d x}(2 \delta / 15)
\end{aligned}
$$

$$
\therefore \delta d \delta=\frac{15 \mu d x}{\rho U}
$$

$$
\delta^{2}=\frac{30 \mu d x}{\rho U}
$$

$$
\delta / x=5.5 / \operatorname{Re}_{x}^{1 / 2}
$$

$$
\operatorname{Re}_{x}=U x / v
$$

$$
\delta^{*} / x=1.83 / \mathrm{Re}_{x}^{1 / 2}
$$

$$
\theta / x=0.73 / \operatorname{Re}_{x}^{1 / 2}
$$

$$
C_{D}=1.46 / \mathrm{Re}_{L}^{1 / 2}=2 C_{f}(L)
$$

## Boundary layer approximations, equations, and comments



2D NS, $\rho=$ constant, neglect $g$
$u_{x}+v_{y}=0$
$u_{t}+u u_{x}+v u_{y}=-\frac{1}{\rho} \frac{\partial p}{\partial x}+v\left(u_{x x}+u_{y y}\right)$
$v_{t}+u v_{x}+v v_{y}=-\frac{1}{\rho} \frac{\partial p}{\partial y}+v\left(v_{x x}+v_{y y}\right)$
Introduce non-dimensional variables that includes scales such that all variables are of $\mathrm{O}(1)$ :
$x^{*}=x / L$
$y^{*}=\frac{y}{L} \sqrt{\operatorname{Re}}$
$t^{*}=t U / L$
$u^{*}=u / U$
$v^{*}=\frac{v}{U} \sqrt{R e}$
$p^{*}=\frac{p-p_{0}}{\rho U^{2}}$
$R e_{x}=U L / v$

The NS equations become (drop *)
$u_{x}+v_{y}=0$
$u_{t}+u u_{x}+v u_{y}=-p_{x}+\frac{1}{\underline{R e}} u_{x x}+u_{y y}$
$\frac{1}{R e}\left(v_{t}+u v_{x}+v v_{y}\right)=-\overline{p_{y}+\frac{1}{R e^{2}}} v_{x x}+\frac{1}{\underline{R e}} v_{y y}$

For large $\operatorname{Re}$ (BL assumptions) the underlined terms drop out and the BL equations are obtained.

Therefore, $y$-momentum equation reduces to
$p_{y}=0$
i.e. $p=p(x, t)$
$\Rightarrow p_{x}=-\rho\left(U_{t}+U U_{x}\right) \quad$ From Euler/Bernoulli equation for external flow

## 2D BL equations:

$u_{x}+v_{y}=0$
$u_{t}+u u_{x}+v u_{y}=\left(U_{t}+U U_{x}\right)+v u_{y y}$

## Note:

(1) $U(x, t), p(x, t)$ impressed on BL by the external flow.
(2) $\frac{\partial^{2}}{\partial x^{2}}=0$ : i.e., longitudinal (or stream-wise) diffusion is neglected.
(3) Due to (2), the equations are parabolic in x. Physically, this means all downstream influences are lost other than that contained in external flow. A marching solution is possible.
(4) Boundary conditions


No slip: $u(x, 0, t)=v(x, 0, t)=0$
Initial condition: $u(x, y, 0)$ known
Inlet condition: $u\left(x_{0}, y, t\right)$ given at $x_{0}$
Matching with outer flow: $u(x, \infty, t)=U(x, t)$
(5) When applying the boundary layer equations one must keep in mind the restrictions imposed on them due to the basic BL assumptions
$\rightarrow$ not applicable for thick BL or separated flows (although they can be used to estimate occurrence of separation).
(6) Curvilinear coordinates


Although BL equations have been written in Cartesian Coordinates, they apply to curved surfaces provided $\delta \ll \mathrm{R}$ and $\mathrm{x}, \mathrm{y}$ are curvilinear coordinates measured along and normal to the surface, respectively. In such a system we would find under the BL assumptions

$$
p_{y}=\frac{\rho u^{2}}{R}
$$

Assume $u$ is a linear function of $y: u=U y / \delta$

$$
\begin{aligned}
& \frac{d p}{d y}=\frac{\rho U^{2} y^{2}}{R \delta^{2}} \\
& p(\delta)-p(0) \propto \frac{\rho U^{2} \delta}{3 R}
\end{aligned}
$$

Or
$\frac{\Delta p}{\rho U^{2}} \propto \frac{\delta}{3 R} ;$ therefore, we require $\delta \ll R$
(7) Practical use of the BL theory

For a given body geometry:
(a) Inviscid theory gives $\mathrm{p}(\mathrm{x}) \rightarrow$ integration gives L and $\mathrm{D}=0$
(b) BL theory gives $\rightarrow \delta^{*}(x), \tau_{w}(x), \theta(x)$, etc. and predicts separation if any
(c) If separation present then no further information $\rightarrow$ must use inviscid models, BL equation in inverse mode, or NS equation.
(d) If separation is absent, integration of $\tau_{w}(x) \rightarrow$ frictional resistance and body $+\delta^{*}$, inviscid theory gives $\rightarrow \mathrm{p}(\mathrm{x})$ for body $+\delta^{*}$, can go back to (b) for more accurate BL calculation including viscous - inviscid interaction

