

One-Dimensional Search Methods



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In addition to solving nonlinear optimization problems with a single variable, we require an algorithm to do "line searches" as part of a multi-dimensional nonlinear optimization problem:

$$\text{Minimize}_t f(\mathbf{x}^k + t \mathbf{d}^k)$$

where \mathbf{x}^k = the k^{th} iterate, $\mathbf{x}^k \in \mathbb{R}^n$


\mathbf{d}^k = (feasible) direction of descent


t = step size


$\mathbf{x}^{k+1} = \mathbf{x}^k + t^* \mathbf{d}^k$ for optimal stepsize t^*


- an analytic expression for $f(x)$ might be unknown... $f(x)$ might be "evaluated" by performing a laboratory or simulation experiment, for example
- it is assumed that the function f is *unimodal*, i.e., a local optimum will be globally optimal.
- the result of minimization will be a "sufficiently small" *interval of uncertainty* containing the optimum.
- the derivative of f need not be computed in many of these methods.

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 Three-Point Equi-Interval Search

 Golden-Section Search

 Fibonacci Search

 Polynomial Interpolation

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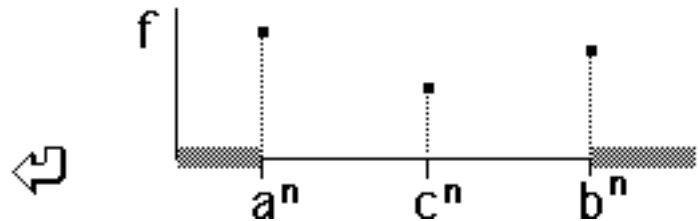
**Three-Point
Equi-Interval
Search**

*Simple, but inefficient....
not recommended!*

Assume that at the n^{th} iteration we have the interval of uncertainty $[a^n, b^n]$ and its midpoint

$$c^n = \frac{a^n + b^n}{2},$$

along with the function values $f(a^n)$, $f(b^n)$, & $f(c^n)$

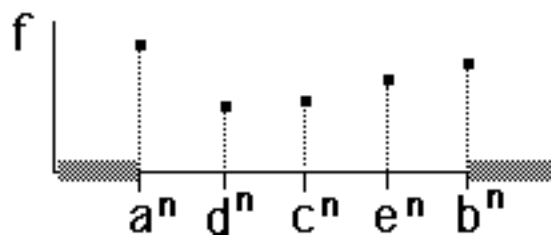


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Find the midpoints of the two subintervals $[a^n, c^n]$ and $[c^n, b^n]$:

$$d^n = \frac{3a^n + b^n}{4}, \quad e^n = \frac{a^n + 3b^n}{4}$$

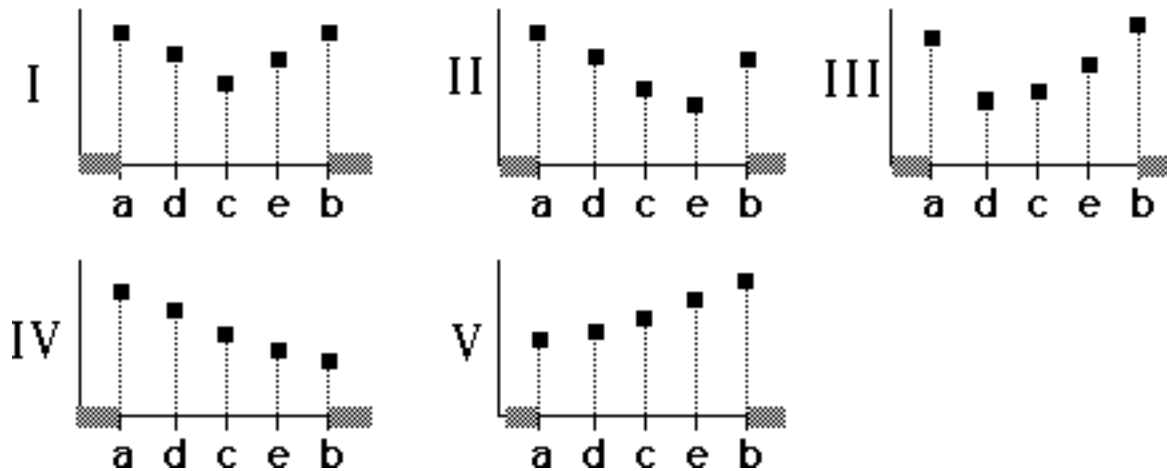
and evaluate $f(d^n)$ and $f(e^n)$:



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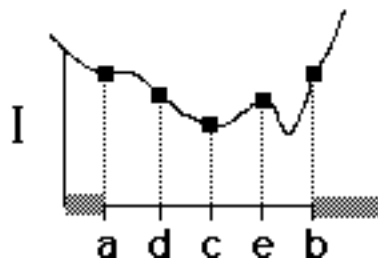
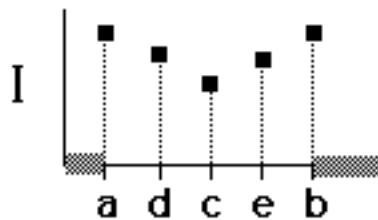
Consider the relative magnitudes of the function at these five points:

There are several cases to consider:



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For example, suppose that $f(c)$ is lower than $f(d)$ and $f(e)$.



