

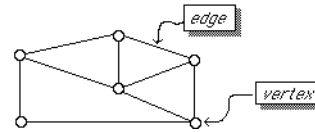
**Graphs and Networks:
basic definitions & concepts**



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A GRAPH consists of

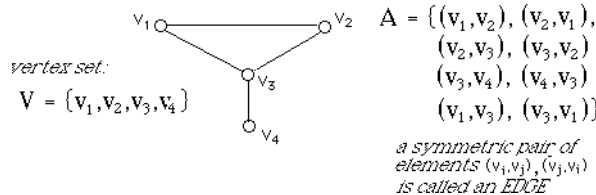
- a collection of VERTICES or NODES
- a collection of LINKS or EDGES



Formally, a GRAPH is a pair of sets (V,A) where

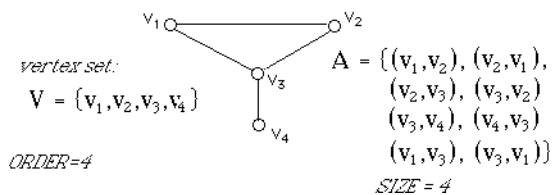
- V is non-empty
- A is an irreflexive, symmetric relation on V

$(v_i, v_i) \notin A$ $(v_i, v_j) \in A \Leftrightarrow (v_j, v_i) \in A$

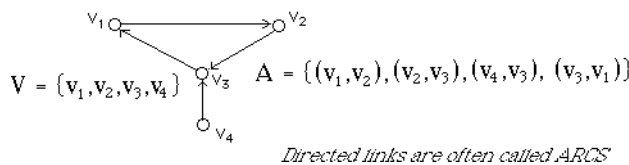


The number of vertices is the **ORDER** of the graph

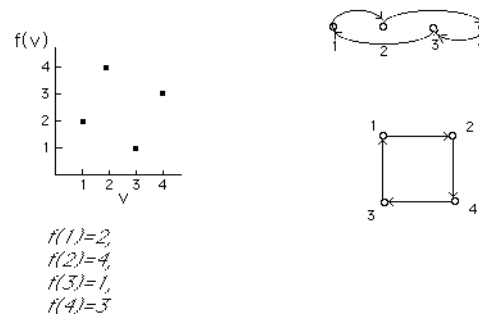
The number of edges is the **SIZE** of the graph



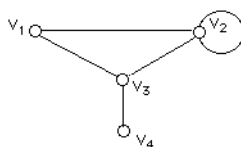
A **DIGRAPH** or DIRECTED GRAPH is a pair of sets (V,A) where A is not symmetric, that is, the links have directions



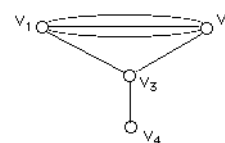
Three representations of a digraph $G=(V,A)$ where $V=(1,2,3,4)$ and $A=((1,2), (2,4), (4,3), (3,1))$



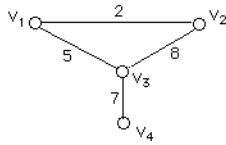
A "pure" graph has no loops, i.e., (v_i, v_i) is not a valid edge. If the edge set includes (v_i, v_i) , the entity is called a LOOP-GRAPH



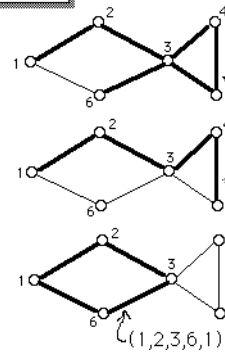
If multiple edges are allowed joining pairs of vertices, then the entity is called a MULTI-GRAPH



If each edge of a graph has an associated number, the entity is called a **NETWORK**



GRAPH

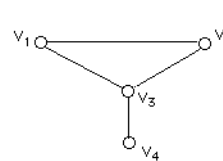


CHAIN: a sequence of vertices, $(x_0, x_1, \dots, x_i, x_{i+1}, \dots, x_s)$ where each pair (x_i, x_{i+1}) is an edge
(1,2,3,4,5,3,6)

ELEMENTARY CHAIN (no vertices are repeated)
(1,2,3,4,5)

