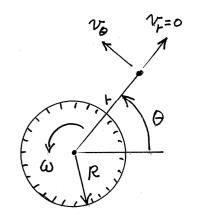
## 6.94

6.94 An infinitely long, solid, vertical cylinder of radius R is located in an infinite mass of an incompressible fluid. Start with the Navier-Stokes equation in the  $\theta$  direction and derive an expression for the velocity distribution for the steady flow case in which the cylinder is rotating about a fixed axis with a constant angular velocity  $\omega$ . You need not consider body forces. Assume that the flow is axisymmetric and the fluid is at rest at infinity.



For this flow field, 
$$v_{r}=0$$
,  $v_{z}=0$ , and from the continuity equation,
$$\frac{1}{r}\frac{\partial(rv_{r})}{\partial r}+\frac{1}{r}\frac{\partial v_{\theta}}{\partial \theta}+\frac{\partial v_{z}}{\partial z}=0 \qquad (Eq. 6.35)$$
It follows that 
$$\frac{\partial v_{\theta}}{\partial \theta}=0 \qquad (See figure for notation.)$$

Thus, the Navier-Stokes equation in the O-direction (Eq. 6.1286) for steady How reduces to

$$0 = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left[ \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_{\theta}}{\partial r} \right) - \frac{v_{\theta}}{r^2} \right]$$

Due to the symmetry of the How,

$$\frac{\partial P}{\partial B} = 0$$

so that

or

$$\frac{\partial^2 V_{\Theta}}{\partial r^2} + \frac{1}{r} \frac{\partial V_{\Theta}}{\partial r} - \frac{V_{\Theta}}{r^2} = 0 \tag{1}$$

Since Vo is a function of only r, Eq. (1) can be expressed as an ordinary differential equation, and Ve-written as

$$\frac{d^2 v_{\theta}}{dr^2} + \frac{d}{dr} \left( \frac{v_{\theta}}{r} \right) = 0 \tag{2}$$

Equation (2) can be integrated to yield

or
$$\frac{d v_0}{dr} + \frac{v_0}{r} = c_1$$

$$+ \frac{d v_0}{dr} + v_0 = c_1 r$$

$$(con't)$$
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(con't)

Equation (3) can be expressed as

$$\frac{d(rV_{\theta})}{dr} = c, r$$

and a second integration yields

$$+ v_{\theta}^{2} = \frac{c_{1} + c_{2}}{2} + c_{2}$$

or

$$\mathcal{V}_{\theta} = \frac{C_1 + C_2}{Z} + \frac{C_2}{F}$$

As  $t \to \infty$ ,  $v_0 \to 0$ , (since fluid is at rest at infinity) so that  $C_1 = 0$ . Thus,

and since at t=R,  $v_0=R\omega$ , it follows that  $c_2=R^2\omega$  and

$$V_{\theta} = \frac{R^2 \omega}{H}$$