## (8) Separation and shear stress

At the wall, $u=v=0 \rightarrow u_{y y}=\frac{1}{\mu} p_{x}$

$$
1^{\text {st }} \text { derivative u gives } \tau_{w} \rightarrow \tau_{w}=\left.\mu u y\right|_{w}
$$

$$
\tau_{w}=0 \text { separation }
$$

$2^{\text {nd }}$ derivative u depends on $p_{x}$


## Laminar Boundary Layer ( $\operatorname{Re}_{\text {trans }}=5 \times \mathbf{1 0}^{5}-3 \times \mathbf{1 0}^{6}$ ) -

 Similarity solutions (2D, steady, incompressible): method of reducing PDE to ODE by appropriate similarity transformation; also, as a result of transformation at least one coordinate lacks origin such that the solution collapses to same form at all length or time scales$$
\begin{gathered}
u_{x}+v_{y}=0 \\
u u_{x}+v u_{y}=U U_{x}+v u_{y y}
\end{gathered}
$$

BCs: $u(x, 0)=v(x, 0)=0$
$u(x, \infty)=U(x)$

+ inlet condition
For Similarity $\frac{u(x, y)}{U(x)}=F\left(\frac{y}{g(x)}\right)$ expect $g(x)$ related to $\delta(x)$
Or in terms of stream function $\psi: u=\psi_{y} v=-\psi_{x}$
For similarity $\quad \psi=U(x) g(x) f(\eta) \quad \eta=y / g(x)$

$$
u=\psi_{y}=U f^{\prime} \quad v=-\psi_{x}=-\left(U_{x} g f+U g_{x} f-U g_{x} \eta f^{\prime}\right)
$$

BC :

$$
\begin{aligned}
& u(x, 0)=0 \Rightarrow \\
& \begin{aligned}
v(x, 0)=0 \Rightarrow & U(x) f^{\prime}(0)=0 \Rightarrow f^{\prime}(0)=0 \\
& -U(x) g_{x}(x) \times 0 \times f^{\prime}(0)=0 \\
\Rightarrow & \left(U_{x}(x) g(x)+U(x) g_{x}(x)\right) f(0)=0 \\
\Rightarrow & f(0)=0
\end{aligned} \\
& u(x, \infty)=U(x) \Rightarrow U(x) f^{\prime}(\infty)=U(x) \Rightarrow f^{\prime}(\infty)=1
\end{aligned}
$$

Write boundary layer equations in terms of $\psi$

$$
\psi_{y} \psi_{y x}-\psi_{x} \psi_{y y}=U U_{x}+v \psi_{y y y}
$$

Substitute

$$
\begin{gathered}
\psi_{y y}=U f^{\prime \prime} / g \\
\psi_{y y y}=U f^{\prime \prime \prime} / g^{2} \\
\psi_{x y}=U_{x} f^{\prime}-U f^{\prime \prime} \eta g_{x} / g
\end{gathered}
$$

Assemble them together:

$$
\begin{aligned}
& \left(U f^{\prime}\right)\left(U_{x} f^{\prime}-U f^{\prime \prime} \eta \frac{g_{x}}{g}\right)-\left(U_{x} g f+U g_{x} f-U g_{x} \eta f^{\prime}\right)\left(U f^{\prime \prime} / g\right) \\
& =U U_{x}+v\left(U f^{\prime \prime \prime} / g^{2}\right) \\
& U U_{x} f^{\prime 2}-U U_{x} f f^{\prime \prime}-U^{2} g_{x} / g f f^{\prime \prime}=U U_{x}+v \frac{U}{g^{2}} f^{\prime \prime \prime} \\
& U U_{x} f^{\prime 2}-\frac{U}{g}(U g)_{x} f f^{\prime \prime}=U U_{x}+v \frac{U}{g^{2}} f^{\prime \prime \prime} \\
& f^{\prime \prime \prime}+\sqrt[\frac{g}{v}(U g)_{x}]{\mathrm{c}_{1}} f f^{\prime \prime}+\frac{g^{2}}{v} U_{x}\left(1-f^{\prime 2}\right)=0
\end{aligned}
$$

Where for similarity $C_{1}$ and $C_{2}$ are constant or function $\eta$ only

- i.e., for a chosen pair of $\mathrm{C}_{1}$ and $\mathrm{C}_{2} \rightarrow U(x), g(x)$ can be found (Potential flow is NOT known a priori)
- Then solution of $f^{\prime \prime \prime}+C_{1} f f^{\prime \prime}+C_{2}\left(1-f^{\prime 2}\right)=0$ gives $f(\eta) \rightarrow$ $u(x, y), \tau_{w}=\left.\mu \frac{\partial u}{\partial y}\right|_{w}=\frac{\mu U f^{\prime}(0)}{g}, \delta, \delta^{*}, \theta, \mathrm{H}, \mathrm{C}_{\mathrm{f}}, \mathrm{C}_{\mathrm{D}}$

