

Stokes Stream Function & Axisymmetric Flow

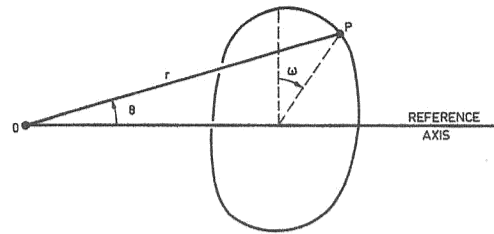


FIGURE 5.1
Definition sketch of spherical coordinates.

$w = \psi$

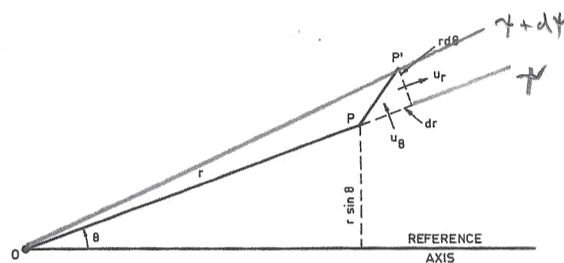


FIGURE 5.2
Velocity components and flow areas defined by a reference point P and neighboring point P'.

$d\theta > 0$
 $dr > 0$

$$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (u_\theta \sin \theta) = 0$$

Continuity equation

$$\nabla \cdot \underline{U} \text{ for } \frac{\partial \psi}{\partial \theta} = 0$$

$$\text{for } u_r = \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \theta} \quad \text{and} \quad u_\theta = -\frac{1}{r \sin \theta} \frac{\partial \psi}{\partial r}$$

$\nabla \cdot \underline{U}$ identically satisfied

Let OP rotate around reference axis such that w varies by 2π while r, θ fixed. The amount of fluid that crosses the surface of revolution formed by OP is

$\pi r^2 = \text{circumference circle generated by OP rotated } 2\pi$

$$2\pi d\psi = 2\pi r \sin \theta (u_r r d\theta - u_\theta dr) = dQ \quad \begin{matrix} \text{quantity of fluid per unit area} \\ \text{outflow - inflow} \end{matrix}$$

$$d\psi = u_r r^2 \sin \theta d\theta - u_\theta r \sin \theta dr = dQ / 2\pi$$

$$= \frac{\partial \psi}{\partial \theta} d\theta + \frac{\partial \psi}{\partial r} dr$$

= difference in flow rate per unit radius

$$\text{ie } \frac{\partial \psi}{\partial \theta} = u_r r^2 \sin \theta \quad \text{and} \quad \frac{\partial \psi}{\partial r} = -u_\theta r \sin \theta$$

with units m^3/s

Note in 2D plane flow ψ has units $\frac{m^2}{s}$

B3. Spherical Polar Coordinates

The spherical polar coordinates used are (r, θ, φ) , where φ is the azimuthal angle (Figure 3.1c). Equations are presented assuming ψ is a scalar, and

$$\mathbf{u} = \mathbf{i}_r u_r + \mathbf{i}_\theta u_\theta + \mathbf{i}_\varphi u_\varphi,$$

where \mathbf{i}_r , \mathbf{i}_θ , and \mathbf{i}_φ are the local unit vectors at a point.

Gradient of a scalar

$$\nabla \psi = \mathbf{i}_r \frac{\partial \psi}{\partial r} + \mathbf{i}_\theta \frac{1}{r} \frac{\partial \psi}{\partial \theta} + \mathbf{i}_\varphi \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \varphi}.$$

Laplacian of a scalar

$$\nabla^2 \psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \psi}{\partial \varphi^2}.$$

Divergence of a vector

$$\nabla \cdot \mathbf{u} = \frac{1}{r^2} \frac{\partial (r^2 u_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial u_\varphi}{\partial \varphi}.$$

Curl of a vector

$$\begin{aligned} \nabla \times \mathbf{u} = & \frac{\mathbf{i}_r}{r \sin \theta} \left[\frac{\partial (u_\varphi \sin \theta)}{\partial \theta} - \frac{\partial u_\theta}{\partial \varphi} \right] + \frac{\mathbf{i}_\theta}{r} \left[\frac{1}{\sin \theta} \frac{\partial u_r}{\partial \varphi} - \frac{\partial (r u_\varphi)}{\partial r} \right] \\ & + \frac{\mathbf{i}_\varphi}{r} \left[\frac{\partial (r u_\theta)}{\partial r} - \frac{\partial u_r}{\partial \theta} \right]. \end{aligned}$$

