

A function g(t) defined for all $t = (t_1, t_2, \dots, t_m)$ in \mathbb{R}^{m} with $t_{i} > 0$ for all i=1, 2, ... m is called a *posynomial* if it is of the form

$$\mathbf{g}(t) = \sum_{i=1}^{n} \mathbf{c}_{i} \prod_{j=1}^{m} \mathbf{t}_{j}^{\mathbf{a}_{ij}}$$

where the ci's are *positive* constants, and the exponents a_{ii}'s are real numbers

©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998

(unconstrained case)

Minimize the posynomial $g(t) = \sum_{i=1}^{n} c_i \prod_{i=1}^{m} t_j^{a_{ij}}$ subject to $t_i > 0$ for j=1,2, ... m

©D. Bricker, U. of IA, 1998 Rewrite g(t): $g(t) = \sum_{i=1}^{n} \delta_i \left(\frac{c_i \prod_{j=1}^{m} t_j^{a_{i,j}}}{\delta_i} \right) \text{ where } \delta_i > 0$ $and \sum_{i=1}^{n} \delta_i = 1$

 $g(t) = \sum_{i=1}^{n} c_i \prod_{j=1}^{m} t_j^{a_{ij}}$ $\frac{2z\sqrt{y}}{x} \qquad i.e., \ 2x^{-2} y^{\frac{1}{2}} z$

 $\frac{\sqrt{x_1}}{x_2}$ + 3x₂²x₃ *i.e.*, x₁^{0.5}x₂⁻¹ + 3x₂²x₃

Note that not all posynomials are polynomials, and not all polynomials are posynomials!

Apply the Arithmetic-Geometric Mean Inequality:

$$g(t) \geq \prod_{i=1}^{n} \left(\frac{c_{i} \prod_{j=1}^{m} t_{j}^{a_{ij}}}{\delta_{i}} \right)^{\delta_{i}} = \prod_{i=1}^{n} \left(\frac{c_{i}}{\delta_{i}} \right)^{\delta_{i}} \left(\prod_{i=1}^{n} \prod_{j=1}^{m} t_{j}^{a_{ij}\delta_{i}} \right)$$

©D. Bricker, U. of IA, 1998

Under the restrictions that

Examples of posynomials

$$\begin{array}{ll} \sum\limits_{i=1}^{n} \ \delta_{i} &= 1 \end{array} & \textit{Normality condition} \\ \sum\limits_{i=1}^{n} \ a_{ij} \ \delta_{i} &= 0, \ j = 1, 2, \ldots \ m \end{array} & \begin{array}{c} \textit{Orthogonal}, \\ \textit{Conditions}, \\ \textit{Conditions},$$

Orthogonality

conditions (one per primal variahla)

then

$$\mathbf{g}(\mathbf{t}) \geq \prod_{i=1}^{n} \left(\frac{c_i}{\delta_i} \right)^{\delta_i}$$

©D. Bricker, U. of IA, 1998

PRIMAL GEOMETRIC PROGRAM

Ŷ

 $\mathbf{g}(\mathbf{t}) \geq \prod_{i=1}^{n} \left(\frac{c_i}{\delta_i} \right)^{\delta_i} \left(\prod_{j=1}^{m} \prod_{i=1}^{n} t_j^{a_{ij}\delta_i} \right) = \prod_{i=1}^{n} \left(\frac{c_i}{\delta_i} \right)^{\delta_i} \prod_{j=1}^{m} t_j^{\sum_{i=1}^{n} a_{ij}\delta_i}$

We would like this lower bound to be not dependent on the variables t_i , j=1, 2, ... m

This will be so if their exponents are zero:

$$\sum_{i=1}^{n} a_{ij} \delta_{i} = 0, \ j=1,2,... \ m$$

then for all t > 0 and nonnegative δ satisfying the normality & orthogonality conditions,

$$\sum_{i=1}^{n} c_{i} \prod_{j=1}^{m} t_{j}^{a_{ij}} = g(t) \ge v(\delta) = \prod_{i=1}^{n} \left(\frac{c_{i}}{\delta_{i}}\right)^{\delta_{i}}$$

the Primal - Dual Inequality

©D. Bricker, U. of IA, 1998

dual

function

Weak Duality Theorem

If t^* solves the primal geometric program (GP) and δ^* solves the dual geometric program (DGP)

$$g(t^*) \ge v(\delta^*)$$

δ

then

Proof: The Primal-Dual Inequality

(We will next show that the above inequality is tight, i.e., that the strong duality property holds.) থ

