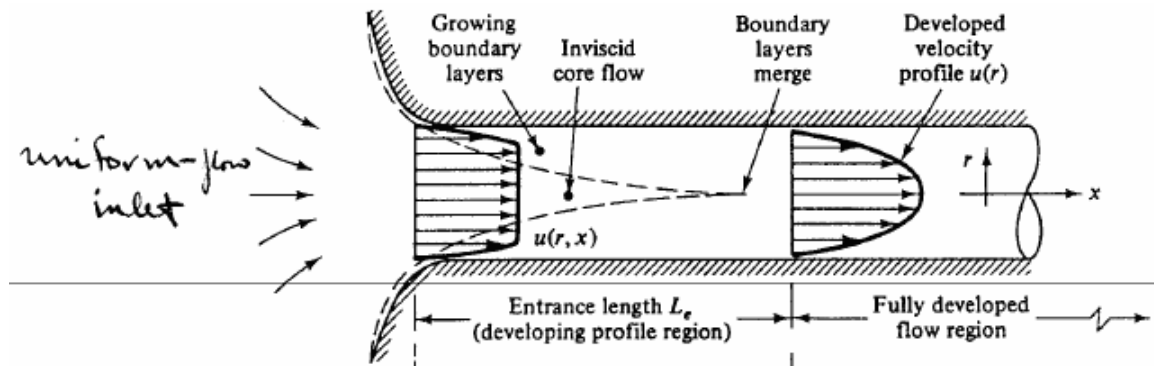
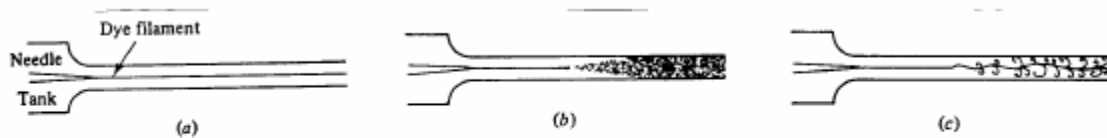


Review for Chapter 8 and Chapter 9

Chapter 8: Flow in Conduits



Laminar flow: $Re_{crit} \sim 2000$, i.e., for $Re < Re_{crit}$ laminar
 $Re > Re_{crit}$ turbulent



laminar

turbulent

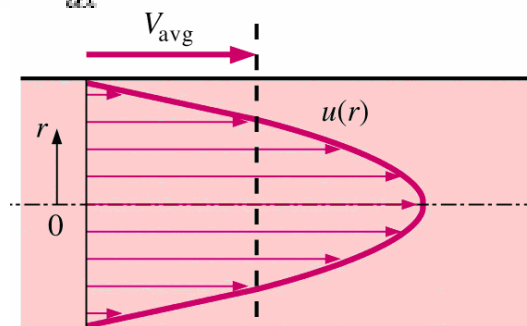
spark photo

Laminar Flow in Pipes

Velocity profile for laminar pipe flow

$$u(r) = \frac{r^2 - r_0^2}{4\mu} \frac{d}{dx}(p + \gamma z),$$

$u(r) > 0$ for $\frac{d}{dx}(p + \gamma z) < 0$, i.e., favorable pressure gradient



Laminar flow

Head loss and friction factor for laminar pipe flow (These are exact solutions!):

$$\frac{P_1}{\gamma} + \frac{V_1^2}{2g} + z_1 = \frac{P_2}{\gamma} + \frac{V_2^2}{2g} + z_2 + h_L$$

$$\Delta h = \left(\frac{P_2}{\gamma} + z_2 \right) - \left(\frac{P_1}{\gamma} + z_1 \right)$$

$$h_L = \frac{P_1 - P_2}{\gamma} + (z_1 - z_2) = -\Delta h$$

$$h_L = \frac{L}{\gamma} \left[-\frac{d}{ds} (p + \gamma z) \right] \quad L = \text{length of pipe} = ds$$

$$= \frac{L}{\gamma} \left[\frac{8\mu \bar{V}}{r_o^2} \right] = -\Delta h \alpha \bar{V}$$

$$h_L = L \left[-\frac{d}{ds} \left(\frac{p}{\gamma} + z \right) \right]$$

$$= L \left(-\frac{dh}{ds} \right)$$

or $h_f = h_L = \frac{32\mu L \bar{V}}{\gamma D^2}$ $h_f = \text{head loss due to friction}$

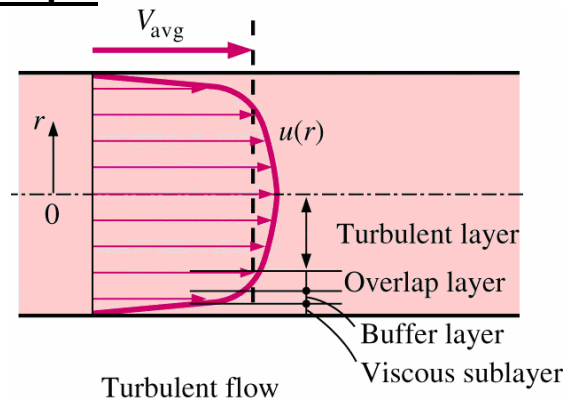
↙ exact solution

$$h_L = \frac{32\mu L V}{\gamma D^2} = f \frac{L V^2}{D 2g}$$

$$\tau_o = \frac{D \gamma h_L}{4 L} \Rightarrow h_L = \frac{4L \tau_o}{D \gamma} = 4L \frac{1}{8} \rho V^2 f / D \gamma = f \frac{L V^2}{D 2g}$$

