

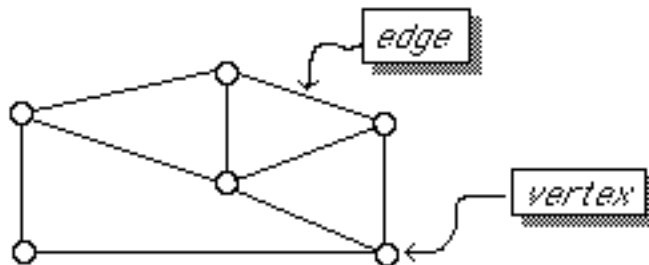
Graphs and Networks: basic definitions & concepts



This Hypercard stack was prepared by:
 Dennis Bricker,
 Dept. of Industrial Engineering,
 University of Iowa,
 Iowa City, Iowa 52242
 e-mail: dennis-bricker@uiowa.edu

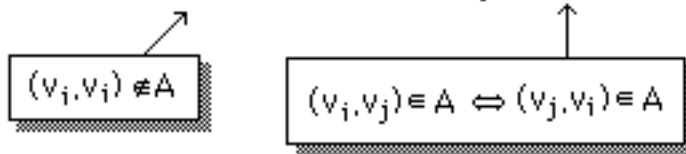
A GRAPH consists of

- a collection of VERTICES or NODES
- a collection of LINKS or EDGES



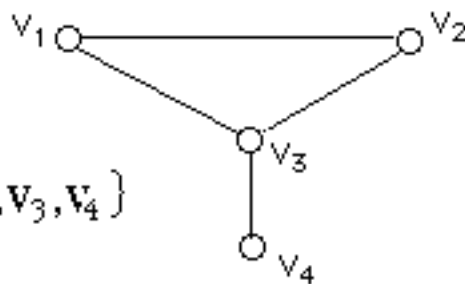
Formally, a GRAPH is a pair of sets (V,A) where

- V is non-empty
- A is an irreflexive, symmetric relation on V



vertex set:

$$V = \{v_1, v_2, v_3, v_4\}$$



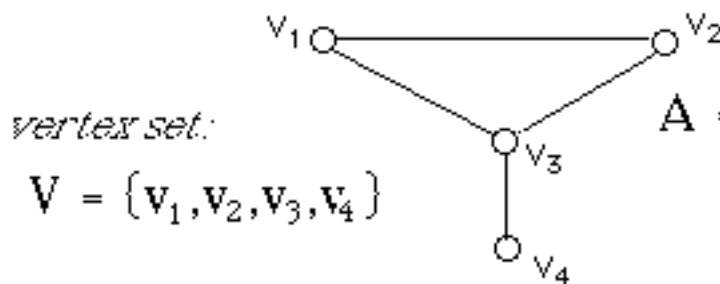
$$A = \{(v_1, v_2), (v_2, v_1), (v_2, v_3), (v_3, v_2), (v_3, v_4), (v_4, v_3), (v_1, v_3), (v_3, v_1)\}$$

a symmetric pair of elements $(v_i, v_j), (v_j, v_i)$ is called an *EDGE*

©D.L.Bricker, U. of Iowa, 1998

The number of vertices is the **ORDER** of the graph

The number of edges is the **SIZE** of the graph



vertex set:

$$V = \{v_1, v_2, v_3, v_4\}$$

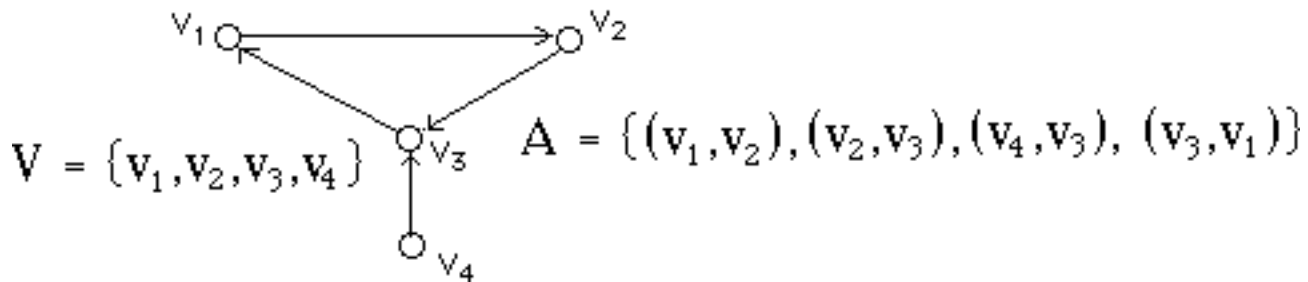
ORDER = 4

$$A = \{(v_1, v_2), (v_2, v_1), (v_2, v_3), (v_3, v_2), (v_3, v_4), (v_4, v_3), (v_1, v_3), (v_3, v_1)\}$$