©D. Bricker, U. of IA, 1998

DGP: Maximize
$$\mathbf{v}(\delta) = \prod_{i=1}^{n} \left(\frac{c_{i}}{\delta_{i}}\right)^{\delta_{i}}$$

subject to
$$\begin{cases} \sum_{i=1}^{n} \delta_{i} = 1 & \text{Normality condition} \\ \sum_{i=1}^{n} a_{ij} \delta_{i} = 0, \ j=1,2,\dots, m & \text{Orthogonality} \\ \delta_{i} > 0, \ i=1, 2, \dots, n \end{cases}$$

©D. Bricker, U. of IA, 1998

Strong Duality Theorem

Dual Geometric Prooram

If $t^* = (t_1^*, t_2^*, \dots, t_m^*)$ solves the primal GP,

then the dual GP is consistent, and the vector

$$\delta^* = (\delta_1^*, \, \delta_2^*, \, \dots \, \delta_n^*) \text{ defined by } \quad \delta_i^* = \frac{c_i \prod_{j=1}^m t_j^{*a_{ij}}}{g(t^*)}$$

is a solution for the dual GP, and $g(t^*) = v(\delta^*)$.

©D. Bricker, U. of IA, 1998

Proof
Notation
$$\mathbf{g}(t) = \sum_{i=1}^{n} \mathbf{u}_{i}(t)$$
 where $\mathbf{u}_{i}(t) = \mathbf{c}_{i} \prod_{j=1}^{m} \mathbf{t}_{j}^{\mathbf{e}_{i,j}}$
Outline of Proof: If we define $\delta_{i}^{*} = \frac{\mathbf{u}_{i}(t^{*})}{\mathbf{g}(t^{*})}$
where t^{*} minimizes $\mathbf{g}(t)$, then

 δ^* is feasible in the dual, and $g(t^*) = v(\delta^*)$.

By the weak duality theorem, $\,\delta^*$ solves the dual GP.

©D. Bricker, U. of IA, 1998

$$\mathbf{g}(t) = \sum_{i=1}^{n} \mathbf{u}_{i}(t) \text{ where } \mathbf{u}_{i}(t) = \mathbf{c}_{i} \prod_{j=1}^{m} t_{j}^{a_{ij}}$$

If t^* minimizes g(t), then t^* satisfies (for k=1, ..., m)

Proof

$$\mathbf{0} = \frac{\partial}{\partial t_k} \mathbf{g}(t) = \sum_{i=1}^n \frac{\partial}{\partial t_k} \mathbf{u}_i(t) = \sum_{i=1}^n \frac{\partial}{\partial t_k} \mathbf{c}_i \prod_{j=1}^m \mathbf{t}_j^{a_{ij}} = \sum_{i=1}^n \mathbf{c}_i \mathbf{a}_{ik} \mathbf{t}_k^{a_{ik}-1} \prod_{j \neq k} \mathbf{t}_j^{a_{ij}}$$

Multiply both sides by t_k :

contributed by that term!

$$\mathbf{t}_k \times \mathbf{0} = \mathbf{t}_k \sum_{i=1}^n \, \mathbf{c}_i \, \mathbf{a}_{i\,k} \, \mathbf{t}_k^{\mathbf{a}_{i\,k}^{-1}} \prod_{j \neq k} \mathbf{t}_j^{\mathbf{a}_{i\,j}} = \sum_{i=1}^n \mathbf{a}_{i\,k} \, \mathbf{c}_i \prod_{j=1}^m \mathbf{t}_j^{\mathbf{a}_{i\,j}} \, = \sum_{i=1}^n \mathbf{a}_{i\,k} \, \mathbf{u}_i(t)$$

Therefore, if t^* minimizes g(t), then t^* satisfies

$$\begin{split} 0 &= \sum_{i=1}^{n} a_{i\,k} \, u_i(t^*) \Longrightarrow \qquad 0 &= \sum_{i=1}^{n} a_{i\,k} \, \frac{u_i(t^*)}{g(t^*)} \ , \ k = 1, \ ...m \\ \text{If we let} \quad \delta_i^* &= \frac{u_i(t^*)}{g(t^*)} \ , \ i = 1, \ 2, \ ... \ n \end{split}$$

then
$$\delta^* = (\delta_1^*, \delta_2^*, \dots, \delta_n^*)$$
 satisfies

$$\mathbf{0} = \sum_{i=1}^{n} \mathbf{a}_{ik} \delta_{i}^{*}, \ \mathbf{k} = 1, \ \dots \mathbf{m}$$

(orthogonality conditions are satisfied!)