The Blasius Solution for Flat-Plate Flow

$$
\mathrm{U}=\mathrm{constant} \rightarrow U_{x}=0 \rightarrow C_{2}=0
$$

Then $C_{1}=\frac{U}{v} g g_{x}$

$$
\frac{d}{d x}\left(g^{2}\right)=\frac{2 C_{1} v}{U} \quad \square g(x)=\left[2 C_{1} v x / U\right]^{1 / 2}
$$

Let $C_{1}=1$, then $g(x)=\sqrt{\frac{2 v x}{U}} \square \eta=y \sqrt{\frac{U}{2 v x}}$


Blasius equations for Flat Plate
Boundary Layer

Solutions by series technique or numerical



$$
\frac{u}{U}=0.99 \text { when } \eta=3.5 \rightarrow \frac{\delta}{x}=\frac{5}{\sqrt{\operatorname{Re}_{x}}} \quad \operatorname{Re}_{x}=\frac{U x}{v}
$$

$$
\delta^{*}=\int_{0}^{\infty}\left(1-\frac{u}{U}\right) d y=\int_{0}^{\infty}\left(1-f^{\prime}\right) d \eta \sqrt{\frac{2 v x}{U}} \rightarrow \frac{\delta^{*}}{x}=\frac{1.7208}{\sqrt{\operatorname{Re}_{x}}}
$$

$$
\theta=\int_{0}^{\infty}\left(1-\frac{u}{U}\right) \frac{u}{U} d y=\int_{0}^{\infty}\left(1-f^{\prime}\right) f^{\prime} \sqrt{\frac{2 v x}{U}} d \eta \rightarrow \sqrt{\frac{\theta}{x}}=\frac{0.664}{\sqrt{\operatorname{Re}_{x}}}
$$

$$
\begin{array}{ll}
\text { So, } \frac{\delta^{*}}{\theta}=H=2.59 \\
\tau_{w}=\left.\mu \frac{\partial u}{\partial y}\right|_{w}=\frac{\mu U f^{\prime \prime}(0)}{\sqrt{2 v x / U}} \rightarrow & C_{f}=\frac{\tau_{w}}{\frac{1}{2} \rho U^{2}}= \\
C_{D}=\frac{D}{\frac{1}{2} \rho U^{2} L}=\int_{0}^{L} C_{f} \frac{d x}{L}=\frac{1.328}{\sqrt{\operatorname{Re}_{L}}} ; & \operatorname{Re}_{L}=\frac{U L}{v} ;
\end{array}
$$

$$
\frac{v}{U}=\frac{\eta f^{\prime}-f}{\sqrt{2 e_{x}}} \ll 1 \quad \text { for } \quad \operatorname{Re}_{x} \gg 1
$$

TABLE 4-1
Numerical solution of the Blasius flat-plate relation, Eq. (4-45)

| $\boldsymbol{\eta}$ | $f(\boldsymbol{\eta})$ | $f^{\prime}(\boldsymbol{\eta})$ | $f^{\prime \prime}(\boldsymbol{\eta})$ |
| :--- | :--- | :--- | :--- |
| 0.0 | 0.0 | 0.0 | 0.46960 |
| 0.1 | 0.00235 | 0.04696 | 0.46956 |
| 0.2 | 0.00939 | 0.09391 | 0.46931 |
| 0.3 | 0.02113 | 0.14081 | 0.46861 |
| 0.4 | 0.03755 | 0.18761 | 0.46725 |
| 0.5 | 0.05864 | 0.23423 | 0.46503 |
| 0.6 | 0.08439 | 0.28058 | 0.46173 |
| 0.7 | 0.11474 | 0.32653 | 0.45718 |
| 0.8 | 0.14967 | 0.37196 | 0.45119 |
| 0.9 | 0.18911 | 0.41672 | 0.44363 |
| 1.0 | 0.23299 | 0.46063 | 0.43438 |
| 1.1 | 0.28121 | 0.50354 | 0.42337 |
| 1.2 | 0.33366 | 0.54525 | 0.41057 |
| 1.3 | 0.39021 | 0.58559 | 0.39598 |
| 1.4 | 0.45072 | 0.62439 | 0.37969 |
| 1.5 | 0.51503 | 0.66147 | 0.36180 |
| 1.6 | 0.58296 | 0.69670 | 0.34249 |
| 1.7 | 0.65430 | 0.72993 | 0.32195 |
| 1.8 | 0.72887 | 0.76106 | 0.30045 |
| 1.9 | 0.80644 | 0.79000 | 0.27825 |
| 2.0 | 0.88680 | 0.81669 | 0.25567 |
| 2.2 | 1.05495 | 0.86330 | 0.21058 |
| 2.4 | 1.23153 | 0.90107 | 0.16756 |
| 2.6 | 1.41482 | 0.93060 | 0.12861 |
| 2.8 | 1.60328 | 0.95288 | 0.09511 |
| 3.0 | 1.79557 | 0.96905 | 0.06771 |
| 3.2 | 1.99058 | 0.98037 | 0.04637 |
| 3.4 | 2.18747 | 0.98797 | 0.03054 |
| 3.6 | 2.38559 | 0.99289 | 0.01933 |
| 3.8 | 2.58450 | 0.99594 | 0.01176 |
| 4.0 | 2.78388 | 0.99777 | 0.00687 |
| 4.2 | 2.98355 | 0.99882 | 0.00386 |
| 4.4 | 3.18338 | 0.99940 | 0.00208 |
| 4.6 | 3.38329 | 0.99970 | 0.00108 |
| 4.8 | 3.58325 | 0.99986 | 0.00054 |
|  |  |  |  |
|  |  |  |  |