SIZE = 4

©D.L.Bricker, U. of Iowa, 1998

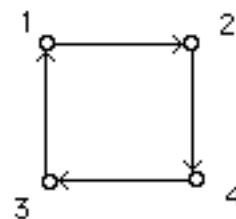
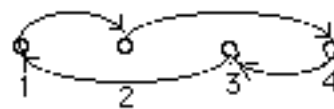
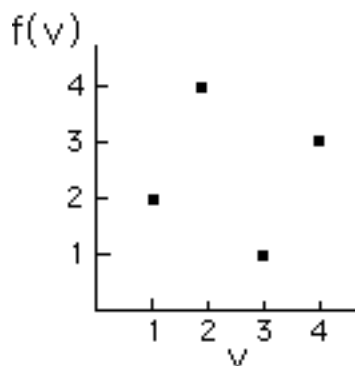
A **DIGRAPH** or DIRECTED GRAPH is a pair of sets (V,A) where A is not symmetric, that is, the links have directions



Directed links are often called ARCS

©D.L.Bricker, U. of Iowa, 1998

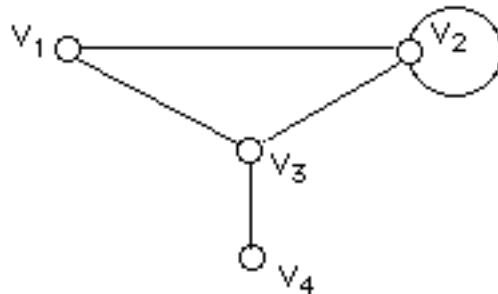
Three representations of a digraph $G=(V,A)$ where $V=(1,2,3,4)$ and $A=\{(1,2), (2,4), (4,3), (3,1)\}$



$$\begin{aligned} f(1) &= 2, \\ f(2) &= 4, \\ f(3) &= 1, \\ f(4) &= 3 \end{aligned}$$

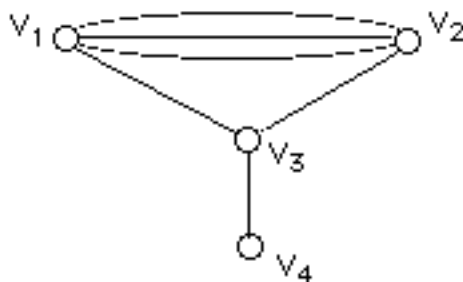
©D.L.Bricker, U. of Iowa, 1998

A "pure" graph has no loops, i.e., (v_i, v_i) is not a valid edge. If the edge set includes (v_i, v_i) , the entity is called a LOOP-GRAPH



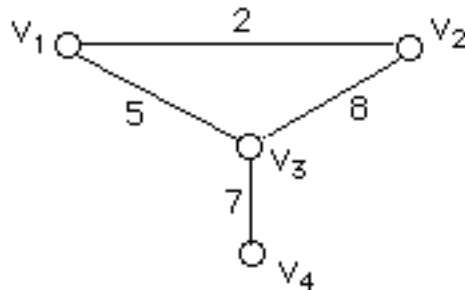
©D.L.Bricker, U. of Iowa, 1998

If multiple edges are allowed joining pairs of vertices, then the entity is called a MULTI-GRAPH



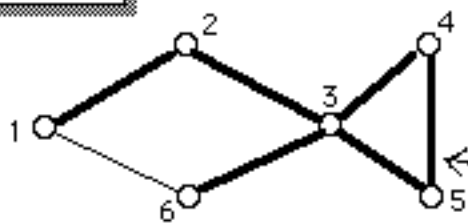
©D.L.Bricker, U. of Iowa, 1998

If each edge of a graph has an associated number, the entity is called a **NETWORK**