Assuming that the function is unimodal, the minimum cannot be in the interval [e,b]!

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And so, using our assumption of unimodality, this allows us to eliminate portions of the interval $[a, b]$ as possible locations for the optimum.

x^ cannot be in $[a, d]$ or $[e, b]$:*

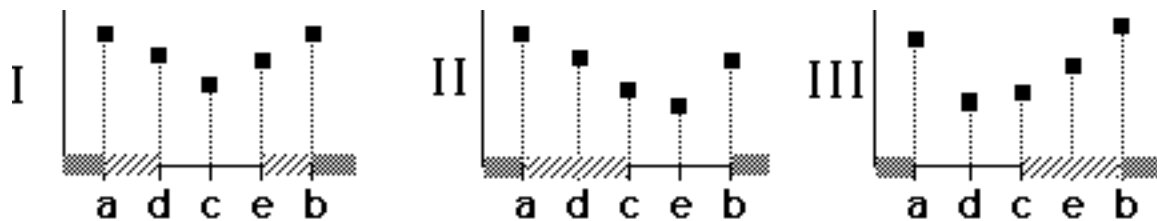


We therefore choose

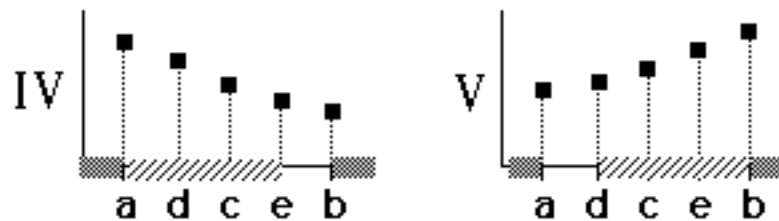
$$a^{n+1} = d^n, c^{n+1} = c^n, b^{n+1} = e^n$$

to begin iteration $n+1$.

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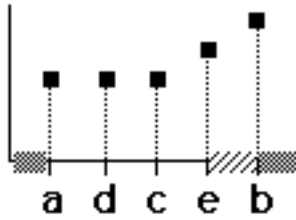


In cases I, II, and III, 50% of the interval is eliminated.



In cases IV and V, 75% of the interval is eliminated!

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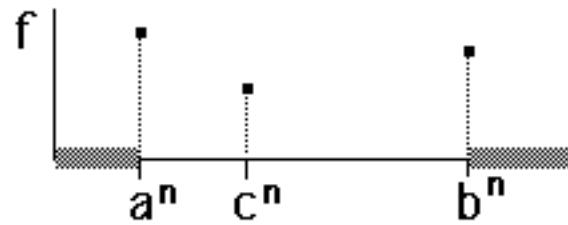


In the event that the smallest of $f(a)$, $f(b)$, $f(c)$, $f(d)$, & $f(e)$ is not unique, less than 25% of the interval can be eliminated.

This event will generally be very rare, especially given round-off errors, etc.



Golden-Section Search

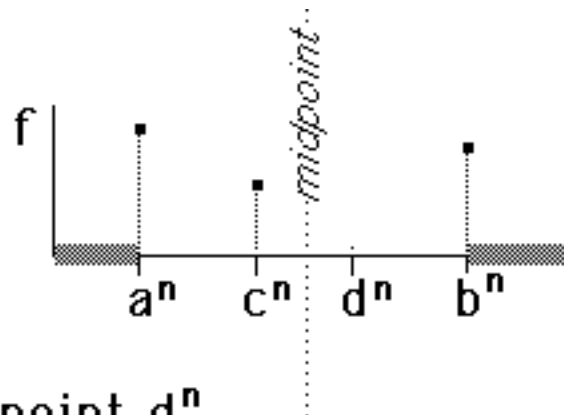


As in 3-point equi-interval search, at the n iteration we have an interval of uncertainty $[a^n, b^n]$ and an interior point $c^n \in (a^n, b^n)$, but c^n is *not the midpoint*!

We insert a *single* additional point d^n so that c^n and d^n are *symmetric* about the midpoint of the interval $[a^n, b^n]$ and compare the values of $f(a^n)$, $f(b^n)$, $f(c^n)$, & $f(d^n)$.