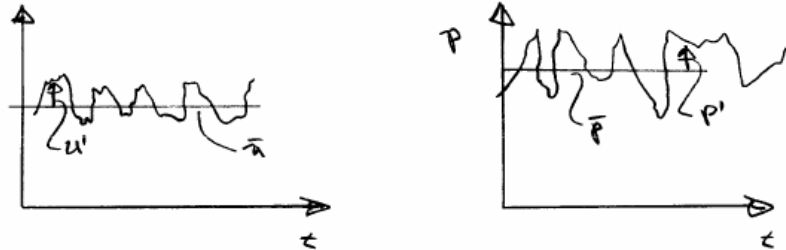
$$\therefore f = \frac{64}{Re} \quad Re = \frac{VD}{\nu}$$

Turbulent Flow in Pipes



$$h_f = f \cdot \frac{L}{D} \cdot \frac{\bar{V}^2}{2g} \quad \text{Darcy - Weisbach Equation}$$

Description of turbulent flow



Velocity and pressure are **random functions of time!!**

They can be separated into two parts such as **mean** and **fluctuation** components:

$$\begin{aligned} u &= \bar{u} + u' & p &= \bar{p} + p' \\ v &= \bar{v} + v' & \text{and for compressible flow} \\ w &= \bar{w} + w' & \rho &= \bar{\rho} + \rho' \text{ and } T = \bar{T} + T' \end{aligned}$$

Most important influence of turbulence on the mean motion:

→ An increase in the fluid stress by “Reynolds stresses”

$$\tau'_{ij} = -\rho \overline{u'_i u'_j}$$

$$= \begin{bmatrix} -\rho \overline{u'^2} & -\rho \overline{u'v'} & -\rho \overline{u'w'} \\ -\rho \overline{u'v'} & -\rho \overline{v'^2} & -\rho \overline{v'w'} \\ -\rho \overline{u'w'} & -\rho \overline{v'w'} & -\rho \overline{w'^2} \end{bmatrix}$$

Mean flow equations for turbulent flow

→ Reynolds Averaged Navier Stokes (RANS) equations

Continuity $\nabla \cdot \underline{V} = 0$ i.e. $\nabla \cdot \bar{\underline{V}} = 0$ and $\nabla \cdot \underline{V}' = 0$

Momentum $\rho \frac{D\bar{V}}{Dt} = -\rho g \hat{k} - \nabla \bar{p} + \nabla \cdot \tau_{ij}$

$$\tau_{ij} = \mu \left[\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right] - \underbrace{\rho \overline{u'_i u'_j}}_{\tau'_{ij}}$$

$u_1 = u$	$x_1 = x$
$u_2 = v$	$x_2 = y$
$u_3 = w$	$x_3 = z$

‘Modeling’ required!!

Turbulence Modeling:

a) Eddy viscosity, Mixing-length theory, One-equation model,
Two-equation model

→ ($k-\varepsilon$ model, $k-\omega$ model: **Recall CFD-PreLab2, Lab2!!**)

b) Mean-flow velocity profile correlations

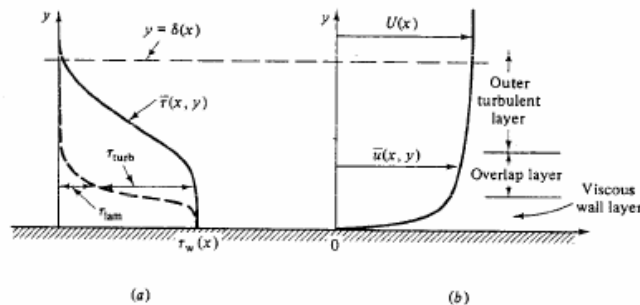


Fig. 6.9 Typical velocity and shear distributions in turbulent flow near a wall: (a) shear; (b) velocity. *(measurements)*

Inner layer: viscous stress dominates

Outer layer: turbulent stress dominates

Overlap layer: both types of stress important

1) Inner layer

$$u = f(\mu, \tau_w, \rho, y) \quad \text{note: not } f(\delta)$$

$$u^+ = f(y^+) \quad \text{law-of-the-wall}$$

$$u^+ = y^+$$

where: $u^+ = \frac{u}{u^*}$

$$u^* = \text{friction velocity} = \sqrt{\tau_w / \rho}$$

$$y^+ = \frac{yu^*}{\nu}$$

very near the wall:

$$\tau \sim \tau_w \sim \text{constant} = \mu \frac{du}{dy} \quad \Rightarrow \quad u = cy \quad \text{or} \quad u^+ = y^+$$

2) Outer layer

$$\frac{U_e - u}{u^*} = f\left(\frac{y}{\delta}\right) \quad \text{velocity defect law}$$