FIGURE 4-6
The Blasius solution for the flat-plate boundary layer: (a) numerical solution of Eq. (4-45); (b) comparison of $f^{\prime}=u / U$ with experiments by Liepmann (1943).

| Oseen | $\mathrm{C}_{\mathrm{D}}$ <br> $3-226\left(3^{\text {rd }}\right.$ <br> edition,vicous <br> flows $)$ | $<1$ |
| :---: | :---: | :---: |
| Blasius |  | $\operatorname{Re}_{L}$ |
|  |  |  |
|  |  | $\times 10^{6}$ |

LE Higher
order
correction
$C_{D}=1.328 / \sqrt{\operatorname{Re}_{L}}+2.3 / \operatorname{Re}_{L}$


Similar breakdown occurs at Trailing edge. From triple - deck theory the correction is $+2.661 / \operatorname{Re}_{L}^{7 / 8}$

Rex small therefore local breakdown of BL approximation


Fig. 7.9. Velocity distribution in the laminar boundary layer on a flat plate at zero incidence, as measured by Niknradse [20]


Fig. 7.10. Local coefficient of skin friction on a flat plate at zero incidence in incompressible flow, determined from direct measurement of shearing stress by Liepmann and Dhawan $[6,18]$
Theory: laminar from eqn. (7.32); turbulent from eqn. (21.12)

$$
\left.\begin{array}{ll}
\frac{\text { Falkner-Skan Wedge Flows }}{f^{\prime \prime \prime}+C_{1} f f^{\prime \prime}+C_{2}\left(1-f^{\prime 2}\right)=0} & f=f(\eta) \\
f(0)=f^{\prime}(0)=0, \quad f^{\prime}(\infty)=1 \\
g & \eta=y / g(x) \\
o^{2} & u / U=f^{\prime}(\eta)
\end{array}\right\}
$$

$$
C_{1}=\frac{g}{v}(U g)_{x} \quad C_{2}=\frac{g^{2}}{v} U_{x}
$$

(Blasius Solution: $\mathrm{C}_{2}=0, \mathrm{C}_{1}=1$ )
Consider $\left(U g^{2}\right)_{x}=2 U g g_{x}+g^{2} U_{x}$

$$
\begin{aligned}
& =2 U g g_{x}+2 g^{2} U_{x}-g^{2} U_{x} \\
& =2 g(U g)_{x}-g^{2} U_{x} \\
& =2 v C_{1}-v C_{2}
\end{aligned}
$$

Hence $\rightarrow \quad\left(U g^{2}\right)_{x}=v\left(2 C_{1}-C_{2}\right), \quad C_{2}=\frac{g^{2}}{v} U_{x}$
Choose $\mathrm{C}_{1}=1$ and $\mathrm{C}_{2}$ arbitrary $=\mathrm{C}$,

Integrate

$$
U g^{2}=v(2-C) x
$$

Combine

$$
\frac{U_{x}}{U}=\frac{C}{2-C} \frac{1}{x}
$$

$C=g^{2} U_{x} / v$

Then

$$
\ln U=\frac{C}{2-C} \ln x+k
$$

$$
\left\{\begin{array}{c}
U(x)=k x^{C /(2-C)} \\
g(x)=\sqrt{\frac{v(2-C)}{k}} x^{\frac{1-C}{2-C}}
\end{array}\right.
$$



Change constants

$$
\begin{gathered}
U(x)=k x^{m} \\
\eta=\frac{y}{g}=y \sqrt{\frac{m+1}{2} \frac{U}{v^{\prime} x}} \\
f^{\prime \prime \prime}+f f^{\prime \prime}+\beta\left(1-f^{\prime 2}\right)=0, \quad \beta=\frac{2 m}{m+1}, m=\frac{\beta}{2-\beta} \\
f(0)=f^{\prime}(0)=0 \quad f^{\prime}(\infty)=1
\end{gathered}
$$

Solutions for $-0.19884 \leq \beta \leq 1.0$

Separation $\left(\tau_{w}=0\right)$
Solutions show many commonly observed characteristics of BL flow:

- The parameter $\beta$ is a measure of the pressure gradient, $d p / d x$.