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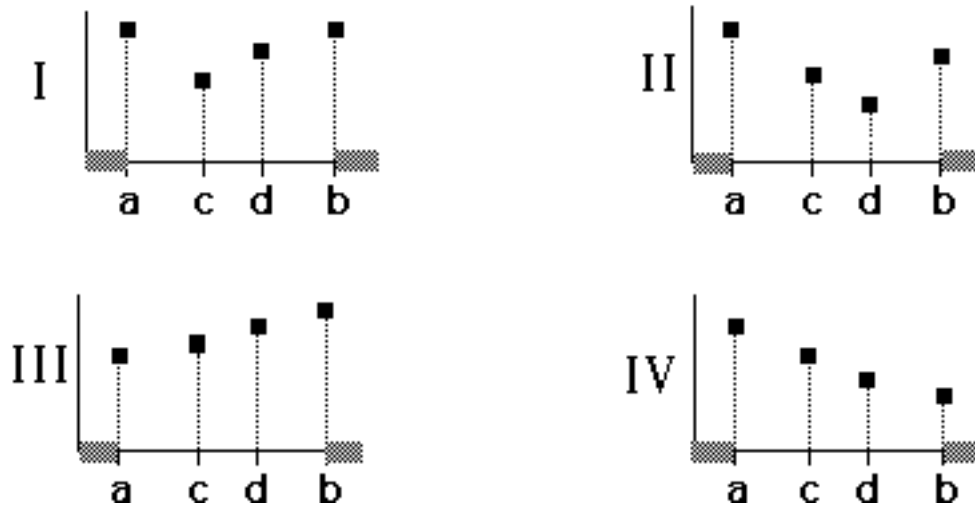
The new point d^n is selected so as to be symmetric to c^n in the interval.

$$b^n - d^n = c^n - a^n$$

$$\Rightarrow \boxed{d^n = a^n + b^n - c^n}$$

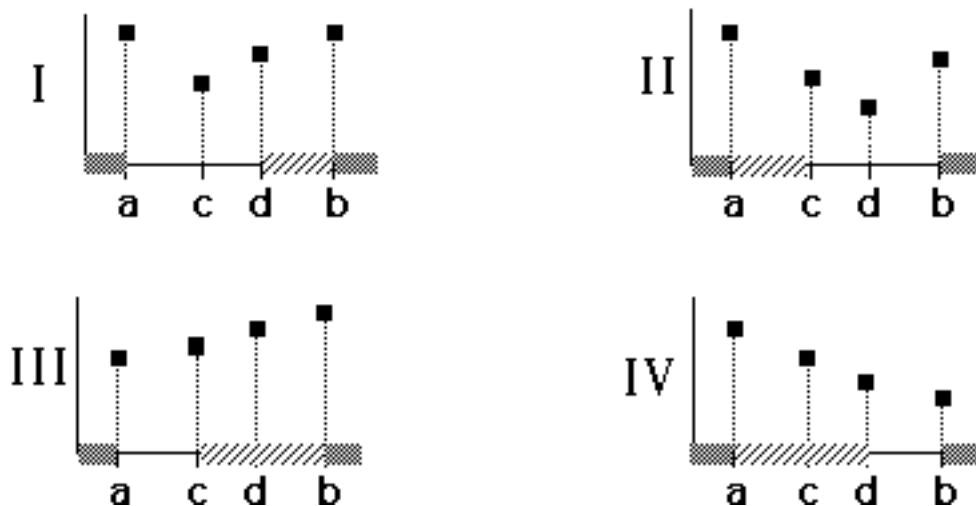
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Assuming unimodality, we can eliminate a segment from the interval of uncertainty



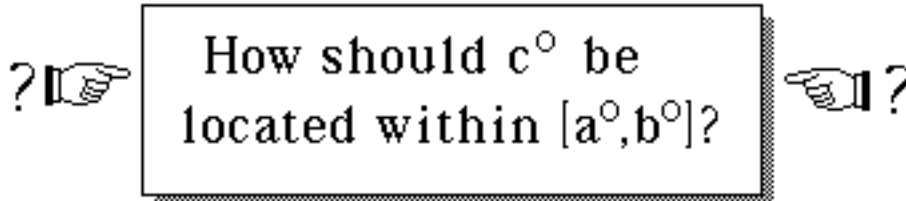
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The shaded segments (////) can be eliminated from the interval of uncertainty:



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Once the location of c^0 has been determined within the original interval of uncertainty $[a^0, b^0]$, the location of subsequent points is determined (by symmetry).