3) Overlap layer

$$\frac{u}{u^*} = \frac{1}{\kappa} \ln y^+ + B \quad \text{log-law}$$

\uparrow \uparrow
 .41 5

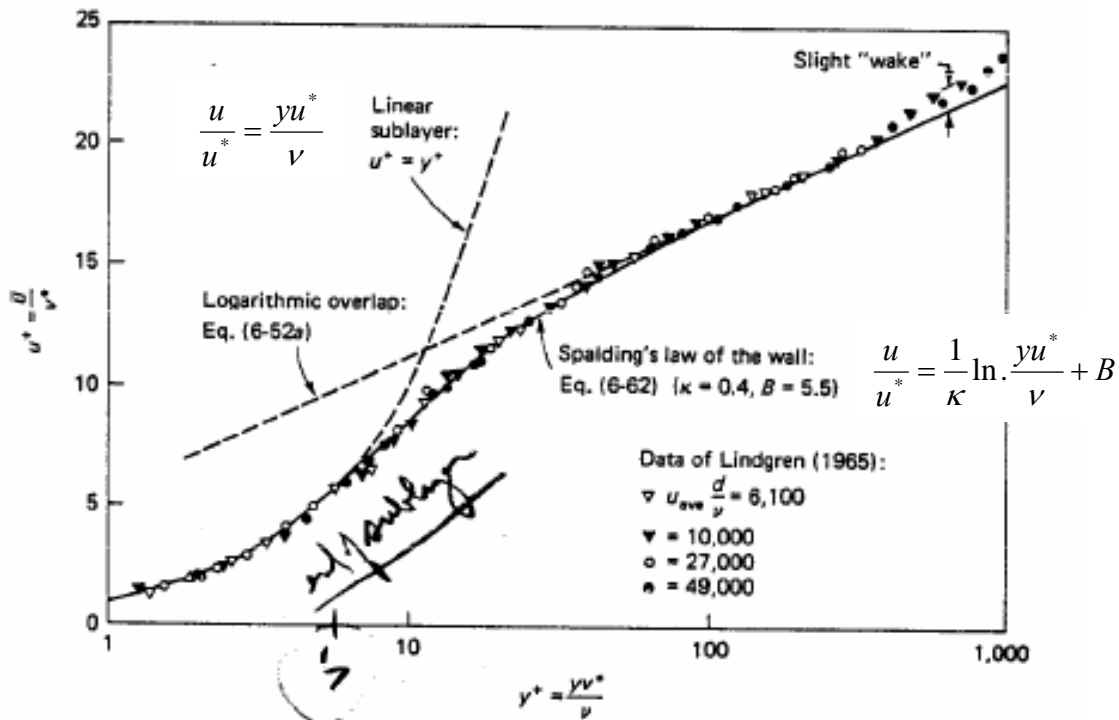


FIGURE 6-6
Comparison of Spalding's inner-law expression with the pipe-flow data of Lindgren (1965).

Velocity distribution and resistance in smooth pipes

$$\frac{V}{u^*} = 2.44 \ln \frac{r_o u^*}{\nu} + 1.34 = \left(\frac{\rho V^2}{\tau_o} \right)^{1/2} = \left(\frac{8}{f} \right)^{1/2}$$

$$\frac{1}{2} \text{Re} \left(\frac{f}{8} \right)^{1/2}$$

$$\frac{1}{\sqrt{f}} = 2 \log(\text{Re} f^{1/2}) - .8 \quad \text{Re} > 3000$$

$$h_f = .316 \left(\frac{\mu}{\rho V D} \right)^{1/4} \frac{L V^2}{D 2g}$$

Velocity distribution and resistance in rough pipes:

Inner layer:

$$u^+ = u^+(y/k)$$

Overlap layer:

$$u_R^+ = \frac{1}{\kappa} \ln \frac{y}{k} + \text{constant} \quad \text{rough}$$

$$k^+ = \frac{\kappa u^*}{v}$$

1. $k^+ < 5$ hydraulically smooth (no effect of roughness)
2. $5 < k^+ < 70$ transitional roughness (Re dependence)
3. $k^+ > 70$ fully rough (independent Re)

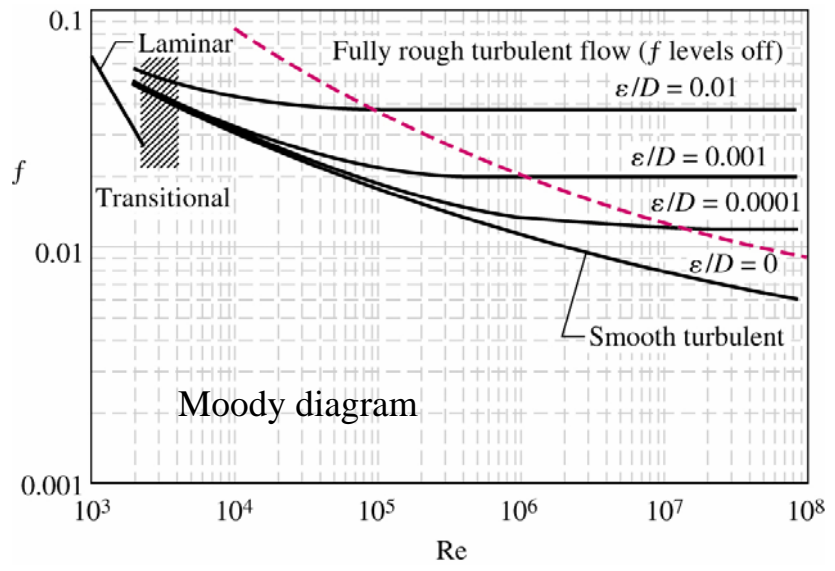
Head losses and friction factor for turbulent pipe flow:

Friction factor:

$$\frac{1}{\sqrt{f}} = 1.14 - 2 \log \left(\frac{k_s/D + 9.35/Re \sqrt{f}}{1} \right), \text{ as shown in Moody diagram}$$

$k_s/D =$ roughness parameter

$$h_t = f \frac{L V^2}{D 2g} = h_1 - h_2, \quad h_1 = \frac{P_1}{\gamma} + z_1, \quad h_2 = \frac{P_2}{\gamma} + z_2$$



Types of problems for turbulent pipe flow

Three Cononical Types of Problems

1. Determine The Head Loss

$$h_f = f \frac{L}{D} \frac{V^2}{2g} = -\Delta h = \left(\frac{p_1}{\gamma} + z_1 \right) - \left(\frac{p_2}{\gamma} + z_2 \right)$$

$$f = f(\text{Re}, k/D)$$

2. Determine The Flow Rate

$$V = \left[\frac{2gh_f}{L/D} \right]^{1/2} f^{-1/2}$$

known from problem statement

Given $f \rightarrow V \rightarrow \text{Re} \rightarrow f$, repeat to convergence

2. Determine The Pipe Diameter Rate

$$D = \left[\frac{8LQ^2}{\pi^2 gh_f} \right]^{1/5} f^{-1/5}$$

known from problem statement

Given $f \rightarrow D \rightarrow \text{Re}, k/D \rightarrow f$, repeat to convergence

Flows at pipe inlets and losses from fittings

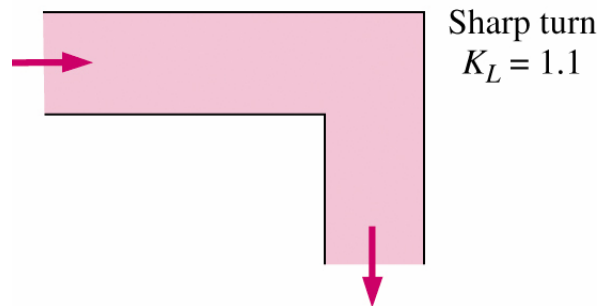
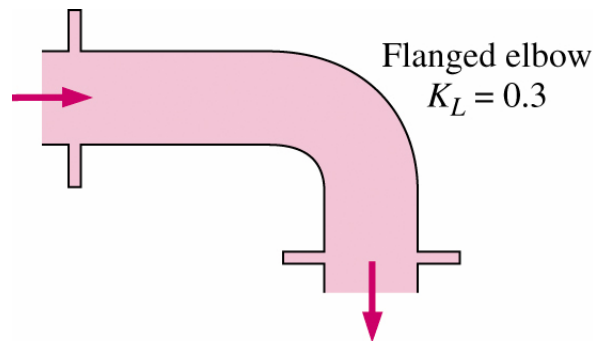
1. entrance and exit effects
 2. expansions and contractions
 3. bends, elbows, tees, and other fittings
 4. valves (open or partially closed)
- } can be large effect

Modified Energy Equation to Include Minor Losses:

$$\frac{p_1}{\gamma} + z_1 + \frac{1}{2g} \alpha_1 V_1^2 + h_p = \frac{p_2}{\gamma} + z_2 + \frac{1}{2g} \alpha_2 V_2^2 + h_t + h_f + \sum h_m$$

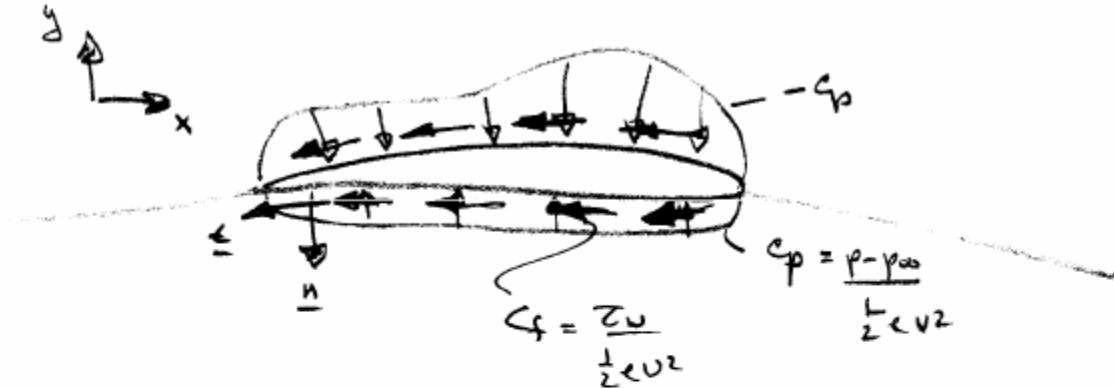
$h_m = K \frac{V^2}{2g}$

(K : minor loss coefficient \rightarrow Depending on the shape of the pipe inlet/exit/curvature)