©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998

$${}^{*}_{t} = \frac{c_{i} \prod_{j=1}^{m} t_{j}^{*} a_{ij}}{g(t^{*})} \underbrace{ \begin{array}{c} \textit{term # i of the} \\ \textit{primal objective} \end{array}}_{optimal value} \\ optimal value \\ \textit{of posynomial} \end{array}$$

That is, the optimal dual variable δ_i^* , associated with term i of the primal objective function, is

simply the fraction of the optimal cost which is

11/16/98

and

 $\sum_{i=1}^{n} \delta_{i}^{*} = \sum_{i=1}^{n} \frac{\mathbf{u}_{i}(t^{*})}{\mathbf{g}(t^{*})} = \frac{\sum_{i=1}^{n} \mathbf{u}_{i}(t^{*})}{\mathbf{g}(t^{*})} = 1 \qquad (normality condition)$ (is satisfied!)

Therefore, δ^* is feasible in the dual GP.

Also,
$$\mathbf{g}(\mathbf{t}^*) = \mathbf{g}(\mathbf{t}^*)^{\delta_1 + \dots + \delta_n} = \mathbf{g}(\mathbf{t}^*)^{\delta_1} \mathbf{g}(\mathbf{t}^*)^{\delta_2} \cdots \mathbf{g}(\mathbf{t}^*)^{\delta_n}$$

$$= \left[\frac{\mathbf{u}_1(\mathbf{t}^*)}{\delta_1}\right]^{\delta_1} \left[\frac{\mathbf{u}_2(\mathbf{t}^*)}{\delta_2}\right]^{\delta_2} \cdots \left[\frac{\mathbf{u}_n(\mathbf{t}^*)}{\delta_n}\right]^{\delta_n}$$

$$= \left[\frac{\mathbf{c}_1}{\delta_1}\right]^{\delta_1} \left[\frac{\mathbf{c}_2}{\delta_2}\right]^{\delta_2} \cdots \left[\frac{\mathbf{c}_n}{\delta_n}\right]^{\delta_n} \left[\prod_{j=1}^m \mathbf{t}^{*j}_j\right]^{\delta_1} \left[\prod_{j=1}^m \mathbf{t}^{*j}_j\right]^{\delta_2} \cdots \left[\prod_{j=1}^m \mathbf{t}^{*j}_j\right]^{\delta_n}$$

©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998

$$g(t^*) = \left[\frac{c_1}{\delta_1}\right]^{\delta_1} \left[\frac{c_2}{\delta_2}\right]^{\delta_2} \cdots \left[\frac{c_n}{\delta_n}\right]^{\delta_n} \prod_{j=1}^m t_j^* \prod_{i=1}^{\sum_{j=1}^n a_{ij}\delta_i} \\ = \left[\frac{c_1}{\delta_1}\right]^{\delta_1} \left[\frac{c_2}{\delta_2}\right]^{\delta_2} \cdots \left[\frac{c_n}{\delta_n}\right]^{\delta_n} \prod_{j=1}^m t_j^* \prod_{j=1}^n t_j^* \prod_{j=1}^n$$