For $\beta>0, d p / d x<0$ and the pressure gradient is favorable. For $\beta<0$, the $d p / d x>0$ and the pressure gradient is adverse.

- Negative $\beta$ solutions drop away from Blasius profiles as separation approached
- Positive $\beta$ solutions squeeze closer to wall due to flow acceleration
- Accelerated flow: $\tau_{\text {max }}$ near wall
- Decelerated flow: $\tau_{\text {max }}$ moves toward $\delta / 2$


FIGURE 4-11
(a) Velocity profiles and (b) shear-stress profiles for the Falkner-Skan equation.

## Momentum Integral Equation

Historically similarity and other AFD methods used for idealized flows and momentum integral methods for practical applications, including pressure gradients.

Momentum integral equation, which is valid for both laminar and turbulent flow:

$$
\int_{y=0}^{\infty}(\mathrm{BL} \text { form of momentumequation }+(u-U) \text { continuity }) d y
$$

$$
\begin{aligned}
& \frac{\tau_{w}}{\rho U^{2}}=\underbrace{\frac{1}{2} C_{f}=\frac{d \theta}{d x}}_{\text {For flat plate equation } \rightarrow \frac{d U}{d x}}+(2+H) \frac{\theta}{U} \frac{d U}{d x}
\end{aligned}
$$

$$
\theta=\int_{0}^{\delta} \frac{u}{U}\left(1-\frac{u}{U}\right) d y
$$

$$
H=\frac{\delta^{*}}{\theta}
$$

$$
\delta^{*}=\int_{0}^{\delta}\left(1-\frac{u}{U}\right) d y
$$

Momentum: $u u_{x}+v u_{y}=-\frac{\partial}{\partial x}\left(\frac{p}{\rho}\right)+\frac{1}{\rho} \frac{\partial \tau}{\partial y}$
The pressure gradient is evaluated form the outer potential flow using Bernoulli equation
$p+\frac{1}{2} \rho U^{2}=$ constant
$p_{x}+\frac{1}{2} \rho 2 U U_{x}=0$
$-p_{x}=\rho U U_{x}$

$$
\begin{aligned}
& (u-U) \underbrace{\left(u_{x}+v_{y}\right)}_{\text {Continuity }}=u u_{x}+u v_{y}-U u_{x}-U v_{y} \\
& \underbrace{u u_{x}+v u_{y}-U U_{x}-\frac{1}{\rho} \tau_{y}}_{0}+\underbrace{u u_{x}+u v_{y}-U u_{x}+U v_{y}}_{0}=0 \\
& -\frac{1}{\rho} \tau_{y}=-2 u u_{x}-v u_{y}+U U_{x}-u v_{y}+U u_{x}+U v_{y} \\
& =\frac{\partial}{\partial x}\left(u U-u^{2}\right)+(U-u) U_{x}+\frac{\partial}{\partial y}(v U+v u) \\
& \int_{0}^{\infty}-\frac{1}{\rho} \tau_{y} d y=-\left(\tau / \sigma_{\infty}^{0}-\tau_{w}\right) / \rho=\frac{\partial}{\partial x} \int_{0}^{\infty} u(U-u) d y+U_{x} \int_{0}^{\infty}(U-u) d y+\left.(v U /-v u)\right|_{0} ^{\infty} \\
& \frac{\tau_{w}}{\rho}=\frac{\partial}{\partial x}\left[U^{2} \int_{0}^{\infty} \frac{u}{U}\left(1-\frac{u}{U}\right) d y+U_{x} \int_{0}^{\infty}(U-u) d y\right]= \\
& U^{2} \theta_{x}+2 U U_{x} \theta+U_{x} \delta^{*} \\
& \frac{C_{f}}{2}=\frac{d \theta}{d x}+\left(2 \theta+\delta^{*}\right) \frac{1}{U} \frac{d U}{d x} \\
& \frac{C_{f}}{2}=\frac{d \theta}{d x}+(2+H) \frac{\theta}{U} \frac{d U}{d x}, H=\frac{\delta^{*}}{\theta} \\
& \frac{\tau_{w}}{\rho U^{2}}=\frac{1}{2} C_{f}=\theta_{x}+(2+H) \frac{\theta}{U} U_{x}
\end{aligned}
$$

Historically two approaches for solving the momentum integral equation for specified potential flow $U(x)$ :

