

Control System

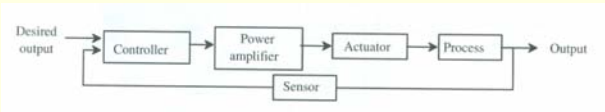
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Generic Control Loop



Manwell *et al.* (2002), p. 330

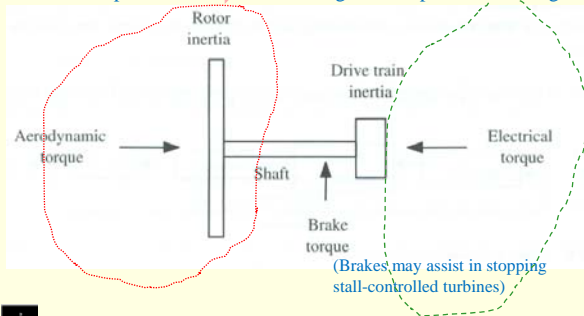


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Simple Turbine Model

Control problem → Rotor and generator power balancing +



Manwell *et al.* (2002), p. 329



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Goals of Turbine Control

- ✓ Maximization of energy production
- ✓ Safe turbine operations
- ✓ Minimization of operations and maintenance costs (by reducing loads and increasing life-time of components and subsystems)

Power (torque) balancing



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Typical Control Strategies (1)

Below rated power

$U_{cut-in} < U < U_{rated}$

- Fixed speed: Stall regulated, Pitch regulated
- Variable speed: Stall regulated, Pitch regulated

Above rated power

$U_{rated} < U < U_{stall}$

- Fixed speed: Stall regulated, Pitch regulated
- Variable speed: Stall regulated, Pitch regulated

$U = \text{wind speed}$

$U_{cut-in}, U_{cut-out} = \text{cut-in, cut-out wind speed}$

$P = \text{RPM} \times \text{Torque}$

$\lambda = \frac{r \omega}{V}$

$P = \frac{1}{2} \rho A C_p(\lambda) V^3$

Max power **Power limitation**

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Typical Control Strategies (2)

$U_{cut-in} < U < U_{rated}$

- Fixed speed: Stall regulated, Pitch regulated
- Variable speed: Stall regulated, Pitch regulated

Examples

- Fixed speed, stall – synchronous generator; AC
- Fixed speed, stall – asynchronous generator; AC
- Fixed speed, pitch – synchronous generator; AC
- Fixed speed, pitch – asynchronous generator; AC
- Variable speed, stall – asynchronous generator; AC
- Variable speed, pitch – asynchronous generator; AC

$P = \text{RPM} \times \text{Torque}$

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Typical Control Strategies (3)

$U_{cut-in} < U < U_{stall}$

- Fixed speed: Stall regulated, Pitch regulated
- Variable speed: Stall regulated, Pitch regulated

Examples

- Fixed speed, stall – synchronous generator; AC
- Fixed speed, stall – asynchronous generator; AC
- Fixed speed, pitch – synchronous generator; AC
- Fixed speed, pitch – asynchronous generator; AC
- Variable speed, stall – asynchronous generator; AC
- Variable speed, pitch – asynchronous generator; AC