That is, if t^{*} is optimal in the primal GP, then δ^* is feasible and optimal in DGP, where m aii

$$\delta_i^* = \frac{c_i \prod_{j=1}^{m} t_j^*}{g(t^*)}$$

and

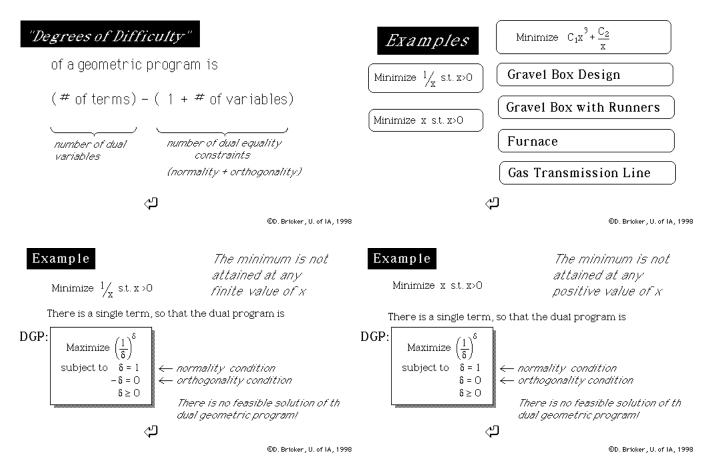
$$g(t^*) = v(\delta^*)$$

Ŷ

Q.E.D.

©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998



11/16/98

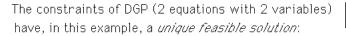
Example

GP: Minimize
$$f(x) = C_1 x^3 + \frac{C_2}{x}$$
, where $C_1 > 0 \& C_2 > 0$

Define two dual variables, one per term of the posynomial:

 $C_{1}x^{3} \longleftrightarrow \delta_{1}$ $\frac{C_{2}}{x} = C_{2}x^{-1} \longleftrightarrow \delta_{2}$ $\begin{cases} \delta_{1} + \delta_{2} = 1 \iff Normality \ constraint \\ 3 \ \delta_{1} - \delta_{2} = 0 \iff Orthogonality \ constraint \\ \delta_{1} > 0 \ \& \delta_{2} > 0 \end{cases}$

©D. Bricker, U. of IA, 1998

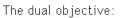


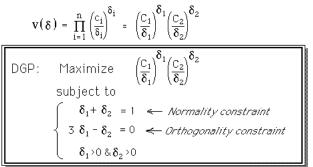
$$\begin{cases} \delta_{1} + \delta_{2} = 1 & \delta_{1} = \frac{1}{4} \\ 3 \ \delta_{1} - \delta_{2} = 0 \implies \delta_{2} = \frac{3}{4} \\ \delta_{1} > 0 \& \delta_{2} > 0 \end{cases}$$
$$\mathbf{v}(\delta) = \left(\frac{C_{1}}{\delta_{1}}\right)^{\delta_{1}} \left(\frac{C_{2}}{\delta_{2}}\right)^{\delta_{2}} = \left(\frac{C_{1}}{\frac{1}{4}}\right)^{\frac{1}{4}} \left(\frac{C_{2}}{\frac{3}{4}}\right)^{\frac{3}{4}} = 4 \left(\frac{1}{3}\right)^{\frac{3}{4}} C_{1}^{\frac{1}{4}} C_{2}^{\frac{3}{4}}$$

In this example, DGP had a unique feasible solution... such is not the case in general,

problem in DGP!

so that one must actually solve a maximization





©D. Bricker, U. of IA, 1998

Computation of the Primal Optimal Solution

$$\delta_{1} = \frac{1}{4} = \frac{C_{1}x^{*3}}{f(x^{*})} \qquad \delta_{2} = \frac{3}{4} = \frac{\frac{C_{2}}{x^{*}}}{f(x^{*})}$$
Since $f(x^{*}) = v(\delta^{*}) = 4\left(\frac{1}{3}\right)^{3/4}C_{1}^{1/4}C_{2}^{3/4}$

$$\frac{C_{2}}{x^{*}} = \frac{3}{4}(4)\left(\frac{1}{3}\right)^{3/4}C_{1}^{1/4}C_{2}^{3/4} \implies x^{*} = \left(\frac{1}{3}\right)^{1/4}C_{1}^{-1/4}C_{2}^{1/4}$$

©D. Bricker, U. of IA, 1998

Example: Gravel Box Design

400 m of gravel is to be ferried across a river on a barge. A box (with open top) is to be built for this purpose. After all the gravel has been ferried, the box is to be discarded.