Laplacian of a vector

$$\begin{aligned} \nabla^2 \mathbf{u} = & \mathbf{i}_r \left[\nabla^2 u_r - \frac{2u_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\varphi}{\partial \varphi} \right] \\ & + \mathbf{i}_\theta \left[\nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\varphi}{\partial \varphi} \right] \\ & + \mathbf{i}_\varphi \left[\nabla^2 u_\varphi + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \varphi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \varphi} - \frac{u_\varphi}{r^2 \sin^2 \theta} \right]. \end{aligned}$$

Strain rate and viscous stress (for incompressible form $\sigma_{ij} = 2\mu e_{ij}$)

$$e_{rr} = \frac{\partial u_r}{\partial r} = \frac{1}{2\mu} \sigma_{rr},$$

$$e_{\theta\theta} = \frac{1}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r}{r} = \frac{1}{2\mu} \sigma_{\theta\theta},$$

$$e_{\varphi\varphi} = \frac{1}{r \sin \theta} \frac{\partial u_\varphi}{\partial \varphi} + \frac{u_r}{r} + \frac{u_\theta \cot \theta}{r} = \frac{1}{2\mu} \sigma_{\varphi\varphi},$$

$$e_{\theta\varphi} = \frac{\sin \theta}{2r} \frac{\partial}{\partial \theta} \left(\frac{u_\varphi}{\sin \theta} \right) + \frac{1}{2r \sin \theta} \frac{\partial u_\theta}{\partial \varphi} = \frac{1}{2\mu} \sigma_{\theta\varphi},$$

$$e_{\varphi r} = \frac{1}{2r \sin \theta} \frac{\partial u_r}{\partial \varphi} + \frac{r}{2} \frac{\partial}{\partial r} \left(\frac{u_\varphi}{r} \right) = \frac{1}{2\mu} \sigma_{\varphi r},$$

$$e_{r\theta} = \frac{r}{2} \frac{\partial}{\partial r} \left(\frac{u_\theta}{r} \right) + \frac{1}{2r} \frac{\partial u_r}{\partial \theta} = \frac{1}{2\mu} \sigma_{r\theta}.$$

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

Spherical
coordinates

Vorticity

$$\omega_r = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (u_\varphi \sin \theta) - \frac{\partial u_\theta}{\partial \varphi} \right],$$

$$\omega_\theta = \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial u_r}{\partial \varphi} - \frac{\partial (r u_\varphi)}{\partial r} \right],$$

$$\omega_\varphi = \frac{1}{r} \left[\frac{\partial}{\partial r} (r u_\theta) - \frac{\partial u_r}{\partial \theta} \right].$$

Equation of continuity

$$\frac{\partial \rho}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r} (\rho r^2 u_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\rho u_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} (\rho u_\varphi) = 0.$$

Navier-Stokes equations with constant ρ and ν , and no body force

$$\begin{aligned} \frac{\partial u_r}{\partial t} + (\mathbf{u} \cdot \nabla) u_r - \frac{u_\theta^2 + u_\varphi^2}{r} \\ = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left[\nabla^2 u_r - \frac{2u_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial (u_\theta \sin \theta)}{\partial \theta} - \frac{2}{r^2 \sin \theta} \frac{\partial u_\varphi}{\partial \varphi} \right], \end{aligned}$$

$$\begin{aligned} \frac{\partial u_\theta}{\partial t} + (\mathbf{u} \cdot \nabla) u_\theta + \frac{u_r u_\theta}{r} - \frac{u_\varphi^2 \cot \theta}{r} \\ = -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left[\nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\varphi}{\partial \varphi} \right], \end{aligned}$$