Chapter 9: Flow over Immersed Bodies

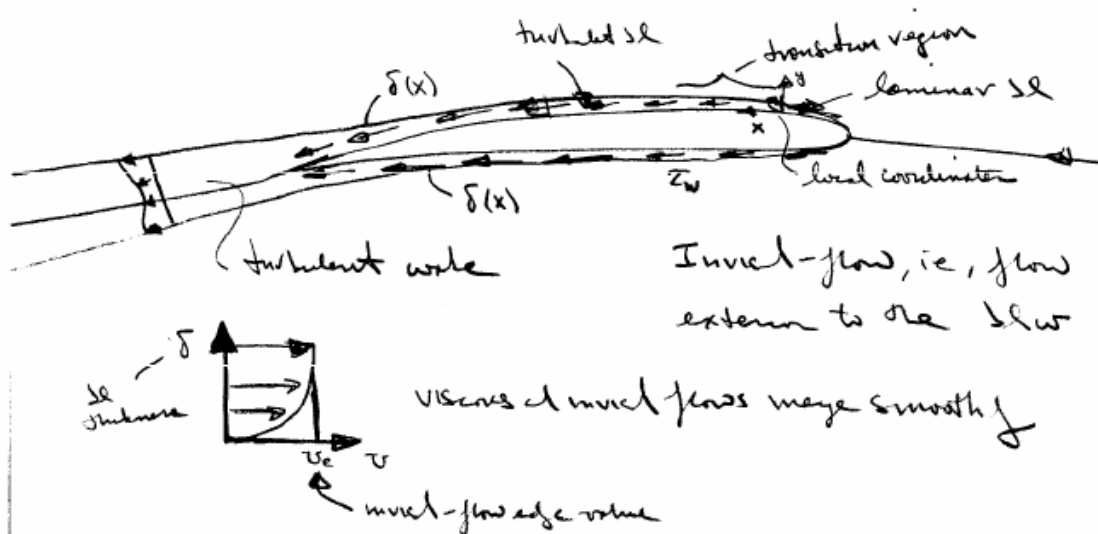
Separation of drag: Form and skin-friction



$$C_D = \frac{1}{\frac{1}{2}\rho V^2 A} \left\{ \underbrace{\int_S (p - p_\infty) \underline{n} \cdot \hat{i} dA}_{C_{Dp}} + \underbrace{\int_S \tau_w \underline{t} \cdot \hat{i} dA}_{C_f} \right\} : \text{Drag}$$

$$C_L = \frac{1}{\frac{1}{2}\rho V^2 A} \left\{ \int_S (p - p_\infty) \underline{n} \cdot \hat{j} dA \right\} : \text{Lift}$$

Qualitative description of the boundary layer



Boundary layer equation (2D case presented)

→ Obtained from NS equation order of magnitude for each terms

Variable	order of magnitude		
u	U	$O(1)$	$\varepsilon = \delta/L$
v	$\delta \ll L$	$O(\varepsilon)$	
$\frac{\partial}{\partial x}$	L	$O(1)$	
$\frac{\partial}{\partial y}$	$1/\delta$	$O(\varepsilon^{-1})$	
ν	δ^2	ε^2	

Boundary layer equation in 2D:

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2}$$

$$\frac{\partial p}{\partial y} = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

Quantitative relations for the laminar boundary layer

Laminar boundary layer over a flat plate → Blasius solution

$$\delta = \frac{5x}{\sqrt{Re}} \quad \text{value of } y \text{ where } u/U_\infty = .99$$

$$Re_x = \frac{U_\infty x}{\nu}$$

$$c_f = \frac{2\tau_w}{\rho U_\infty^2} = \frac{0.664}{\sqrt{Re_x}} = \frac{\theta}{x}$$

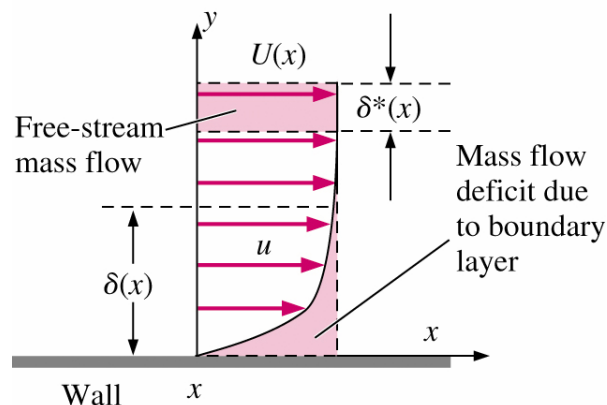
$$C_f = \frac{1}{L} \int_0^L c_f dx = 2c_f(L)$$

$$= \frac{1.328}{\sqrt{Re_L}}$$

$$\frac{U_\infty L}{\nu}$$

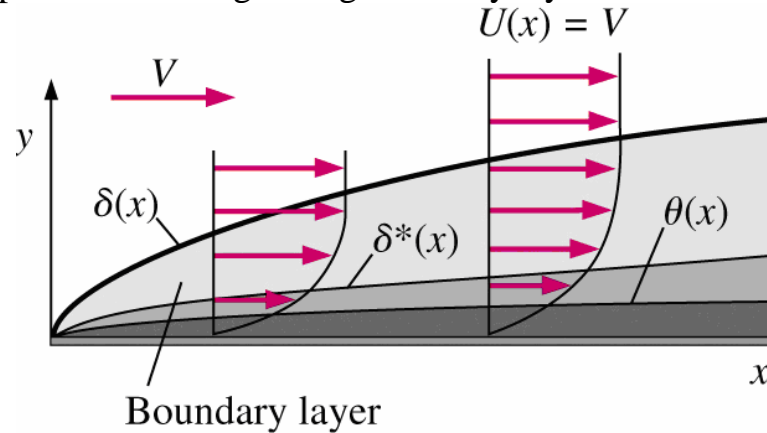
$$\delta^* = \int_0^\delta \left(1 - \frac{u}{U_\infty}\right) dy = 1.7208 \frac{x}{\sqrt{Re_x}} \quad \text{displacement thickness}$$