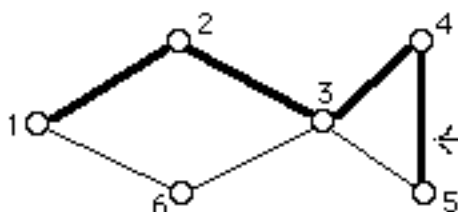


©D.L.Bricker, U. of Iowa, 1998

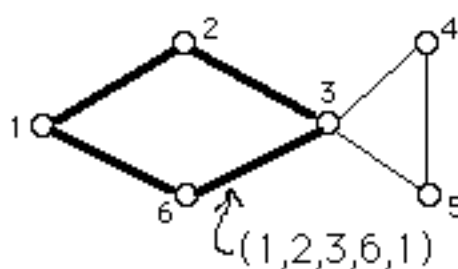
GRAPH



CHAIN : a sequence of vertices, $(x_0, x_1, \dots, x_i, x_{i+1}, \dots, x_s)$ where each pair (x_i, x_{i+1}) is an edge
 $(1,2,3,4,5,3,6)$



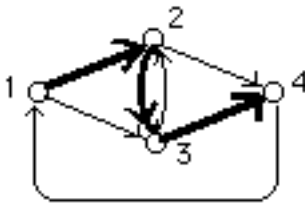
ELEMENTARY CHAIN (no vertices are repeated)
 $(1,2,3,4,5)$



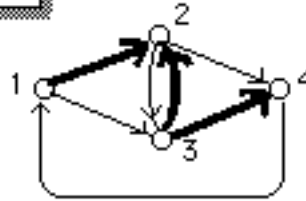
CYCLE (a closed chain, i.e., the first and last vertices of the chain are the same)
 $(1,2,3,6,1)$

©D.L.Bricker, U. of Iowa, 1998

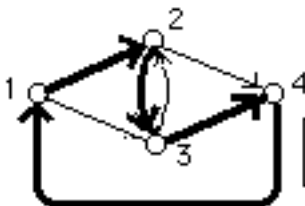
DIGRAPH



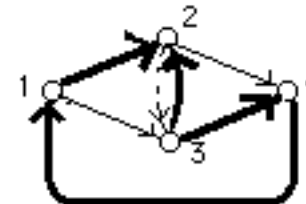
PATH



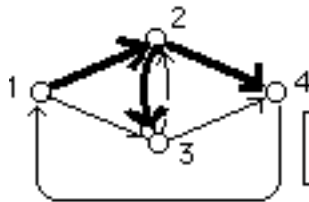
CHAIN



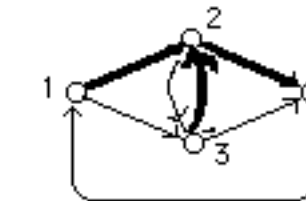
CIRCUIT



CYCLE



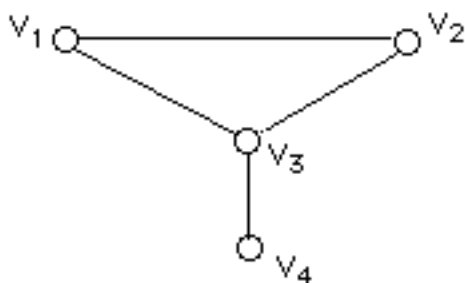
BRANCHING



TREE

©D.L.Bricker, U. of Iowa, 1998

The **DEGREE** of a vertex is the number of edges incident with the vertex

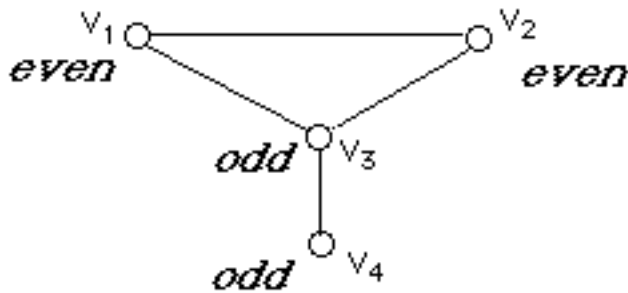


<i>vertex</i>	<i>degree</i>
1	2
2	2
3	3
4	1

Theorem: The sum of the degrees of the vertices of a graph is twice the number of edges