$$\begin{aligned} \frac{\partial u_\varphi}{\partial t} + (\mathbf{u} \cdot \nabla) u_\varphi + \frac{u_\varphi u_r}{r} + \frac{u_\theta u_\varphi \cot \theta}{r} \\ = -\frac{1}{\rho r \sin \theta} \frac{\partial p}{\partial \varphi} + \nu \left[\nabla^2 u_\varphi + \frac{2}{r^2 \sin \theta} \frac{\partial u_r}{\partial \varphi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial u_\theta}{\partial \varphi} - \frac{u_\varphi}{r^2 \sin^2 \theta} \right], \end{aligned}$$

where

$$\mathbf{u} \cdot \nabla = u_r \frac{\partial}{\partial r} + \frac{u_\theta}{r} \frac{\partial}{\partial \theta} + \frac{u_\varphi}{r \sin \theta} \frac{\partial}{\partial \varphi},$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}.$$

Stokes sphere solution using separation of variables

$$\nabla p = \mu \nabla^2 \underline{v}$$

$$0 = \nabla^2 \underline{\omega}$$

$$\text{note: } -\nabla \times \nabla \times \underline{\omega} = -\nabla(\nabla \cdot \underline{\omega}) + \nabla^2 \underline{\omega}$$

only component of velocity is

$$\omega_\theta = \frac{1}{r} \left(\frac{\partial}{\partial r}(r u_\theta) - \frac{\partial u_r}{\partial \theta} \right)$$

rearrange

$$\underline{v} = -\nabla \omega \times \nabla \chi = -\frac{\hat{z}_0}{r \sin \theta} \times \left(\hat{z}_r \chi_r + \hat{z}_\theta \frac{\chi_\theta}{r} + \frac{\hat{z}_\theta}{r \sin \theta} \chi_\theta \right)$$

$$= -\frac{\hat{z}_0}{r \sin \theta} \chi_r + \frac{\hat{z}_r}{r \sin \theta} \frac{\chi_\theta}{r}$$

$$= \underbrace{\frac{\chi_\theta}{r \sin \theta}}_{u_r} \hat{z}_r - \underbrace{\frac{\chi_r}{r \sin \theta}}_{u_\theta} \hat{z}_\theta$$

$$\omega_\theta = -\frac{1}{r} \left[\frac{\chi_r}{\sin \theta} + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \chi_\theta \right) \right]$$

$$\text{combine with } \nabla^2 \omega_\theta = 0 \Rightarrow \left[\frac{\partial^2}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right) \right]^2 \chi = 0 \quad (1)$$

$$\chi_\theta(a, \theta) = 0$$

$$\chi_r(a, \theta) = 0$$

$$\chi(\infty, \theta) = \frac{1}{2} U r^2 \sin^2 \theta$$

$$u_r = 0$$

$$u_\theta = 0$$

uniform flow @ ∞

} $r=a$
no slip

$$\text{Assume } \chi = f(r) \sin^2 \theta$$

is separation of variables used for field solution

substitution in (1)

$$f^{(4)} - \frac{4f''}{r^2} + \frac{8f'}{r^3} - \frac{8f}{r^4} = 0$$

$$f = Av^4 + Bv^2 + cv + D/r$$

∞ condition: $A=0$ and $B = \sigma/2$

$r=a$ condition: $c = -3\sigma a/4$ and $D = \sigma a^3/4$

$$\chi = \sigma v^2 \sin^2 \theta \left[\frac{1}{2} - \frac{3a}{4v} + \frac{a^3}{4v^3} \right]$$

$$= \frac{\sigma \sin^2 \theta}{4} \left[2v^2 - 3av + \frac{a^3}{v} \right]$$

\uparrow uniform flow \uparrow Stokeslet \uparrow dipole

$$u_v = \sigma \cos \theta \left(1 - \frac{3a}{2v} + \frac{a^3}{2v^3} \right)$$

$$u_\theta = -\sigma \sin \theta \left(1 - \frac{3a}{4v} - \frac{a^3}{4v^3} \right)$$