In "Golden Section" search, this is done so that the ratio $\frac{c^n - a^n}{b^n - a^n}$ is constant (α) $\forall n$ (assuming points are labeled so that $c^n < d^n$)

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This requirement uniquely determines

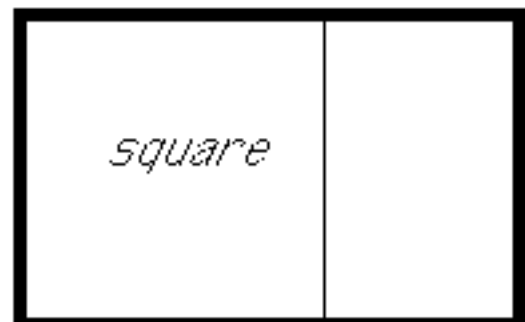
$$\alpha = \frac{c^n - a^n}{b^n - a^n} = \frac{3 - \sqrt{5}}{2} \quad \forall n$$

$$= 0.381966$$

$$\beta = 1 - \alpha = 0.618034$$

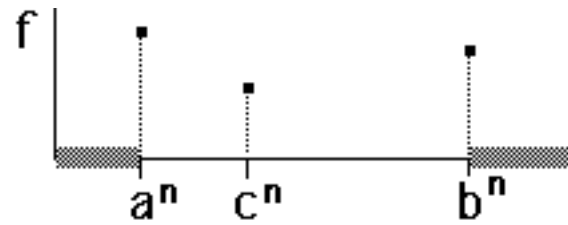
known to early Greek mathematicians as the "Golden Section"

If a rectangle with ratio width:length = β is cut to yield a square, the other rectangle also has width:length = β 



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Fibonacci Search



As is the case with Golden Section Search, this method begins each iteration with an interval of uncertainty $[a, b]$ and one interior point c , and then inserts another interior point d which is symmetric to c .

In Fibonacci search, however, the ratio $\frac{c^n - a^n}{b^n - a^n}$ is not constant, but converges to $1/2$!

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Given: $[a^1, b^1]$ = initial interval of uncertainty

$$I_k = b^k - a^k$$

$I_n = b^n - a^n$ = desired length of interval of uncertainty

ϵ = "distinguishability constant" > 0

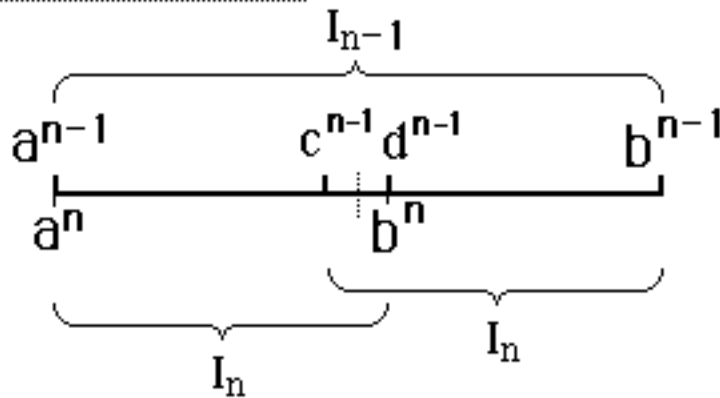
(i.e., x & y are indistinguishable if $|x - y| < \epsilon$)