©D.L.Bricker, U. of Iowa, 1998

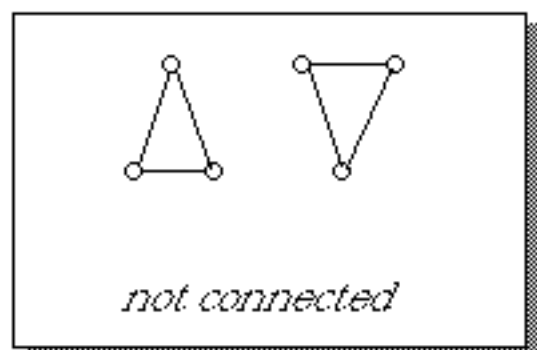
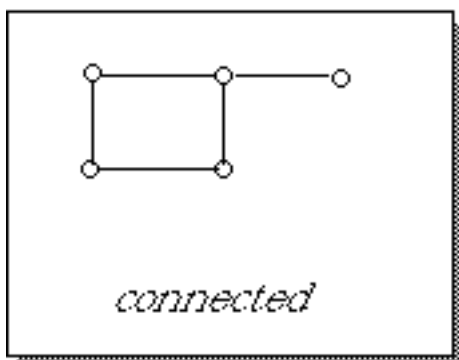
A vertex of a graph is **EVEN** or **ODD** according to whether its degree is an even or odd integer, respectively.



Theorem: Every graph contains an even number of odd vertices

©D.L.Bricker, U. of Iowa, 1998

A graph is **CONNECTED** if, for every pair of vertices, x & y , there is a chain of edges from vertex x to vertex y .

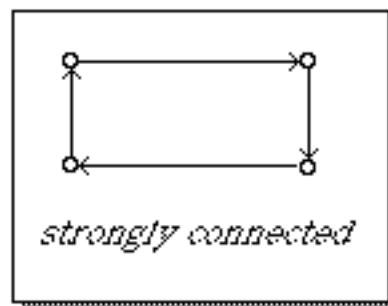
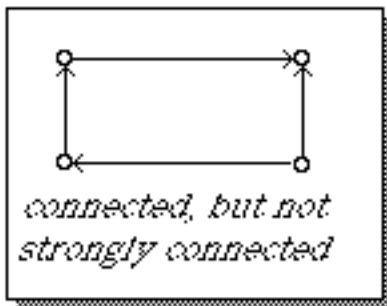


©D.L.Bricker, U. of Iowa, 1998

A directed graph is **CONNECTED**

if, for every pair of vertices, x & y , there is a chain of edges from vertex x to vertex y ,

and **STRONGLY CONNECTED** if there is a path of edges from vertex x to vertex y .



©D.L.Bricker, U. of Iowa, 1998

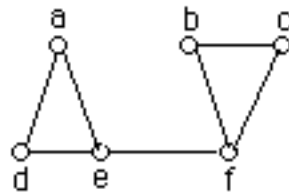
Suppose that we wish to assign directions to the edges of a connected graph so as to obtain a **STRONGLY-CONNECTED** digraph.

Under what conditions, if any, is this possible?

For example, can we make each street in a city one-way so that a vehicle at any intersection can reach any other intersection?

©D.L.Bricker, U. of Iowa, 1998

A **BRIDGE** of a connected graph is an edge which, if removed, destroys the graph's connectedness.



Edge (e,f) is a BRIDGE of the graph

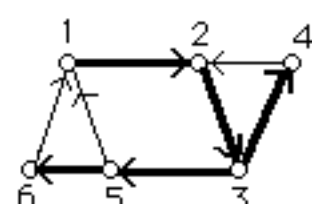
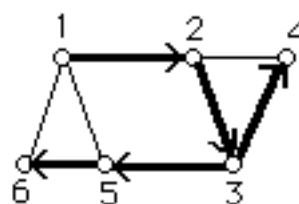
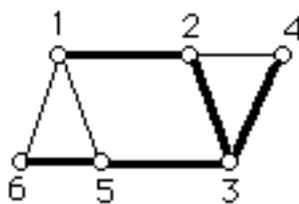
Robbins' Theorem

A graph has a strongly-connected orientation if and only if the graph is connected and has no bridge.

©D.L.Bricker, U. of Iowa, 1998

Finding a Strongly-Connected Orientation

- First, find a DEPTH-FIRST-SEARCH SPANNING TREE
- Orient all edges ON the spanning tree from the vertex with smaller label to the vertex with the larger label
- Orient all edges NOT on the spanning tree from the vertex with larger label to the vertex with smaller label