p_{max}/p_{min}
at fwd/bk

Stagnation points
 $= \pm 3\mu\sigma/2a$

$$\nabla p = \mu \nabla^2 \underline{v}$$

$$p = -\frac{3a\mu \cos \theta}{2r^2} + p_\infty$$

p is anti-symmetric
+ front - back
center pressure drag

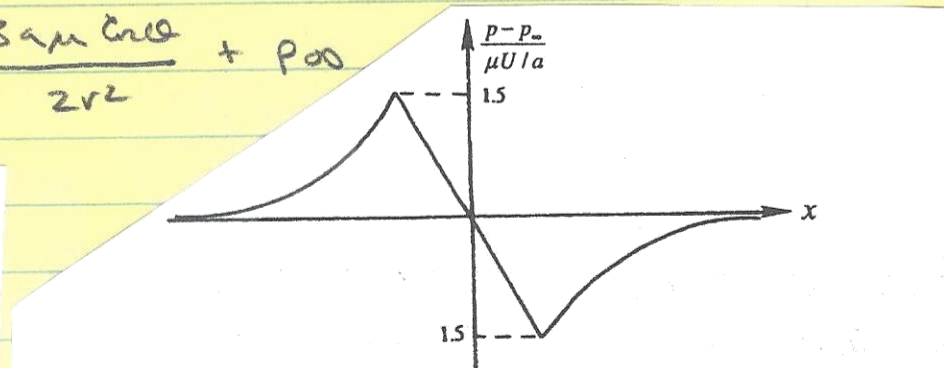
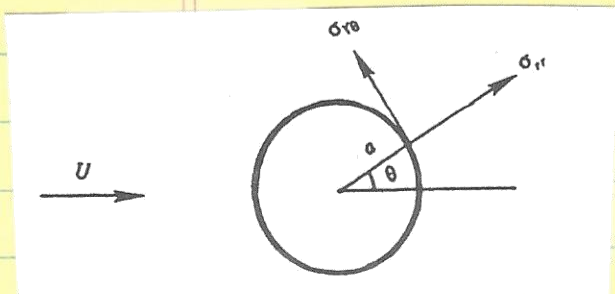


Figure 9.14 Creeping flow over a sphere. The upper panel shows the viscous stress components at the surface. The lower panel shows the pressure distribution in an axial ($\varphi = \text{const.}$) plane.

Viscous shear stress

$$\tau_{rr} = 2\mu \frac{\partial v_r}{\partial r} = 2\mu U \cos\theta \left[\frac{3a}{2r^2} - \frac{3a^3}{2r^4} \right]$$

σ in
 F_x

$$\tau_{r\theta} = \mu \left[\frac{1}{r} \frac{\partial v_r}{\partial \theta} + \frac{\partial u_\theta}{\partial r} - \frac{u_\theta}{r} \right] = -\frac{\mu U \sin\theta}{r} \left(\frac{3a^3}{2r^3} \right)$$

$$F = - \int_0^{2\pi} \tau_{r\theta} \Big|_{r=a} \sin\theta dA - \int_0^{2\pi} p \Big|_{r=a} \cos\theta dA$$

$$dA = 2\pi a^2 \sin\theta d\theta$$

$$\text{Surface area: } 4\pi a^2$$

$$V: \frac{4}{3}\pi a^3$$

$$F = \underbrace{4\pi\mu U a}_{2/3 \text{ viscous}} + \underbrace{2\pi\mu U a}_{1/3 \text{ pressure}} = 6\pi\mu U a \quad \propto U$$

$\propto \mu$

$Re \ll 1$, but agrees EFD upto $Re=1$

$$\frac{F}{\mu U a} = 6\pi = \text{constant} \quad \text{since } \nabla \cdot \nabla \psi = 0$$