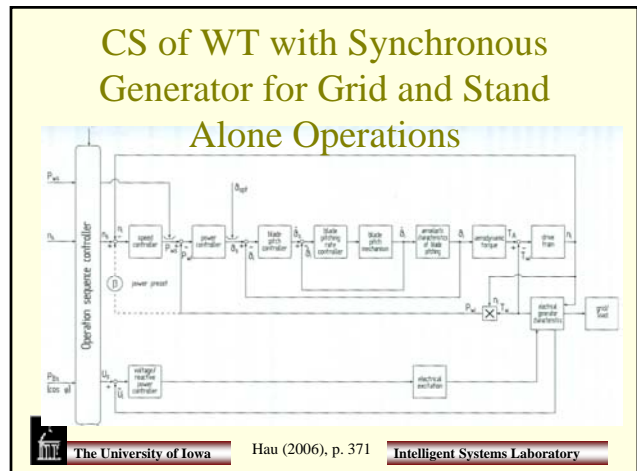
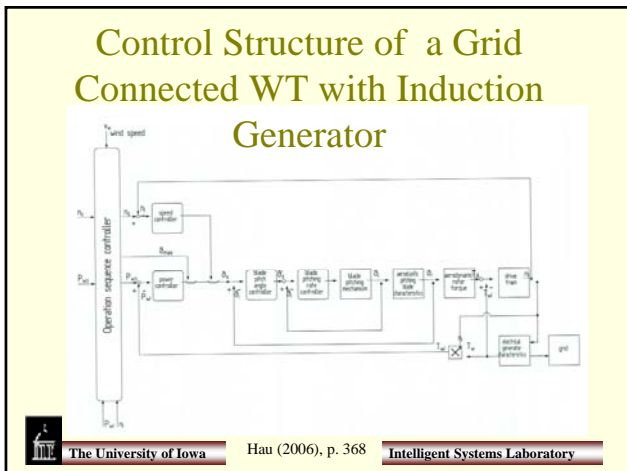
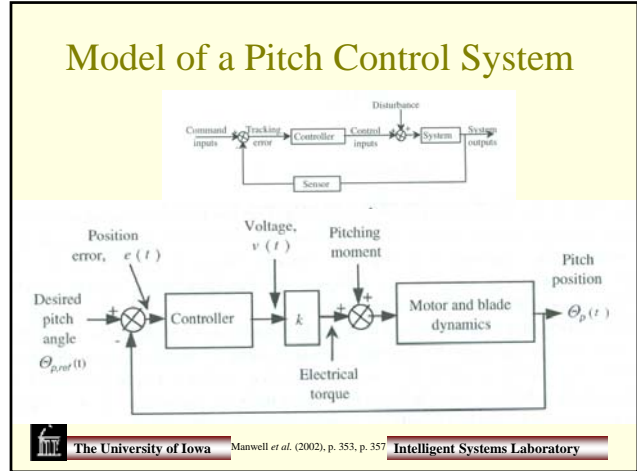
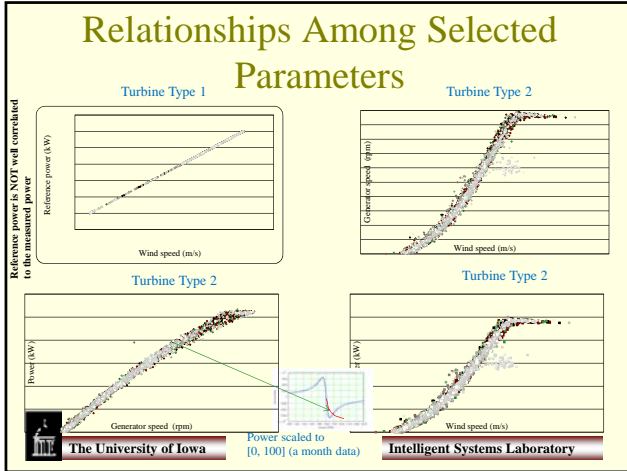
$P = \text{RPM} \times \text{Torque}$

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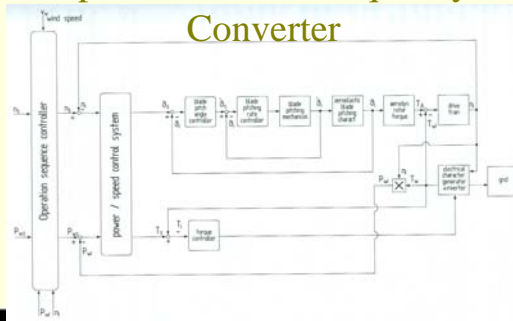
Variable-Speed Closed Loop Control

$P = \text{RPM} \times \text{Torque}$

The University of Iowa Manwell et al. (2002), p. 362 Intelligent Systems Laboratory



Control Structure a Variable Speed WT with Frequency Converter



The University of Iowa Hau (2006), p. 373 Intelligent Systems Laboratory



Wind Turbine Controller

✓ The wind turbine controller consists of a number of computers continuously monitoring the condition of the wind turbine and collect data on its operations

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- ✓ The controller also controls a large number of switches, hydraulic pumps, valves, and motors within the wind turbine
- ✓ As wind turbine sizes increase to megawatt machines, it becomes even more important that they have a high availability rate, i.e., that they function reliably all the time