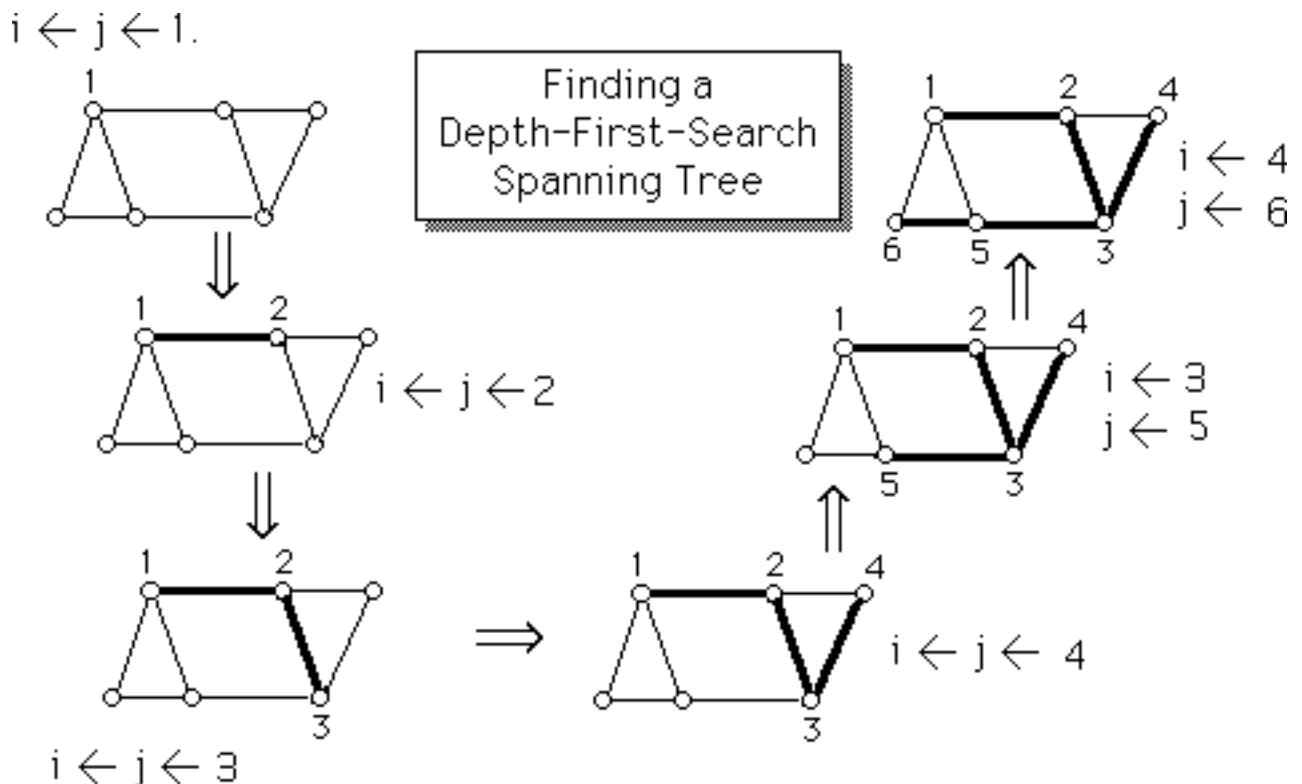


©D.L.Bricker, U. of Iowa, 1998

DEPTH-FIRST-SEARCH SPANNING TREE

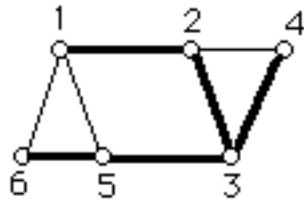
- [0] Select any vertex, and label it "1". Let $i \leftarrow j \leftarrow 1$.
- [1] Select any vertex which is connected by a single edge to the vertex labeled "i". If none, go to step [4]; otherwise, proceed to step [2]
- [2] Label the selected vertex "j+1"
- [3] Let $i \leftarrow j \leftarrow j+1$. Go to step [1].
- [4] Let $i \leftarrow i-1$. If $i=0$, STOP; otherwise, go to step [1].

©D.L.Bricker, U. of Iowa, 1998

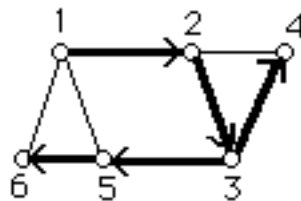


©D.L.Bricker, U. of Iowa, 1998

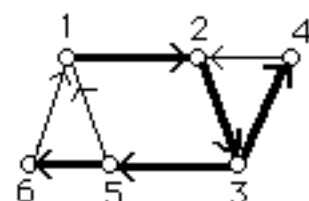
Example: Finding a strongly-connected orientation of a connected graph