R not important

$$C_D = \frac{2F}{\rho U^2 4\pi a^2} = 24/Re \quad Re = \frac{2a\rho U}{\mu}$$

$Re > 20$ separation \uparrow drag \uparrow

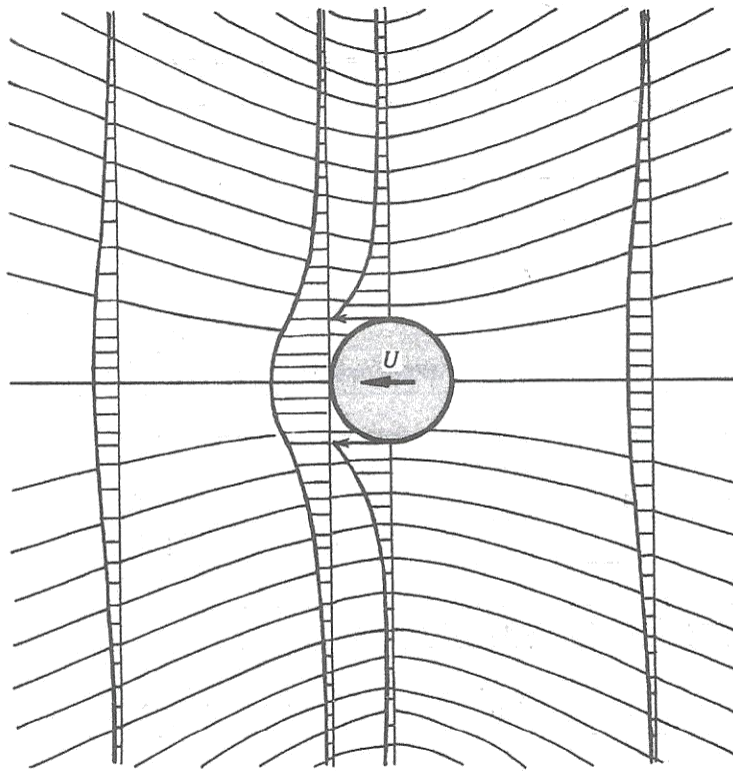


Figure 9.16 Streamlines and velocity distributions in Stokes' solution of creeping flow due to a moving sphere. Note the upstream and downstream symmetry, which is a result of complete neglect of nonlinearity.

marked reference frame γ - uniform stream $= U \sqrt{z} \sin \theta \left(-\frac{3a}{4\nu} + \frac{r^3}{4r^3} \right)$

Symmetric free Δ of $\mathbf{v} \cdot \nabla = 0$
 at no work ie change in direction
 just sign $-\mathbf{v}$ at $-\rho$

W or uniformity Stokes Solution: Oseen Approximation

$$\text{viscous free } \Delta = \text{shear gradient} \sim \frac{\mu U a}{\nu^3} \quad r \rightarrow \infty$$

$$\text{marked free } \Delta \sim \epsilon \nu \frac{\partial u_x}{\partial r} \sim \frac{\epsilon U a}{r^2} \quad r \rightarrow \infty$$

$$\frac{\text{marked free}}{\text{viscous free}} \sim \frac{\epsilon U a}{\mu} \frac{r}{a} = Re \frac{r}{a} \quad r \rightarrow \infty$$

marked not negligible for $\frac{r}{a} \sim \frac{1}{Re}$ no matter how small Re , which occurs at distances of order ν/U

It can be shown that under 1st order term ψ is infinite at large distances, which is called Whitehead paradox, as was the case for the 0th order 2D solution, which was called Stokes paradox: singular perturbation problems

Oseen improvement:

$$u = U + u' \quad v = v' \quad w = w' \quad u', v', w' = \text{Cartesian components}$$

e.g. X-momentum $u u_x + v u_y + w u_z = U u'_x + [u' u'_x + v' u'_y + w' u'_z]$ perturbation $\ll U$ at $r \rightarrow \infty$

Oseen Equations $\rho U \frac{\partial u'_i}{\partial x} = -\frac{\partial p}{\partial x_i} + \mu \nabla^2 u'_i$

$u'_i = (u', v', w')$ i.e. $\underline{v} \cdot \nabla \underline{v} \sim U \frac{\partial \underline{u}}{\partial x}$

Same order Stokes near body; however, in far field provides better approximation where solution $\sim U$