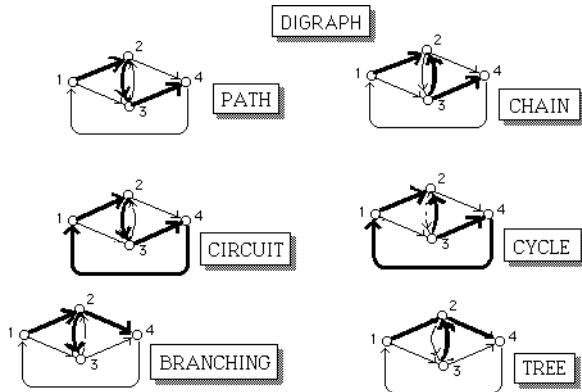
CYCLE (a closed chain, i.e., the first and last vertices of the chain are the same)
(1,2,3,6,1)

The **DEGREE** of a vertex is the number of edges incident with the vertex

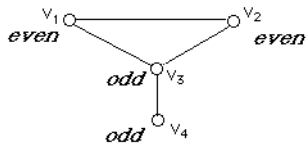


vertex	degree
1	2
2	2
3	3
4	1

Theorem: The sum of the degrees of the vertices of a graph is twice the number of edges

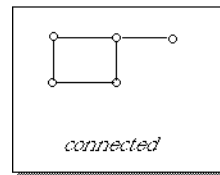


A vertex of a graph is **EVEN** or **ODD** according to whether its degree is an even or odd integer, respectively.

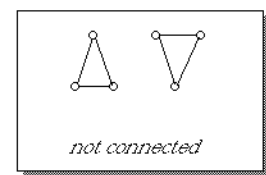


Theorem: Every graph contains an even number of odd vertices

A graph is **CONNECTED** if, for every pair of vertices, x & y , there is a chain of edges from vertex x to vertex y .

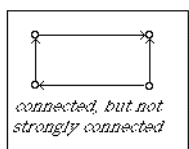


connected

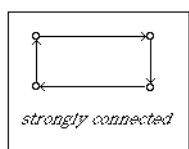


not connected

A directed graph is **CONNECTED** if, for every pair of vertices, x & y , there is a chain of edges from vertex x to vertex y , and **STRONGLY CONNECTED** if there is a path of edges from vertex x to vertex y .



connected, but not strongly connected



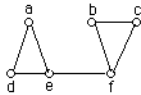
strongly connected

Suppose that we wish to assign directions to the edges of a connected graph so as to obtain a **STRONGLY-CONNECTED** digraph.

Under what conditions, if any, is this possible?

For example, can we make each street in a city one-way so that a vehicle at any intersection can reach any other intersection?

A **BRIDGE** of a connected graph is an edge which, if removed, destroys the graph's connectedness.



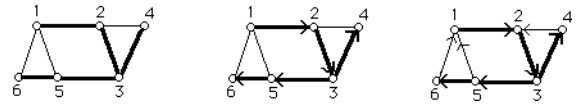
Edge (e,f) is a BRIDGE of the graph

Robbins' Theorem

A graph has a strongly-connected orientation if and only if the graph is connected and has no bridge.

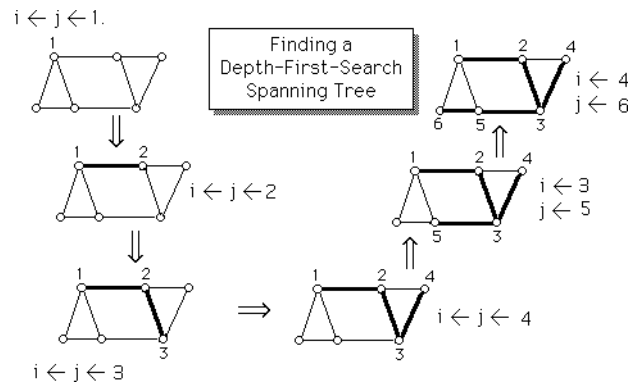
Finding a Strongly-Connected Orientation

- First, find a DEPTH-FIRST-SEARCH SPANNING TREE
- Orient all edges ON the spanning tree from the vertex with smaller label to the vertex with the larger label
- Orient all edges NOT on the spanning tree from the vertex with larger label to the vertex with smaller label