Displacement thickness: **imaginary increase** in thickness of the wall, as seen by the outer flow, due to the effect of the growing boundary layer.



$$\theta = \int_0^{\delta} \left(1 - \frac{u}{U_{\infty}}\right) \frac{u}{U_{\infty}} dy = 0.664 \frac{x}{\sqrt{\text{Re}_x}} \quad \text{momentum thickness}$$

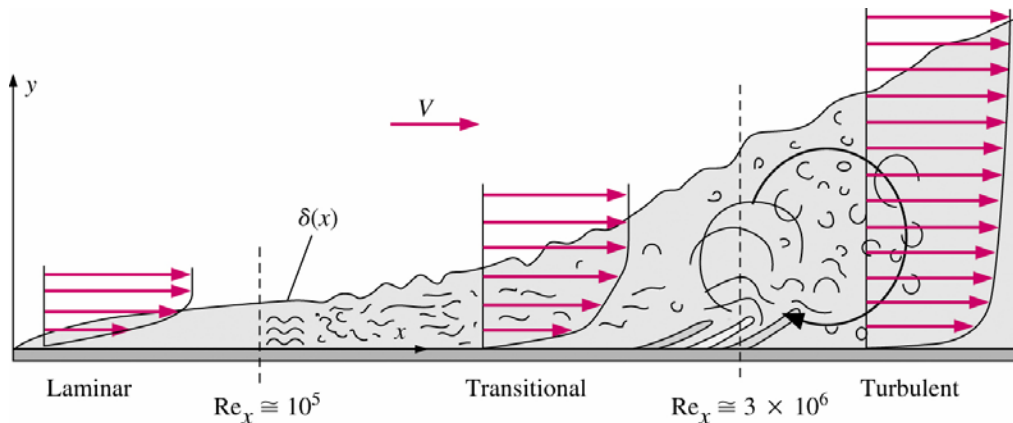
Momentum thickness: **the loss of momentum flux** per unit width divided by ρU^2 due to the presence of the growing boundary layer.



$$H = \text{shape parameter} = \frac{\delta^*}{\theta} = 2.5916$$

Quantitative relations for the turbulent boundary layer

Transition from laminar boundary-layer to turbulent boundary-layer:



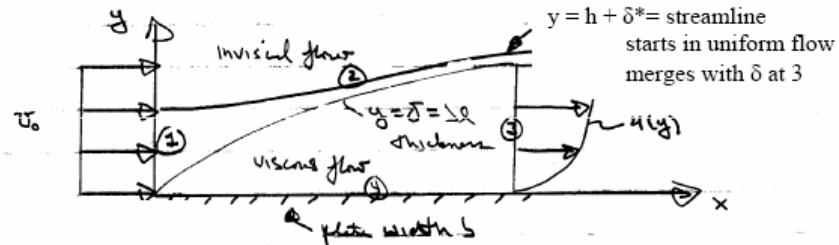
Engineering critical Reynolds number: $\text{Re}_{x, cr} = 5 \times 10^5$

→ $\text{Re}_x < \text{Re}_{x, cr}$: boundary layer is most likely laminar.

→ $\text{Re}_x > \text{Re}_{x, cr}$: boundary layer is most likely turbulent.

Momentum Integral Analysis: obtain general momentum integral relation

→ Valid for **both laminar and turbulent** flow



Steady
 $\rho = \text{constant}$
 neglect g
 $v \ll u = u_0 \Rightarrow p = \text{constant}$
 i.e., $-\nabla p = 0$

CV = 1, 2, 3, 4

$$-D = \text{drag} = b \int_0^x \tau_w dx \quad \text{pressure force} = 0 \text{ for } v \ll U_0$$

force on CV
wall shear stress
 $u \sim U_0$

$$\Sigma F_x = -D = \rho \int_1 u (\underline{V} \cdot d\underline{A}) + \rho \int_3 u (\underline{V} \cdot d\underline{A})$$

$$= \rho (-U_0^2 b h) + \rho b \int_3 u^2 dy$$

$$D(x) = \rho b U_0 \int_0^\delta u dy - \rho b \int_0^\delta u^2 dy$$

$$= \rho b \int_0^\delta u (U_0 - u) dy$$

$$C_D = \frac{D}{\frac{1}{2} \rho U_0^2 b L} = \frac{2}{L} \int_0^\delta \frac{u}{U_0} \left(1 - \frac{u}{U_0} \right) dy$$

$\theta = \text{momentum thickness}$

On the other hand, C_D can be expressed as

$$C_D = \frac{D}{\frac{1}{2} \rho U_0^2 A} = \frac{b \int_0^x \tau_w dx}{\frac{1}{2} \rho U_0^2 b L} = \frac{2\theta}{L}$$

Then,

$$\int_0^x \frac{\tau_w}{\frac{1}{2} \rho U_0^2} (x) dx = 2\theta(x)$$

Therefore,

$$\frac{1}{2} \left(\frac{\tau_w}{\frac{1}{2} \rho U_0^2} \right) = \frac{d\theta}{dx}$$