## 1. Guessed Profiles

2. Empirical Correlations

Best approach is to use empirical correlations to get integral parameters $\left(\delta, \delta^{*}, \theta, H, \mathrm{C}_{\mathrm{f}}, \mathrm{C}_{\mathrm{D}}\right)$ after which use these to get velocity profile $\mathrm{u} / \mathrm{U}$

## Thwaites Method

Multiply momentum integral equation by $\frac{U \theta}{v}$
$\frac{\tau_{w} \theta}{\mu U}=\frac{U \theta}{v} \frac{d \theta}{d x}+\frac{\theta^{2}}{v} \frac{d U}{d x}(2+H)$
The equation is dimensionless and, LHS and H can be correlated with pressure gradient parameter $\lambda=\frac{\theta^{2}}{v} \frac{d U}{d x}$ as shear and shape-factor correlations

$$
\begin{aligned}
& \frac{\tau_{w} \theta}{\mu U}=S(\lambda)=(\lambda+0.09)^{0.62} \\
& H=\delta^{*} / \theta=H(\lambda)=\sum_{i=0}^{5} a_{i}(0.25-\lambda)^{i}
\end{aligned}
$$

$a_{i}=(2,4.14,-83.5,854,-3337,4576)$
Note
$\frac{U \theta}{\nu} \frac{d \theta}{d x}=\frac{1}{2} U \frac{d}{d x}\left(\frac{\theta^{2}}{\vartheta}\right)$

Substitute above into momentum integral equation
$S(\lambda)=\frac{1}{2} U \frac{d}{d x}\left(\frac{\theta^{2}}{v}\right)+\lambda(2+H)$
$U \frac{d\left(\lambda / U_{x}\right)}{d x}=2[S-\lambda(2+H) \lambda]=F(\lambda)$
$F(\lambda)=0.45-6 \lambda$ based on AFD and EFD

Define $z=\frac{\theta^{2}}{v}$ so that $\lambda=z \frac{d U}{d x}$

$$
\begin{aligned}
& U \frac{d z}{d x}=0.45-6 \lambda=0.45-6 z \frac{d U}{d x} \\
& U \frac{d z}{d x}+6 z \frac{d U}{d x}=0.45 \\
& \text { i.e., } \frac{1}{U^{5}} \frac{d}{d x}\left(z U^{6}\right)=0.45 \\
& z U^{6}=0.45 \int_{0}^{x} U^{5} d x+C
\end{aligned}
$$

$$
\Rightarrow \theta^{2}=\theta_{0}^{2}+\frac{0.45 v}{U^{6}} \int_{0}^{x} U^{5} d x
$$

$\theta_{0}(x=0)=0$ and $\mathrm{U}(\mathrm{x})$ known from potential flow solution

Complete solution:
$\lambda=\lambda(\theta)=\frac{\theta^{2}}{v} \frac{d U}{d x}$
$\frac{\tau_{w} \theta}{\mu U}=S(\lambda)$
$\delta^{*}=\theta H(\lambda)$
Accuracy: mild $p_{x} \pm 5 \%$ and strong adverse $p_{x}\left(\tau_{w}\right.$ near 0$) \pm 15 \%$

## i. Pohlhausen Velocity Profile:

$$
\frac{u}{U}=f(\eta)=a \eta+b \eta^{2}+c \eta^{3}+d \eta^{4} \text { with } \eta=\frac{y}{\delta}
$$

$\mathrm{a}, \mathrm{b}, \mathrm{c}, \mathrm{d}$ determined from boundary conditions

1) $y=0 \rightarrow u=0, u_{y y}=-\frac{U}{v} U_{x}$
2) $y=\delta \rightarrow u=U, u_{y}=0, u_{y y}=0$

No slip is automatically satisfied.

$$
\begin{aligned}
& F(\eta)=2 \eta-2 \eta^{3}+\eta^{4} \\
& G(\eta)=\frac{\eta}{6}(1-\eta)^{3}
\end{aligned}
$$

separation

$$
\Lambda=\frac{\delta^{2}}{v} \frac{d U}{d x}=-p_{x} \frac{\delta^{2}}{\mu U}
$$

pressure gradient parameter related to

$$
\lambda=\lambda(\Lambda)=\left(\frac{37}{315}-\frac{\Lambda}{945}+\frac{\Lambda^{2}}{9072}\right) \Lambda
$$

Profiles are fairly realistic, except near separation. In guessed profile methods $u / U$ directly used to solve momentum integral equation numerically, but accuracy not as good as empirical correlation methods; therefore, use Thwaites's method to get $\lambda$, etc., and then use $\lambda$ to get $\Lambda$ and plot $\mathrm{u} / \mathrm{U}$.