For ease of discussion, assume $I_1 = b^1 - a^1 = 1$

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At the last iteration

The distance between c^n and d^n will be ϵ



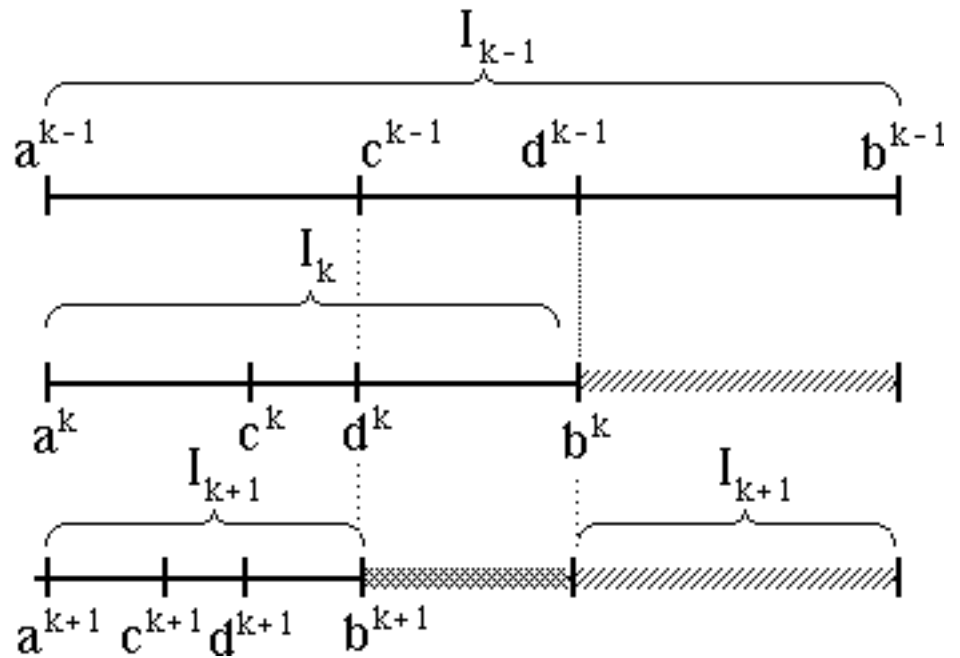
$$I_{n-1} = 2 I_n - \epsilon$$

The final interval of uncertainty will be one of these two intervals

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In general, we have

$$I_{k-1} = I_k + I_{k+1}$$



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$$I_{k-1} = I_k + I_{k+1}$$

"Fibonacci Numbers"

$$\begin{aligned} \Rightarrow I_{n-1} &= 2 I_n - \epsilon & = F_2 I_n - F_0 \epsilon \\ I_{n-2} &= 3 I_n - \epsilon & = F_3 I_n - F_0 \epsilon \\ I_{n-3} &= 5 I_n - 2 \epsilon & = F_4 I_n - F_1 \epsilon \\ I_{n-4} &= 8 I_n - 3 \epsilon & = F_5 I_n - F_2 \epsilon \\ I_{n-5} &= 13 I_n - 5 \epsilon & = F_6 I_n - F_3 \epsilon \\ &\vdots & \\ I_{n-k} &= F_{k+1} I_n - F_{k-1} \epsilon \\ &\vdots & \\ 1 &= I_1 = F_n I_n - F_{n-2} \epsilon \end{aligned}$$

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Fibonacci Numbers

Leonardo of Pisa,
son of Bonacci ("Fibonacci")
1202 AD.

Rule for Generating the Sequence:

$$\begin{aligned} F_0 &= F_1 \equiv 1 \\ F_n &= F_{n-1} + F_{n-2}, \quad n \geq 2 \end{aligned}$$

$$\begin{aligned} \Rightarrow F_2 &= F_1 + F_0 = 1+1 = 2 \\ F_3 &= F_2 + F_1 = 2+1 = 3 \\ F_4 &= F_3 + F_2 = 3+2 = 5 \\ F_5 &= F_4 + F_3 = 5+3 = 8 \\ &\vdots \end{aligned}$$

n	F _n
0	1
1	1
2	2
3	3
4	5
5	8
6	13
7	21
8	34
9	55
10	89

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$$I_1 = F_n I_n - F_{n-2} \epsilon$$

Solving for the "reduction ratio" $\frac{I_1}{I_n}$

$$\frac{I_1}{I_n} = \frac{F_n}{1 + F_{n-2} \epsilon}$$

Given a desired reduction ratio, we can find n , the required number of iterations.

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Example

Suppose we desire $I_n \leq 0.01 I_1$

$$\text{i.e., } \frac{I_1}{I_n} \geq 100$$

and suppose $\epsilon \approx 0$

$$\text{Then } \frac{I_1}{I_n} = \frac{F_n}{1 + F_{n-2} \epsilon} \approx F_n$$

Choose n so that $F_n \geq 100$

$$\Rightarrow n = 11$$

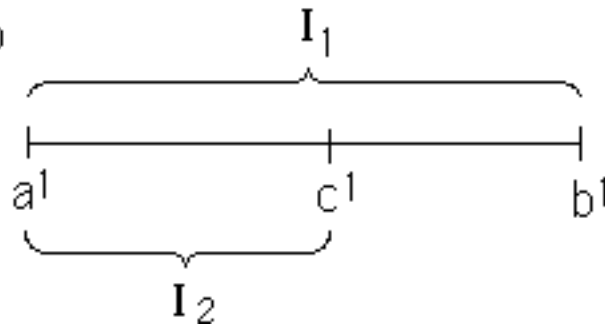
n	F_n
0	1
1	1
2	2
3	3
4	5
5	8
6	13
7	21
8	34
9	55
10	89
11	144
⋮	⋮

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Once we have determined n (the # of iterations), we can compute

$$\begin{aligned} I_2 &= F_{n-1} \left[\frac{1 + F_{n-2} \epsilon}{F_n} \right] - F_{n-3} \epsilon \\ &= \frac{F_{n-1}}{F_n} + \left[\frac{F_{n-1} F_{n-2}}{F_n} \right] \epsilon \end{aligned}$$

This will tell us where to put our initial interior point c^1 within $[a^1, b^1]$.