Finally, momentum integral relation is obtained as

$$\frac{c_f}{2} = \frac{d\theta}{dx} \quad c_f = \text{local skin friction coefficient}$$

momentum integral relation for flat plate boundary layer

Approximate solutions for a **laminar** boundary layer obtained from momentum integral analysis:

	Exact Blasius	
$\delta = \frac{4.65x}{\sqrt{Re_x}}$	$\frac{5x}{\sqrt{Re_x}}$	7% ↓
$\tau_w = \frac{.323\rho V^2}{\sqrt{Re_x}}$	$\frac{.332\rho U^2}{\sqrt{Re_x}}$	3% ↓
$c_f = \frac{.646}{\sqrt{Re_x}}$	$\frac{.664}{\sqrt{Re_x}}$	
$C_f = \frac{1.29}{\sqrt{Re_L}}$	$\frac{1.33}{\sqrt{Re_L}}$	

Approximate solutions for a **turbulent** boundary layer obtained from momentum integral analysis:

$$\frac{\delta}{x} = .16 Re_x^{-1/7}$$

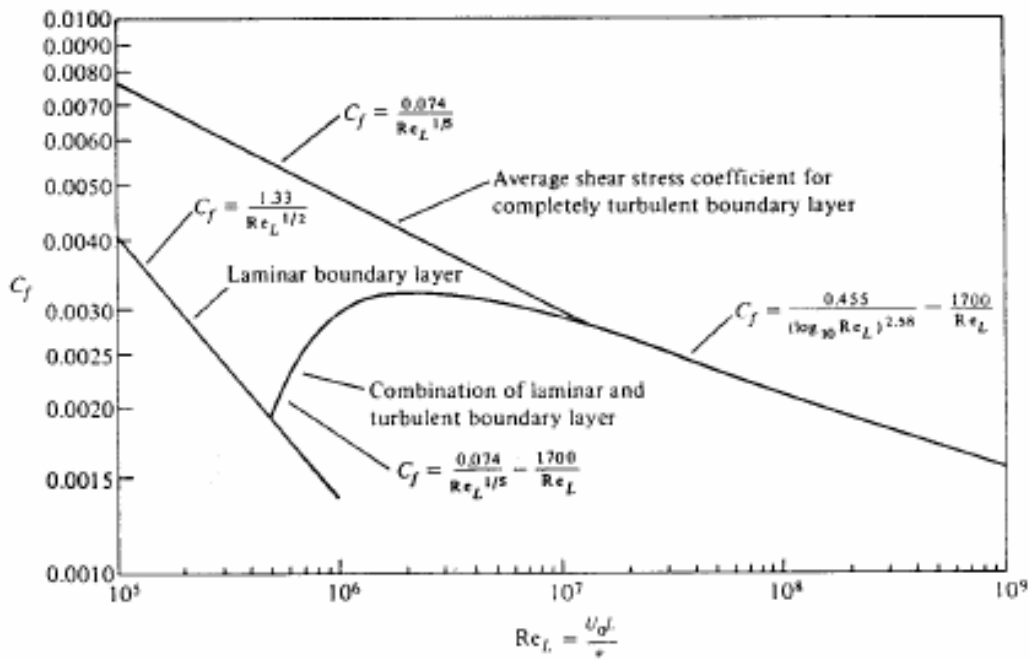
$$c_f = \frac{.027}{Re_x^{1/7}}$$

$$C_f = \frac{.031}{Re_L^{1/7}} = \frac{7}{6} C_f(L)$$

Total shear-stress coefficient	$C_f = \frac{.455}{(\log_{10} Re_L)^{2.58}} \frac{-1700}{Re_L}$	$Re > 10^7$
--------------------------------	---	-------------

$$\frac{\delta}{L} = c_f (.98 \log Re_L - .732)$$

Local shear-stress coefficient	$c_f = (2 \log Re_x - .65)^{-2.3}$
--------------------------------	------------------------------------



C_f vs Re_L relationship in laminar and turbulent boundary layer

Drag of 2D bodies

Flat-plate parallel to the flow:

$$C_{Dp} = \frac{1}{\frac{1}{2}\rho V^2 A^s} \int (p - p_\infty) \underline{n} \cdot \underline{i} = 0$$

$$C_f = \frac{1}{\frac{1}{2}\rho V^2 A^s} \int \tau_w \underline{t} \cdot \hat{i} dA$$