## ii. Howarth linearly decelerating flow (example of exact solution of steady state 2D boundary layer)



Howarth proposed a linearly decelerating external velocity distribution $U(x)=U_{0}\left(1-\frac{x}{L}\right)$ as a theoretical model for laminar boundary layer study. Use Thwaites's method to compute:
a) $X_{\text {sep }}$
b) $C_{f}\left(\frac{x}{L}=0.1\right)$

Note $U_{x}=-U_{0} / L$
Solution

$$
\theta^{2}=\frac{0.45 v}{U_{0}^{6}\left(1-\frac{x}{L}\right)^{6}} \int_{0}^{x} U_{0}^{5}\left(1-\frac{x}{L}\right)^{5} d x=0.075 \frac{v L}{U_{0}}\left[\left(1-\frac{x}{L}\right)^{-6}-1\right]
$$

can be evaluated for given $L, \operatorname{Re}_{L}$

$$
\theta=0 \rightarrow x=0
$$

(Note:

$$
\theta=\infty \rightarrow x=L
$$

$\lambda=\frac{\theta^{2}}{v} \frac{d U}{d x}=-0.075\left[\left(1-\frac{x}{L}\right)^{-6}-1\right]$
$\lambda_{\text {sep }}=-0.09 \Rightarrow \frac{X_{\text {sep }}}{L}=0.123$
$3 \%$ higher than exact solution $=0.1199$
$C_{f}\left(\frac{x}{L}=0.1\right) \rightarrow$ i.e. just before separation
$\lambda=-0.0661$
$S(\lambda)=0.099=\frac{1}{2} C_{f} \mathrm{Re}_{\theta}$
$C_{f}=\frac{2(0.099)}{\operatorname{Re}_{\theta}}$
Compute $\mathrm{Re}_{\theta}$ in terms if $\mathrm{Re}_{\mathrm{L}}$
$\theta^{2}=0.075 \frac{v L}{U_{0}}\left[(1-0.1)^{-6}-1\right]=0.0661 \frac{\vartheta L}{U_{0}}$
$\frac{\theta^{2}}{L^{2}}=0.0661 \frac{v L}{U_{0}}=\frac{0.0661}{\operatorname{Re}_{L}}$
$\frac{\theta}{L}=\frac{0.257}{\operatorname{Re}_{L}^{1 / 2}}$
$\operatorname{Re}_{\theta}=\frac{\theta}{L} \operatorname{Re}_{L}=0.257 \operatorname{Re}_{L}^{1 / 2}$
To complete solution must
$C_{f}=\frac{2(0.099)}{0.257} \operatorname{Re}_{L}^{-1 / 2}=0.77 \mathrm{Re}_{L}^{-1 / 2} \longrightarrow$ specify $\mathrm{Re}_{\mathrm{L}}$

Consider the complex potential
$F(z)=\frac{a}{2} z^{2}=\frac{a}{2} r^{2} e^{2 i \theta}$
$\varphi=\operatorname{Re}[F(z)]=\frac{a}{2} r^{2} \cos 2 \theta$
$\psi=\operatorname{Im}[F(z)]=\frac{a}{2} r^{2} \sin 2 \theta$
Orthogonal rectangular hyperbolas
$\varphi$ : asymptotes $\mathrm{y}= \pm \mathrm{x}$
$\psi$ : asymptotes $\mathrm{x}=0, \mathrm{y}=0$

1) determine $a$ such that $v_{r}=U_{0}$ at $\mathrm{r}=\mathrm{L}, \theta=90^{\circ}$

$$
v_{r}=a L \cos (2 \times 90)=U_{0} \Rightarrow a L=-U_{0}, \text { i.e. } a=-\frac{U_{0}}{L}
$$

2) let $U(x)=v_{r}$ at $\mathrm{x}=\mathrm{L}-\mathrm{r}$ :

$$
\Rightarrow v_{r}=a(L-x) \cos (2 \times 90)=U(x)
$$

$$
\text { Or: } U(x)=-a(L-x)=\frac{U_{0}}{L}(L-x)=U_{0}\left(1-\frac{x}{L}\right)
$$

$$
\begin{aligned}
& \begin{array}{l}
\left.\left\{\begin{array}{l}
\underline{V}=\nabla \varphi=\varphi_{r} \hat{e}_{r}+\frac{1}{r} \varphi_{\theta} \hat{e}_{\theta} \\
v_{r}=\operatorname{arcos} 2 \theta \\
v_{\theta}=-\operatorname{arsin} 2 \theta
\end{array}\right\} \quad \begin{array}{c}
\hat{e}_{r}=\operatorname{cnoz} \\
\frac{\pi}{2} \leq \theta \leq 0 \text { (flow direction }
\end{array}\right\} \\
\underline{V}=v_{r}(\cos \theta \hat{i}+\sin \theta \hat{j})+v_{\theta}(-\sin \theta \hat{i}+\cos \theta \hat{j})=
\end{array} \\
& \left(v_{r} \cos \theta-v_{\theta} \sin \theta\right) \hat{i}+\left(v_{r} \sin \theta+v_{\theta} \cos \theta\right) \hat{j} \\
& { }^{4} \text { Potential flow slips along surface: (consider } \theta=90^{\circ} \text { ) }
\end{aligned}
$$