 transport
 10¢ per round trip of barge

 materials
 sides & bottom of box: \$10/m

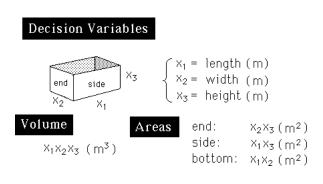
 <</td>
 ends of box: \$20/m

©D. Bricker, U. of IA, 1998

ŝ

©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998



Cost function

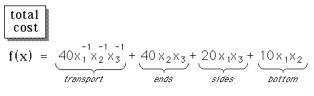
Costs

Transport cost:
$$(0.10 \text{ }^{\text{frip}}) \frac{400 \text{ m}^3}{x_1 x_2 x_3 \text{ m}^3 \text{trip}}$$

Materials
cost:

$$\begin{cases}
\text{ends of box: } 2\left(20 \text{ }^{\text{frip}}_{\text{m}}\right) x_2 x_3 \text{ m}^2\\
\text{sides of box: } 2\left(10 \text{ }^{\text{frip}}_{\text{m}}\right) x_1 x_3 \text{ m}^2\\
\text{bottom: } 2\left(10 \text{ }^{\text{frip}}_{\text{m}}\right) x_1 x_2 \text{ m}^2
\end{cases}$$

©D. Bricker, U. of IA, 1998



cost: $\underbrace{40x_1^{-1}x_2^{-1}x_3^{-1}}_{transport} + \underbrace{40x_2x_3}_{ends} + \underbrace{20x_1x_3}_{sides} + \underbrace{10x_1x_2}_{bottom}$

 $= 40x_1^{-1}x_2^{-1}x_3^{-1} + 40x_1^0x_2^1x_3^1 + 20x_1^1x_2^0x_3^1 + 10x_1^1x_2^1x_3^0$

(exponent of x_i in term i is the coefficient of δ_i)

The orthogonality constraint corresponding to x_1 is

a posynomial!

 $-\delta_1 + \delta_3 + \delta_4 = 0$

Define a "weight", i.e., dual variable, for each term of the cost function:

$$\delta_1 + \ \delta_2 + \delta_3 + \ \delta_4 \ = \ 1 \,, \qquad \delta_i > 0 \,, \quad i = 1 \,, \ 2 \,, \ 3 \,, \ 4$$

normality constraint

In addition, there will be an "orthogonality constraint" for each of the (primal) variables.

©D. Bricker, U. of IA, 1998

$$40x_{1}^{-1}x_{2}^{-1}x_{3}^{-1} + 40x_{1}^{0}x_{2}^{1}x_{3}^{1} + 20x_{1}^{1}x_{2}^{0}x_{3}^{1} + 10x_{1}^{1}x_{2}^{1}x_{3}^{1}$$

$$exponent matrix:$$

$$\begin{cases}
-\delta_{1} + \delta_{3} + \delta_{4} = 0 \\
-\delta_{1} + \delta_{2} + \delta_{4} = 0 \\
-\delta_{1} + \delta_{2} + \delta_{3} = 0
\end{cases}$$

$$A = \begin{bmatrix}
-1 & -1 & -1 \\
0 & 1 & 1 \\
1 & 0 & 1 \\
1 & 1 & 0
\end{bmatrix}$$

$$-\delta_{1} + \delta_{2} + \delta_{3} = 0$$

$$orthogonality$$
constraints

©D. Bricker, U. of IA, 1998

In this problem, again DGP has an equal number of variables and equations, with a unique feasible solution:

$\int \delta_1 + \delta_2 + \delta_3 + \delta_4$	= 1,	Gauss-Jordan elimination
$-\delta_1 + \delta_3 + \delta_4$	= ()	yields
$\delta_1 + \delta_2 + \delta_4$	= ()	$\delta_1 = 0.4$ $\delta_2 = 0.2$
$-\delta_1 + \delta_2 + \delta_3$	= ()	$\delta_2 = 0.2$ $\delta_3 = 0.2$
-		$\delta_{1} = 0.2$

