

Problem 3

For the given load,

$$\boldsymbol{\sigma} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

which can be used to obtain,

$$W = \frac{\sigma^2}{2E}.$$

From Hooke's law,

$$\boldsymbol{\varepsilon} = \begin{bmatrix} -\nu\sigma/E & 0 & 0 \\ 0 & \sigma/E & 0 \\ 0 & 0 & -\nu\sigma/E \end{bmatrix},$$

which can be integrated to obtain

$$\mathbf{u} = \begin{Bmatrix} u_x \\ u_y \\ u_z \end{Bmatrix} = \begin{Bmatrix} -\nu\sigma x/E \\ \sigma y/E \\ -\nu\sigma z/E \end{Bmatrix} \quad \text{and} \quad \frac{\partial \mathbf{u}}{\partial x} = \begin{Bmatrix} \partial u_x / \partial x \\ \partial u_y / \partial x \\ \partial u_z / \partial x \end{Bmatrix} = \begin{Bmatrix} -\nu\sigma/E \\ 0 \\ 0 \end{Bmatrix}.$$

Also,

$$\mathbf{n} = \begin{Bmatrix} n_x \\ n_y \\ n_z \end{Bmatrix} = \begin{Bmatrix} \cos \theta \\ \sin \theta \\ 0 \end{Bmatrix}$$

and

$$y = R \sin \theta; \quad dy = R \cos \theta d\theta; \quad d\Gamma = R d\theta.$$

Hence,

$$\mathbf{T} = \boldsymbol{\sigma} \mathbf{n} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \sigma & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} \cos \theta \\ \sin \theta \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0 \\ \sigma \sin \theta \\ 0 \end{Bmatrix}$$

and

$$\mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial x} = \mathbf{T}^T \frac{\partial \mathbf{u}}{\partial x} = \begin{Bmatrix} 0 & \sigma \sin \theta & 0 \end{Bmatrix} \begin{Bmatrix} -\nu\sigma/E \\ 0 \\ 0 \end{Bmatrix} = 0.$$

Also,

$$\int_{\Gamma} W dy = \int_0^{2\pi} \frac{\sigma^2}{2E} R \cos \theta d\theta = \frac{\sigma^2}{2E} R [\sin \theta]_0^{2\pi} = 0$$

Therefore,

$$J = \int_{\Gamma} \left[W dy - \mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial x} d\Gamma \right] = \int_{\Gamma} W dy - \int_{\Gamma} \mathbf{T} \cdot \frac{\partial \mathbf{u}}{\partial x} d\Gamma = 0 - 0 = 0.$$