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Communicating with the Outside World

- ✓ The controller communicates with the operator of the wind turbine via a communications link, e.g., sending alarms or requests for service over the Internet or a radio link
- ✓ It is also possible to remotely collect data, and check turbine's status
- ✓ In wind parks, a control room is usually available for collecting data from all wind turbines in the park
- ✓ The substation is connected to a central control room

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A fiber optics communications unit

Internal Communications

- ✓ There is usually a controller both at the bottom of the tower and in the nacelle
- ✓ In recent wind turbine models, the communication between the controllers is usually done using fiber optics
- ✓ In some recent models, a third controller is placed in the hub of the rotor
- ✓ This unit usually communicates with the nacelle unit using serial communications through a cable connected with slip rings and brushes on the main shaft

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Fail Safe Mechanisms and Redundancy

- ✓ Computers and sensors are usually duplicated (redundant) in all safety or operation sensitive areas of large machines
- ✓ The controller continuously compares the readings from measurements throughout the wind turbine to ensure that both the sensors and the computers themselves are OK



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What is Monitored?

- ✓ It is possible to monitor or set somewhere between 100 and 500 parameters in a modern wind turbine
- ✓ The controller may check:
 - ✓ The rotational speed of the rotor
 - ✓ The generator status
 - ✓ Its voltage and current
- ✓ In addition, lightning strikes and their charge may be registered
- ✓ Furthermore measurements are recorded:
 - ✓ Outside air temperature
 - ✓ Temperature in the electronic cabinets
 - ✓ Oil temperature in the gearbox
 - ✓ The temperature of the generator windings
 - ✓ The temperature in gearbox bearings

Different time scales



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What is Monitored?

Example

- ✓ Hydraulic pressure
- ✓ The pitch angle of each rotor blade (for pitch controlled or active stall controlled machines),
- ✓ The yaw angle (by counting the number of teeth on yaw wheel)
- ✓ The number of power cable twists, wind direction,
- ✓ Wind speed from the anemometer,
- ✓ Vibrations in the nacelle and the rotor blades
- ✓ The thickness of the brake linings
- ✓ The tower door is open or closed (alarm system)



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Control Strategies

- ✓ The way a controller interacts with the wind turbine components is usually proprietary to turbine manufacturers
- ✓ Control strategies are responsible for increase in wind turbine productivity
- ✓ An interesting strategy pursued by some manufacturers is to adapt the operational strategy to the local wind climate
- ✓ In this way it may, e.g., be possible to minimize tear and wear of the machine during (rare) periods of rough weather



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Controlling Power Quality from Wind Turbines



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A high voltage section of a controller of a megawatt machine

- ✓ Many think of the controller as the unit **running the wind turbine**, e.g., yaws it against the wind, checks that the safety systems are OK, and starts the turbine
- ✓ The controller performs indeed all these things, but it also looks after the **power quality** of the current generated by the wind turbine



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Grid Connection and Power Quality

- ✓ Electric utilities require that wind turbines connect "softly" to the grid



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Reactive Power Control

- ✓ **Voltage and current** are typically **measured** 128 times per alternating current cycle, (i.e., 50 x 128 times per second or 60 x 128 times per second, depending on the electrical grid frequency)
- ✓ On this basis, a Digital Signal Processor (DSP) processor **calculates the stability of the grid frequency and the active and reactive power of the turbine**
(The reactive power component basically amounts to whether the **voltage and the current are in phase** or not)



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Capacitor bank

Reactive Power Control

- ✓ To ensure the proper power quality, the controller may **switch on or off a number of capacitors** adjusting the **reactive power** (i.e., the **phase angle** between the voltage and the current)
- ✓ As shown above the switchable capacitor bank is quite large in a megawatt sized machine



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A radiation free room with metal walls in the laboratory of one of the largest wind turbine controller manufacturers. The electromagnetic emissions from the components of the controllers are measured in this room.

Electromagnetic Compatibility (EMC)

- ✓ There are powerful electromagnetic fields around power cables and generators in a wind turbine
- ✓ This means that the electronics in the controller system has to be insensitive to electromagnetic fields
- ✓ Conversely, the electronics should not emit electromagnetic radiation which can inhibit the functioning of other electronic equipment



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