©D. Bricker, U. of IA, 1998

Computation of the optimal primal variables

$$\begin{split} \boldsymbol{\delta}_{1}^{\star} &= 0.4 = \begin{pmatrix} -1 & -1 & -1 \\ 40x_{1}x_{2}x_{3} \\ f(x^{\star}) \end{pmatrix} & \text{At the optimum solutions} \\ \text{of the primal & dual,} \\ f(x^{\star}) &= v(\boldsymbol{\delta}^{\star}) \\ \boldsymbol{\delta}_{2}^{\star} &= 0.2 = \begin{pmatrix} 40x_{2}x_{3} \\ f(x^{\star}) \end{pmatrix} & \text{where} \\ \boldsymbol{\delta}_{3}^{\star} &= 0.2 = \begin{pmatrix} 20x_{1}x_{3} \\ f(x^{\star}) \end{pmatrix} & v(\boldsymbol{\delta}) &= \begin{pmatrix} 40 \\ \overline{\boldsymbol{\delta}_{1}} \end{pmatrix}^{\delta_{1}} \begin{pmatrix} 40 \\ \overline{\boldsymbol{\delta}_{2}} \end{pmatrix}^{\delta_{2}} \begin{pmatrix} 20 \\ \overline{\boldsymbol{\delta}_{3}} \end{pmatrix}^{\delta_{3}} \begin{pmatrix} 10 \\ \overline{\boldsymbol{\delta}_{4}} \end{pmatrix}^{\delta_{4}} \\ \boldsymbol{\delta}_{4}^{\star} &= 0.2 = \begin{pmatrix} 10x_{1}x_{2} \\ f(x^{\star}) \end{pmatrix} & v(\boldsymbol{\delta}^{\star}) &= 100 \end{split}$$

DGP

cost:

transport

(e.g., 10¢/trip, etc.)

 $\delta_1 = 0.4$

 $\delta_2 = 0.2$

 $\delta_3 = 0.2$ δ₄ = 0.2

maximize
$$\sqrt{\delta} = \left(\frac{40}{\delta_1}\right)^{\delta_1} \left(\frac{40}{\delta_2}\right)^{\delta_2} \left(\frac{20}{\delta_3}\right)^{\delta_3} \left(\frac{10}{\delta_4}\right)^{\delta_4}$$

 $\delta_1 + \delta_2 + \delta_3 + \delta_4 = 1$
 $-\delta_1 + \delta_3 + \delta_4 = 0$
 $-\delta_1 + \delta_2 + \delta_3 = 0$
 $\delta_1 > 0$ is $1 - 2 - 3 - 4$

hattam

 $0_i > 0, i = 1, 2, 3, 4$ ©D. Bricker, U. of IA, 1998

sides

We immediately have the result that

transportation cost = 40% of total cost

cost of ends = 20% of total cost

cost of sides = 20% of total cost

cost of bottom = 20% of total cost

 $40x_1x_2x_3 + 40x_2x_3 + 20x_1x_3 + 10x_1x_2$

. ends

This is independent of the cost coefficients!

©D. Bricker, U. of IA, 1998

 $\sum_{i=1}^n a_{ij} \, \delta_i = 0$

©D. Bricker, U. of IA, 1998

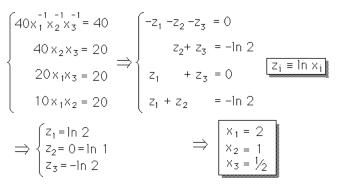
©D. Bricker, U. of IA, 1998

Solve for x:

$$40x_1^{-1}x_2^{-1}x_3^{-1} = (0.4)(100) = 40$$

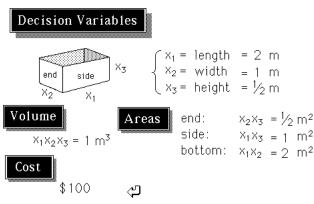
 $40x_2x_3 = (0.2)(100) = 20$
 $20x_1x_3 = (0.2)(100) = 20$
 $10x_1x_2 = (0.2)(100) = 20$

This can be done by taking logs of both sides, to get a linear system in the logarithms of x_i



©D. Bricker, U. of IA, 1998

©D. Bricker, U. of IA, 1998



cost: $40x_1^{-1}x_2^{-1}x_3^{-1} + 40x_2x_3 + 20x_1x_3 + 10x_1x_2 + 5x_1$

. sides bottom

ends

This introduces a new dual variable, δ_{5} :

 $\begin{cases} \delta_1 + \delta_2 + \delta_3 + \delta_4 + \delta_5 = 1 \\ -\delta_1 + \delta_3 + \delta_4 + \delta_5 = 0 \\ -\delta_1 + \delta_2 + \delta_4 = 0 \\ -\delta_1 + \delta_2 + \delta_3 = 0 \end{cases}$

transport

©D. Bricker, U. of IA, 1998

runners

©D. Bricker, U. of IA, 1998

١

٨.