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Example

For example, suppose $n = 11$ and $\epsilon \approx 0$

$$I_2 \approx \frac{F_{10}}{F_{11}} \approx 0.6180555$$

Throughout the remainder of the iterations, the other interior points are located to retain the symmetry of c^k and d^k .



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Polynomial Interpolation

In quadratic & cubic interpolation methods, we use information about the function at two or more points to determine a polynomial in agreement with the known information about the function f .

A minimum point is then computed for the interpolating polynomial to obtain a new point interior to the interval of uncertainty $[a,b]$.



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Polynomial	Given information
Quadratic	$a, f(a), b, f(b), c \in (a,b), f(c)$
Cubic	$a, f(a), f'(a), b, f(b), f'(b)$

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Polynomial Interpolation

- ☞ Lagrange's Interpolating Polynomials
polynomials $p(x)$ with $p(a)=f(a)$, etc.
- ☞ Quadratic Interpolation
- ☞ Hermite Interpolating Polynomials
polynomials $p(x)$ with $p(a)=f(a)$, $p'(a)=f'(a)$
- ☞ Cubic Interpolation

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Lagrange's Interpolating Polynomials

Assume that we are given the $n+1$ values

$$\{ x_0, x_1, x_2, \dots, x_n \}$$

and function values $f(x_i)$,

What is the polynomial $p(x)$ of degree n which agrees exactly with $f(x)$ at the values $x_i, i=0,1,2,\dots,n$?



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Define

$$\mathcal{L}_j(\mathbf{x}) = \prod_{k \neq j} \frac{\mathbf{x} - \mathbf{x}_k}{\mathbf{x}_j - \mathbf{x}_k} = \frac{\mathbf{x} - \mathbf{x}_0}{\mathbf{x}_j - \mathbf{x}_0} \times \frac{\mathbf{x} - \mathbf{x}_1}{\mathbf{x}_j - \mathbf{x}_1} \times \cdots \times \frac{\mathbf{x} - \mathbf{x}_n}{\mathbf{x}_j - \mathbf{x}_n}$$

Properties:

$\mathcal{L}_j(\mathbf{x})$ is a polynomial
of degree n

$$\mathcal{L}_j(\mathbf{x}_j) = 1$$

$$\mathcal{L}_j(\mathbf{x}_k) = 0 \quad \text{for } k \neq j$$

That is, for each \mathbf{x}_j we define a polynomial of degree n which is 1 at \mathbf{x}_j but zero for $\mathbf{x}_k, k \neq j$.

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Lagrange's interpolating polynomial is

$$\mathbf{p}(\mathbf{x}) = \sum_{j=0}^n \mathbf{f}(\mathbf{x}_j) \mathcal{L}_j(\mathbf{x})$$

This polynomial agrees exactly with the function \mathbf{f} at $\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$

i.e.,
$$\mathbf{p}(\mathbf{x}_k) = \sum_{j=0}^n \mathbf{f}(\mathbf{x}_j) \mathcal{L}_j(\mathbf{x}_k) = \mathbf{f}(\mathbf{x}_k) \quad \forall k=0,1,2,\dots,n$$



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Hermite Interpolating Polynomials

Assume that we are given
the $n+1$ triplets of values

$$\begin{aligned} & x_0, f(x_0), f'(x_0) \\ & x_1, f(x_1), f'(x_1) \\ & \vdots \\ & x_n, f(x_n), f'(x_n) \end{aligned}$$

We want to find a polynomial $p(x)$ such that

$$\begin{aligned} p(x_i) &= f(x_i) \\ p'(x_i) &= f'(x_i) \end{aligned} \quad \forall i=0,1,\dots,n$$



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Notation

$$\begin{aligned} f_i &\equiv f(x_i) \\ f'_i &\equiv f'(x_i) = \frac{df}{dx}(x_i) \end{aligned}$$

The polynomial $p(x)$ will be of the form

$$p(x) = \sum_{j=0}^n f_j h_j(x) + \sum_{j=0}^n f'_j \bar{h}_j(x)$$

In order that $p(x_i) = f(x_i)$
 h_j and \bar{h}_j will satisfy

$$\begin{aligned} h_j(x_j) &= 1 \\ h_j(x_k) &= 0 \quad \forall k \neq j \\ \bar{h}_j(x_k) &= 0 \quad \forall k \neq j \end{aligned}$$

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Differentiating $p(x) = \sum_{j=0}^n f_j h_j(x) + \sum_{j=0}^n f'_j \bar{h}_j(x)$

yields $p'(x) = \sum_{j=0}^n f_j h'_j(x) + \sum_{j=0}^n f'_j \bar{h}'_j(x)$

We would therefore like h_j and \bar{h}_j to satisfy

$$\begin{aligned} h'_j(x_k) &= 0 \quad \forall k \neq j \\ \bar{h}'_j(x_k) &= \begin{cases} 1 & \text{if } k = j \\ 0 & \text{if } k \neq j \end{cases} \end{aligned}$$