$$u' = v' = w' = 0 \quad r \rightarrow \infty$$

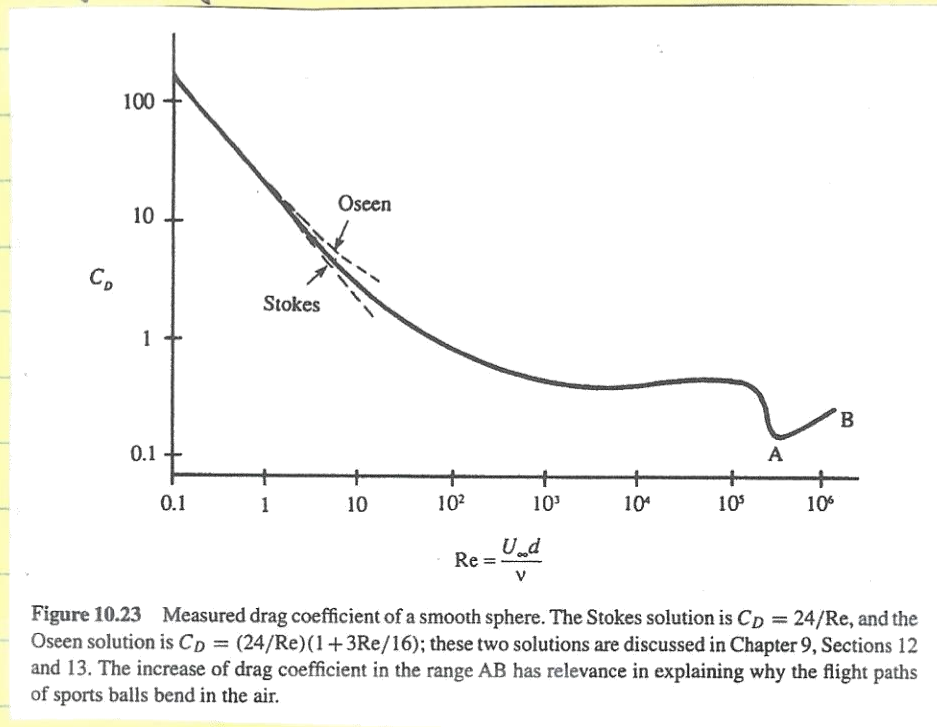
$$u' = -U \quad v' = w' = 0 \quad r = 0$$

$$\frac{\gamma}{\sigma a^2} = \left[\frac{r^2}{2a^2} + \frac{a}{4\nu} \right] \sin^2 \theta - \frac{3}{Re} (1 + \cos \theta) \left\{ 1 - \exp \left[-\frac{Re r}{4a} (1 - \cos \theta) \right] \right\}$$

$Re = 2aU/\nu$ $r/a \sim 1$ recover Stokes solution

$$C_D = \frac{24}{Re} \left(1 + \frac{3}{16} Re \right)$$

Lowest order solution uniformly valid near & far field



Oseen solution for
 matched reference
 frame. Flow no
 longer symmetric,
 but has a wake
 where γ closer together
 v less in wake than front,
 whereas in moving
 reference frame flow
 slower in wake than in front. Advanced methods use
 matched asymptotic expansion techniques

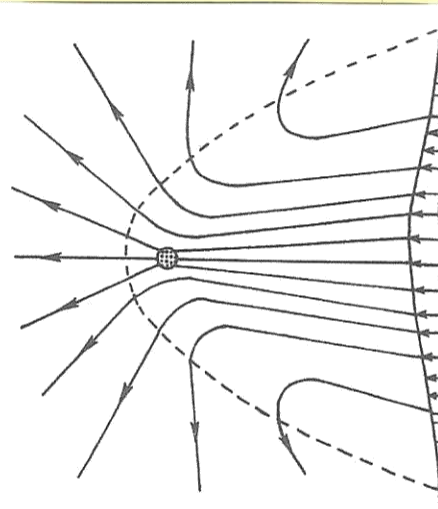


Figure 9.17 Streamlines and velocity distribution in Oseen's solution of creeping flow due to a moving sphere. Note the upstream and downstream asymmetry, which is a result of partial accounting for advection in the far field.

Exercise 9.45. Using the velocity field (8.49), determine the drag on Stokes' sphere from the surface pressure and the viscous surface stresses σ_{rr} and $\sigma_{r\theta}$.