*depth-first-search
spanning tree*



*orient edges
on the tree*



*orient edges
not on the tree*

©D.L.Bricker, U. of Iowa, 1998

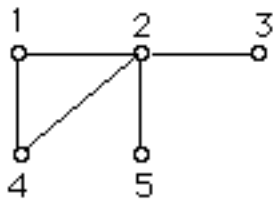
ADJACENCY MATRIX

graph		digraph
$A = \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}$		$A = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}$
$A_i^j = \begin{cases} 1 & \text{if there is an edge (i,j)} \\ 0 & \text{otherwise} \end{cases}$		$A_i^j = \begin{cases} 1 & \text{if there is an arc (i,j)} \\ 0 & \text{otherwise} \end{cases}$

©D.L.Bricker, U. of Iowa, 1998

REACHABILITY MATRIX

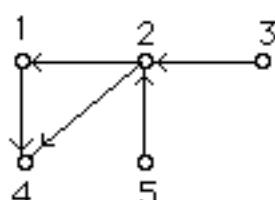
graph



$$R = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$R_i^j = \begin{cases} 1 & \text{if there is a chain} \\ & \text{from vertex } i \text{ to vertex } j \\ 0 & \text{otherwise} \end{cases}$

digraph

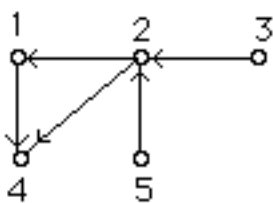


$$R = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 1 \end{bmatrix}$$

$R_i^j = \begin{cases} 1 & \text{if there is a path} \\ & \text{from vertex } i \text{ to vertex } j \\ 0 & \text{otherwise} \end{cases}$

©D.L.Bricker, U. of Iowa, 1998

Consider the generalized inner product $\mathbf{V} \cdot \mathbf{A}$ in APL notation:



$$A = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}$$

$\begin{matrix} \text{row \#2} \\ \text{column \#4} \end{matrix} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \end{bmatrix} \mathbf{V} \cdot \mathbf{A} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \equiv (1 \wedge 1) \mathbf{V} (0 \wedge 1) \mathbf{V} (0 \wedge 0) \mathbf{V} (1 \wedge 0) \mathbf{V} (0 \wedge 0)$

$\equiv 1 \mathbf{V} 0 \mathbf{V} 0 \mathbf{V} 0 \mathbf{V} 0$

$\equiv 1$

indicates that there is an arc (2,1) and an arc (1,4)

indicates that there is a path of 2 arcs from 2 to 4

©D.L.Bricker, U. of Iowa, 1998

The value in row i & column j of the matrix

$$A \vee \wedge A$$

is 1 if there is a path, consisting of 2 arcs,
from vertex i to vertex j ,
and 0 otherwise

$(A \vee \wedge A) \vee \wedge A$ has a 1 in row i & column j
if there is a path consisting of 3 arcs from i to j
etc.

How can the reachability matrix be computed?

©D.L.Bricker, U. of Iowa, 1998

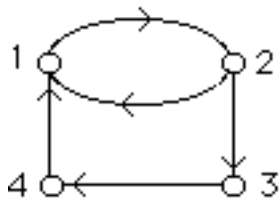
An APL function to compute the reachability matrix:

```

    ∇ R ← A REACH N
    [1] → (N=0)/LAST
    [2] R ← A ∨.∧ A REACH N-1
    [3] → 0
    [4] LAST: R ← IDENTITY 1↑ρA
    ∇
    
```

©D.L.Bricker, U. of Iowa, 1998

Powers of the Adjacency Matrix

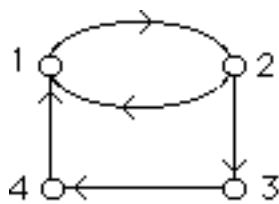


$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} + \cdot \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

inner product (APL)

©D.L.Bricker, U. of Iowa, 1998



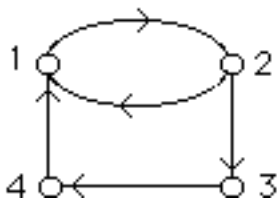
$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$A^3 = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} + \cdot \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

©D.L.Bricker, U. of Iowa, 1998

Theorem: If A is the adjacency matrix of a digraph, then the entry in row i & column j of A^k is the number of paths of length k edges from vertex i to vertex j



$$A^3 = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$

$$A^4 = \begin{bmatrix} 2 & 0 & 1 & 0 \\ 0 & 2 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