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The following functions have the desired properties:

$$\begin{aligned} h_j(x) &= [1 - 2(x - x_j) \mathcal{L}'_j(x_j)] \mathcal{L}_j^2(x) \\ \bar{h}_j(x) &= (x - x_j) \mathcal{L}_j^2(x) \end{aligned}$$



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Quadratic Interpolation

Given: a, b, c
and $f(a), f(b), f(c)$

The interpolating quadratic polynomial is

$$p(x) = f(a) \frac{x-b}{a-b} \times \frac{x-c}{a-c} + f(b) \frac{x-a}{b-a} \times \frac{x-c}{b-c} + f(c) \frac{x-a}{c-a} \times \frac{x-b}{c-b}$$

We want to find the minimum of this polynomial,

and so we will find x such that $\frac{dp(x)}{dx} = 0$



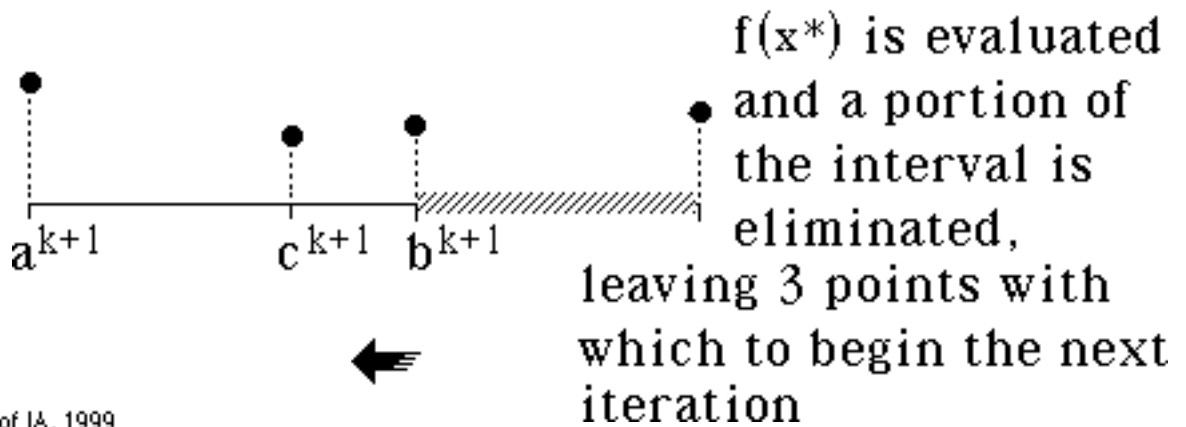
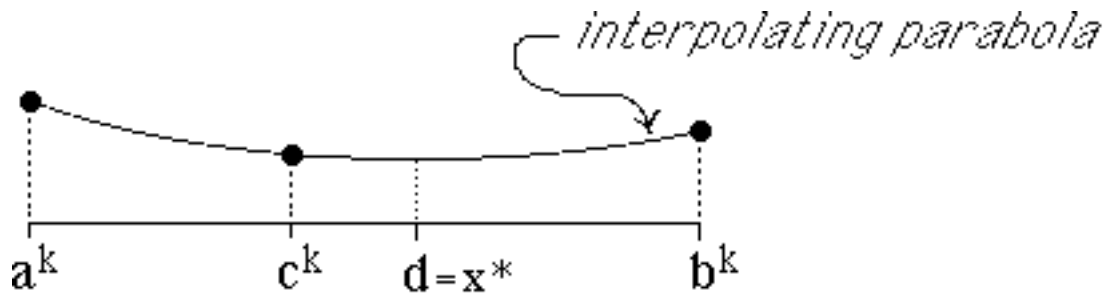
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$$\begin{aligned} \frac{dp(x)}{dx} = & \frac{f(a)}{(a-b)(a-c)} (2x-b-c) + \frac{f(b)}{(b-a)(b-c)} (2x-a-c) \\ & + \frac{f(c)}{(c-a)(c-b)} (2x-a-b) = 0 \end{aligned}$$

$$\Rightarrow x^* = \frac{1}{2} \frac{f(a)(b^2 - c^2) + f(b)(c^2 - a^2) + f(c)(a^2 - b^2)}{f(a)(b-c) + f(b)(c-a) + f(c)(a-b)}$$

Having located this 4th point (call it d), evaluate $f(d)$ and proceed as in Golden Section or Fibonacci search, eliminating a portion of the interval $[a,b]$