Solution 9.45. There are pressure and shear stress contributions to the drag on a moving sphere at low Reynolds number. The pressure distribution is given by (8.50):

$$p(r, \theta) - p_\infty = -\frac{3\mu a U}{2r^2} \cos \theta.$$

The pressure drag can be obtained by integrating this result:

$$F_{\text{pressure}} = - \int_{\text{surface}} p(r = a, \theta) \mathbf{e}_r \cdot \mathbf{e}_z dS = -2\pi a^2 \int_{\theta=0}^{\theta=\pi} \mu \left(\frac{3U}{2a} \right) \cos^2 \theta \sin \theta d\theta = 2\pi\mu U a$$

The viscous drag can be obtained from surface integrals of the viscous stresses:

$$\begin{aligned} F_{\text{viscous}} &= - \int_{\text{surface}} \sigma_{r\theta}(r = a, \theta) \mathbf{e}_\theta \cdot \mathbf{e}_z dS + \int_{\text{surface}} \sigma_{rr}(r = a, \theta) \mathbf{e}_r \cdot \mathbf{e}_z dS \\ &= -2\pi a^2 \int_{\theta=0}^{\theta=\pi} \sigma_{r\theta}(r = a, \theta) \sin^2 \theta d\theta + 2\pi a^2 \int_{\theta=0}^{\theta=\pi} \sigma_{rr}(r = a, \theta) \cos \theta \sin \theta d\theta, \end{aligned}$$

where $\sigma_{r\theta} = \mu \left(\frac{1}{r} \frac{\partial u_r}{\partial \theta} + \frac{\partial u_\theta}{\partial r} - \frac{u_\theta}{r} \right) = -\frac{\mu U \sin \theta}{r} \left(\frac{3a^3}{2r^3} \right)$, and $\sigma_{rr} = 2\mu \frac{\partial u_r}{\partial r} = 2\mu U \cos \theta \left(\frac{3a}{2r^2} - \frac{3a^3}{2r^4} \right)$.

Thus, at $r = a$, $\sigma_{r\theta} \neq 0$, but $\sigma_{rr} = 0$, so

$$F_{\text{viscous}} = 3\pi\mu U a \int_{\theta=0}^{\theta=\pi} \sin^3 \theta d\theta = 4\pi\mu U a.$$

Thus, one third of the drag comes from pressure forces and two thirds come from the shear stress. The total drag is the sum of these two contributions:

$$F_{\text{drag}} = F_{\text{pressure}} + F_{\text{viscous}} = 2\pi\mu U a + 4\pi\mu U a = 6\pi\mu U a.$$

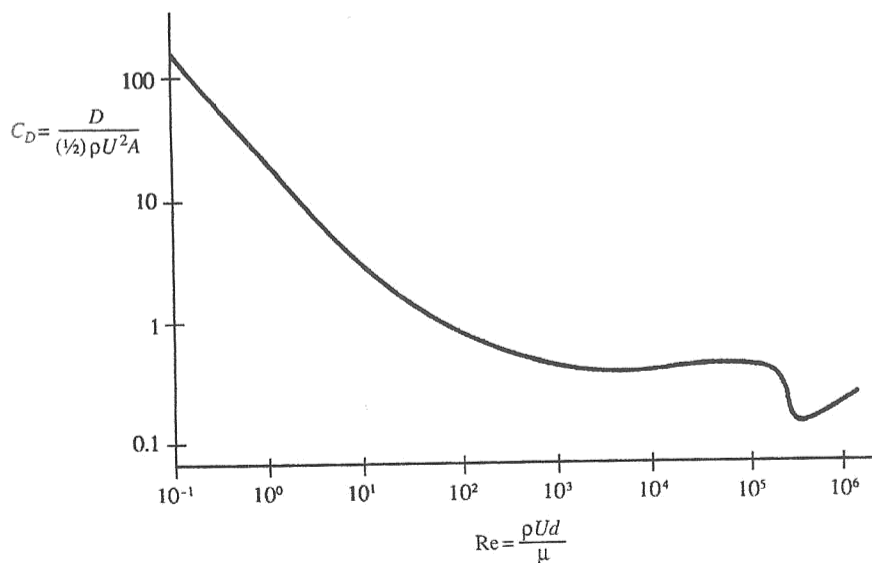


FIGURE 4.23 Coefficient of drag C_D for a sphere vs. the Reynolds number Re based on sphere diameter. At low Reynolds number $C_D \sim 1/Re$, and above $Re \sim 10^3$, $C_D \sim \text{constant}$ (except for the dip between $Re = 10^5$ and 10^6). These behaviors (except for the dip) can be explained by simple dimensional reasoning. The reason for the dip is the transition of the laminar boundary layer to a turbulent one, as explained in Chapter 10.