Fig. 10.2. The fanctiona $F(\eta)$ and $G(\eta)$ for the velocity dintribution in the boundary


Mg, 10.4. The one-parameter family of veloeity profilen from eqn. ( 10.2 en)


## Boundary layer with pressure gradient

$$
\begin{aligned}
& u_{x}+v_{y}=0 \\
& u u_{x}+v u_{y}=-\frac{\partial}{\partial x}(p / \rho)+\frac{1}{\rho} \frac{\partial \tau}{\partial y} \\
& \tau=\mu \frac{\partial u}{\partial y}-\rho \overline{u^{\prime} v^{\prime}}
\end{aligned}
$$

The pressure gradient term has a large influence on the solution. In particular, adverse pressure gradient (i.e. increasing pressure) can cause flow separation. Recall that the $y$ momentum equation subject to the boundary layer assumptions reduced to

$$
\mathrm{p}_{\mathrm{y}}=0 \text { i.e., } \mathrm{p}=\mathrm{p}_{\mathrm{e}}=\text { constant across BL. }
$$

That is, pressure (which drives BL equations) is given by external inviscid flow solution which in many cases is also irrotational. Consider a typical inviscid flow solution (chapter 8)


Even without solving the BL equations we can deduce information about the shape of the velocity profiles just by evaluating the BL equations at the wall $(\mathrm{y}=0)$
$\mu \frac{\partial^{2} u}{\partial y^{2}}=\frac{\partial p_{e}}{\partial x}$
where $\frac{\partial p_{e}}{\partial x}=-\rho \mathrm{U}_{\mathrm{e}} \frac{d U_{e}}{d x}$
which shows that the curvature of the velocity profile at the wall is related to the pressure gradient.

## Effect of Pressure Gradient on Velocity Profiles

Point of inflection: a point where a graph changes between concave upward and concave downward.
The point of inflection is basically the location where second derivative of $u$ is zero, i.e., $\frac{\partial^{2} u}{\partial y^{2}}=0$
(a) favorable gradient: $\mathrm{p}_{\mathrm{x}}<0, \mathrm{U}_{\mathrm{x}}>0, \mathrm{u}_{\mathrm{yy}}<0$


No point of inflection i.e. curvature is negative all across the BL and BL is very resistant to separation. Note $\mathrm{u}_{\mathrm{yy}}(\delta)<0$ in order for u to merge smoothly with U .
(b) zero gradient: $\mathrm{p}_{\mathrm{x}}=\mathrm{U}_{\mathrm{x}}=\mathrm{u}_{\mathrm{yy}}=0$


PI at wall no equation
(c) weak adverse gradient: $\mathrm{p}_{\mathrm{x}}>0, \mathrm{U}_{\mathrm{x}}<0, \mathrm{u}_{\mathrm{yy}}>0$


PI in flow, still no separation
(d) critical adverse gradient: $\mathrm{p}_{\mathrm{x}}>0, \mathrm{U}_{\mathrm{x}}<0, \mathrm{u}_{\mathrm{yy}}>0, \mathrm{u}_{\mathrm{y}}=0$


PI in flow, incipient separation
(e) excessive adverse gradient: $\mathrm{p}_{\mathrm{x}}>0, \mathrm{U}_{\mathrm{x}}<0, \mathrm{u}_{\mathrm{yy}}>0, \mathrm{u}_{\mathrm{y}}<0$

$$
\tau_{\mathrm{w}}<0
$$



PI in flow, backflow near wall i.e. separated flow region
i.e. main flow breaks away or separates from the wall: large increase in drag and loss of performance:
$\mathrm{H}_{\text {separation }}=3.5$ laminar
$=2.4$ turbulent

## 3-D Integral methods

Momentum integral methods perform well (i.e. compare well with experimental data) for a large class of both laminar and turbulent 2D flows. However, for 3D flows they do not, primarily due to the inability of correlating the cross flow velocity components.


The cross flow is driven by $\frac{\partial p}{\partial z}$, which is imposed on BL from the outer potential flow $\mathrm{U}(\mathrm{x}, \mathrm{z})$.

3-D boundary layer equations

$$
\begin{aligned}
& u u_{x}+v u_{y}+w u_{z}=-\frac{\partial}{\partial x}(p / \rho)+\vartheta u_{y y}-\frac{\partial}{\partial y}\left(\overline{u^{\prime} v^{\prime}}\right) \\
& u w_{x}+v w_{y}+w w_{z}=-\frac{\partial}{\partial z}(p / \rho)+\vartheta w_{y y}-\frac{\partial}{\partial y}\left(\overline{v^{\prime} w^{\prime}}\right) \\
& u_{x}+v_{y}+w_{z}=0 \\
& + \text { closure equations }
\end{aligned}
$$

Differential methods have been developed for this reason as well as for extensions to more complex and non-thin boundary layer flows.