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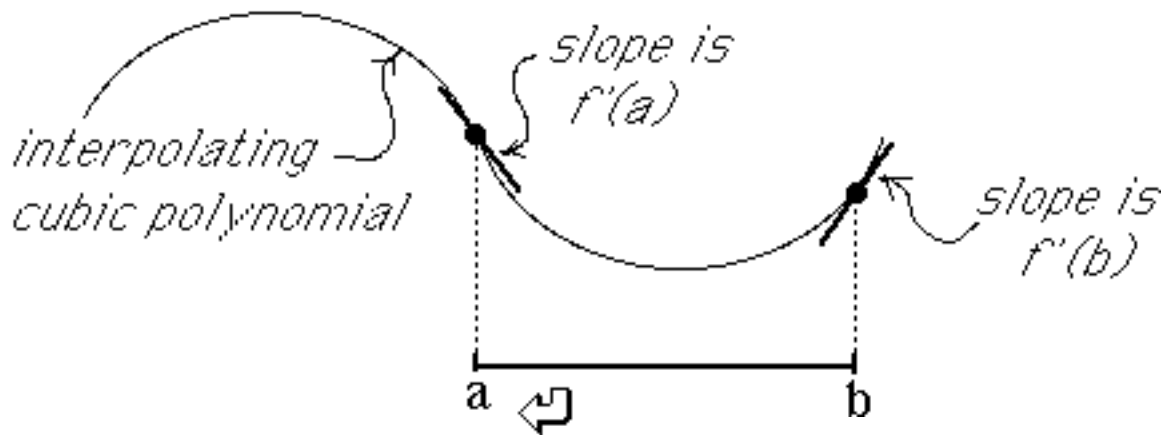


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Cubic Interpolation

Given $a, f(a), f'(a),$ and $b, f(b), f'(b),$

there is a unique cubic polynomial which passes through the points $(a, f(a)), (b, f(b))$ and is tangent to the graph at these points.

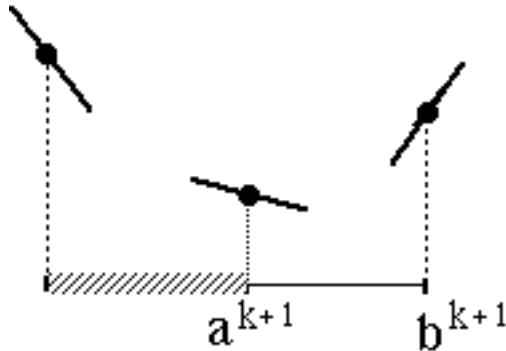


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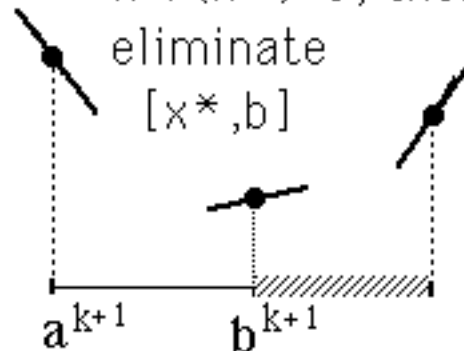
interpolating cubic polynomial

CUBIC INTERPOLATION

If $f'(x^*) < 0$, then eliminate $[a, x^*]$



If $f'(x^*) > 0$, then eliminate $[x^*, b]$



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**Cubic Interpolation,
Using Hermite Polynomials**

Given

$a, f(a), f'(a),$ and $b, f(b), f'(b)$

The interpolating CUBIC polynomial is

$$p(x) = f(a)h_0(x) + f(b)h_1(x) + f'(a)\bar{h}_0(x) + f'(b)\bar{h}_1(x)$$

where

$$h_0(x) = \left[1 - 2 \frac{x - a}{a - b}\right] \left[\frac{x - b}{a - b}\right]^2$$

$$\bar{h}_0(x) = (x - a) \left[\frac{x - b}{a - b}\right]^2$$

$$h_1(x) = \left[1 - 2 \frac{x - b}{b - a}\right] \left[\frac{x - a}{b - a}\right]^2$$

$$\bar{h}_1(x) = (x - b) \left[\frac{x - a}{b - a}\right]^2$$

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Finding the stationary point of $p(x)$ in $[a,b]$

$$\text{Step 1: } z = f'(a) + f'(b) + 3 \left[\frac{f(a) - f(b)}{b - a} \right]$$

$$\text{Step 2: } w = \sqrt{\max \{0, z^2 - f'(a) \times f'(b)\}}$$

$$\text{Step 3: } x^* = b - \frac{(b - a)(f'(b) + w - z)}{f'(b) + 2w - f'(a)}$$