.4-.2δ₅

Now there are 5 variables, but only 4 equations! Modification of original problem:

To ease sliding the box onto the barge, while eliminating wear & tear on the bottom, "runners" are to be placed on the bottom, along the length.

Cost of materials for runners: \$2.50/meter



©D. Bricker, U. of IA, 1998

DGP The dual geometric program

maximize
$$\nabla(\delta) = \left(\frac{40}{\delta_1}\right)^{\delta_1} \left(\frac{40}{\delta_2}\right)^{\delta_2} \left(\frac{20}{\delta_3}\right)^{\delta_3} \left(\frac{10}{\delta_4}\right)^{\delta_4} \left(\frac{5}{\delta_5}\right)^{\delta_5}$$

$$\begin{cases} \delta_1 + \delta_2 + \delta_3 + \delta_4 + \delta_5 = 1\\ -\delta_1 + \delta_3 + \delta_4 + \delta_5 = 0\\ -\delta_1 + \delta_2 + \delta_4 = 0\\ -\delta_1 + \delta_2 + \delta_3 = 0 \end{cases}$$

$$\delta_1 > 0, \ i = 1, 2, 3, 4, 5$$

©D. Bricker, U. of IA, 1998

$$\begin{cases} \delta_{1} + \delta_{2} + \delta_{3} + \delta_{4} + \delta_{5} = 1 \\ -\delta_{1} + \delta_{3} + \delta_{4} + \delta_{5} = 0 \\ -\delta_{1} + \delta_{2} + \delta_{3} &= 0 \\ -\delta_{1} + \delta_{2} + \delta_{3} &= 0 \\ \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ -1 & 0 & 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 0 & 0 \end{bmatrix} \implies \begin{bmatrix} \delta_{1} & \delta_{2} & \delta_{3} & \delta_{4} & \delta_{5} & 0 \\ 0 & 1 & 0 & 0 & -0.4 & 0.2 \\ 0 & 0 & 1 & 0 & 0.6 & 0.2 \\ 0 & 0 & 0 & 1 & 0.6 & 0.2 \end{bmatrix}$$

$$\begin{bmatrix} Gauss - Jordan \\ Elimination \end{bmatrix} \implies \begin{cases} \delta_{1} = 0.4 - 0.2 & \delta_{5} \\ \delta_{2} = 0.2 + 0.4 & \delta_{5} \\ \delta_{3} = 0.2 - 0.6 & \delta_{5} \\ \delta_{4} = 0.2 - 0.6 & \delta_{5} \\ \theta_{0} = 0.4 & 0.4 & 0.4 \\ 0 = 0.2 & 0.6 & \delta_{5} \\ \theta_{0} = 0.2 & 0.6 & \delta_{5} \end{bmatrix}$$

$$A(\delta) = \left(\frac{40}{\delta_1}\right)^{\delta_1} \left(\frac{40}{\delta_2}\right)^{\delta_2} \left(\frac{20}{\delta_3}\right)^{\delta_3} \left(\frac{10}{\delta_4}\right)^{\delta_4} \left(\frac{5}{\delta_5}\right)^{\delta_5} \&\begin{cases} \delta_1 = 0.4 - 0.2 \,\delta_5 \\ \delta_2 = 0.2 + 0.4 \,\delta_5 \\ \delta_3 = 0.2 - 0.6 \,\delta_5 \\ \delta_4 = 0.2 - 0.6 \,\delta_5 \end{cases}$$

$$A(\delta) = \left(\frac{40}{\delta_1}\right)^{(4-2)\delta_5} \left(\frac{40}{\delta_2}\right)^{(2+4)\delta_5} \left(\frac{20}{\delta_2}\right)^{(2-6)\delta_5} \left(\frac{10}{\delta_2}\right)^{(2-6)\delta_5} \left(\frac{10}{\delta$$

.2-.685

We now have a function of a **single variable** to be maximized, using, for example, golden-section search!

.2+.4δ₅

©D. Bricker, U. of IA, 1998

85

.2-.68s

What is the initial interval bounding the optimum?