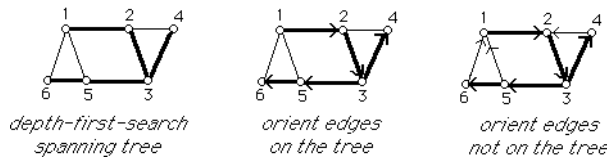


DEPTH-FIRST-SEARCH SPANNING TREE

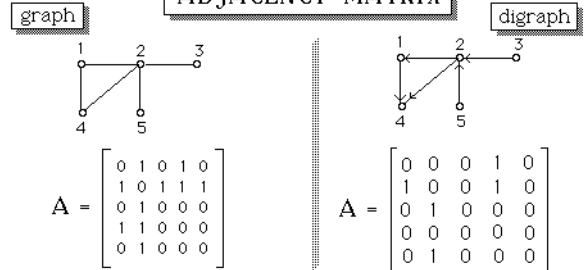
- [0] Select any vertex, and label it "1". Let $i \leftarrow j \leftarrow 1$.
- [1] Select any vertex which is connected by a single edge to the vertex labeled "i". If none, go to step [4]; otherwise, proceed to step [2]
- [2] Label the selected vertex "j+1"
- [3] Let $i \leftarrow j \leftarrow j+1$. Go to step [1].
- [4] Let $i \leftarrow i-1$. If $i=0$, STOP; otherwise, go to step [1].



Example: Finding a strongly-connected orientation of a connected graph

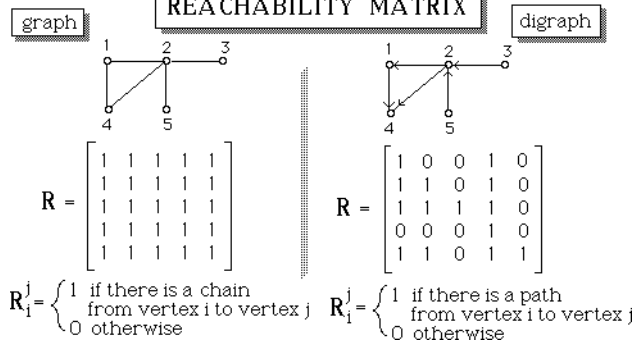


ADJACENCY MATRIX



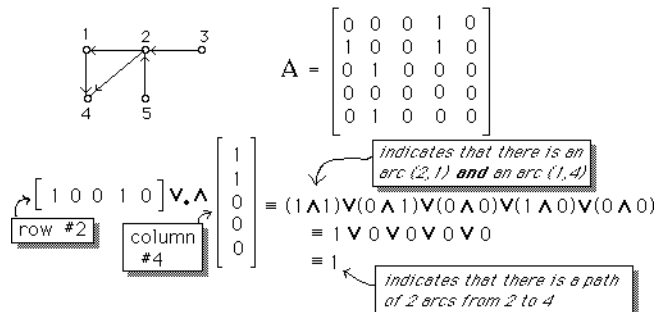
$$A_1^j = \begin{cases} 1 & \text{if there is an edge (i,j)} \\ 0 & \text{otherwise} \end{cases} \quad A_1^j = \begin{cases} 1 & \text{if there is an arc (i,j)} \\ 0 & \text{otherwise} \end{cases}$$

REACHABILITY MATRIX



$$R_1^j = \begin{cases} 1 & \text{if there is a chain from vertex i to vertex j} \\ 0 & \text{otherwise} \end{cases} \quad R_1^j = \begin{cases} 1 & \text{if there is a path from vertex i to vertex j} \\ 0 & \text{otherwise} \end{cases}$$

Consider the generalized inner product $V \cdot A$ in APL notation:



The value in row i & column j of the matrix $A \vee . \wedge A$

is 1 if there is a path, consisting of 2 arcs, from vertex i to vertex j , and 0 otherwise

$(A \vee . \wedge A) \vee . \wedge A$ has a 1 in row i & column j if there is a path consisting of 3 arcs from i to j etc.

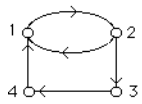
How can the reachability matrix be computed?

An APL function to compute the reachability matrix:

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    ∇R←A REACH N
    [1] →(N=0)/LAST
    [2] R←A ∨.∧ A REACH N-1
    [3] →0
    [4] LAST: R←IDENTITY 1↑ρA
    ∇
    
```

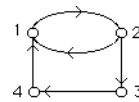
Powers of the Adjacency Matrix



$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} + \times \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

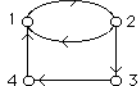
inner product (APL)



$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} \quad A^2 = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$A^3 = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} + \times \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

Theorem: If A is the adjacency matrix of a digraph, then the entry in row i & column j of A^k is the number of paths of length k edges from vertex i to vertex j



$$A^3 = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix} \quad A^4 = \begin{bmatrix} 2 & 0 & 1 & 0 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