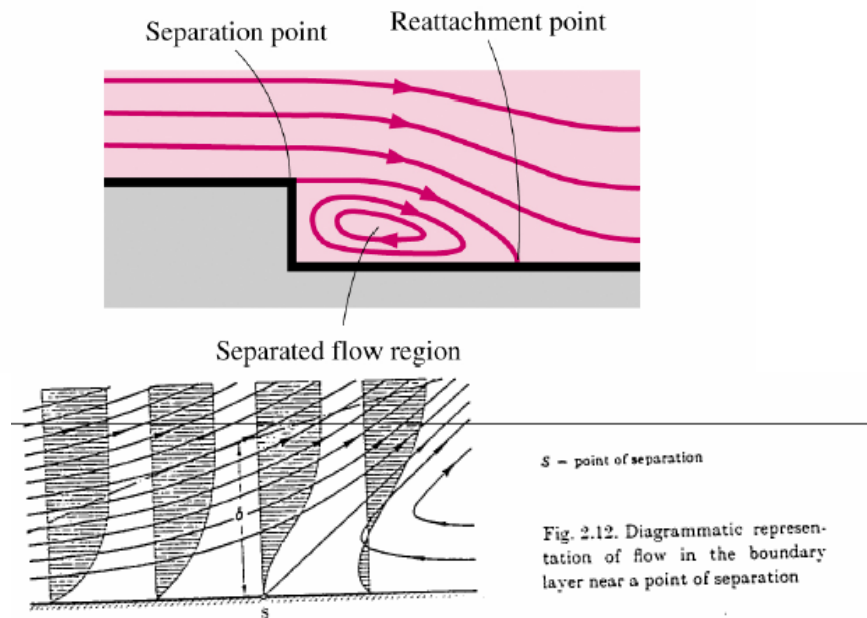
$$= \frac{1.33}{Re_L^{1/2}} \quad \text{laminar flow}$$

$$= \frac{.074}{Re_L^{1/5}} \quad \text{turbulent flow}$$

Flow separation:

→ The fluid stream detaches itself from the surface of the body at sufficiently high velocities. Only appeared in **viscous flow**!!

Flow separation forms the region called 'separated region'



Drag coefficients in common geometries:

Table 7.2
DRAG OF TWO-DIMENSIONAL BODIES AT $Re = 10^3$

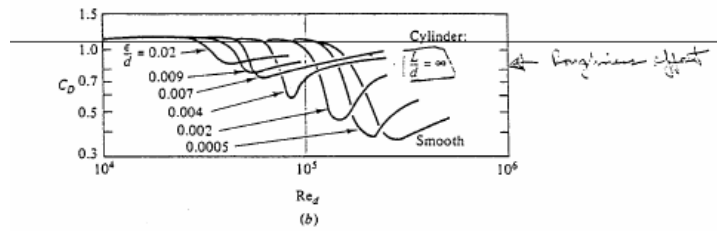
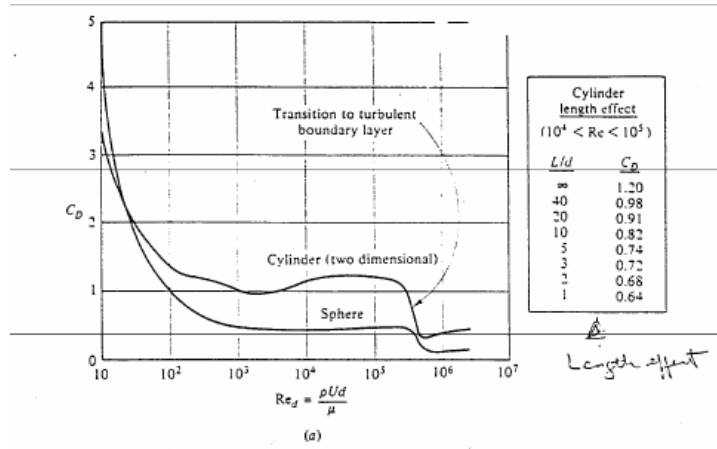
Shape	C_D based on frontal area	Shape	C_D based on frontal area
Plate:		Half-cylinder:	
	2.0		1.2
Square cylinder:			
	2.1		1.7
	1.6	Equilateral triangle:	
Half tube:			1.6
	1.2		2.0
	2.3		

Table 7.3
DRAG OF THREE-DIMENSIONAL BODIES AT $Re \approx 10^3$

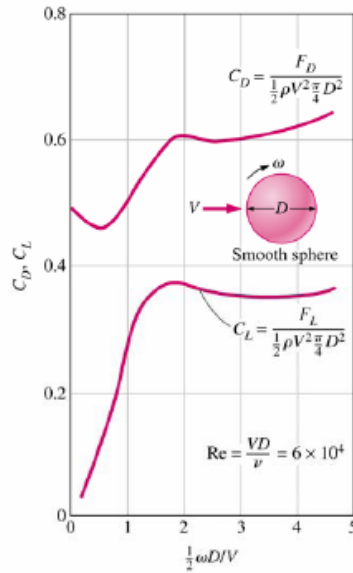
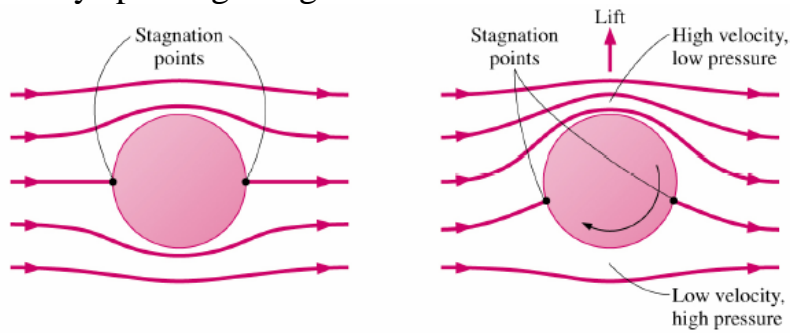
Body	Ratio	C_D based on frontal area
Cube:		
		1.07
		0.81
60° cone:		
		0.5
Disk:		
		1.17
Cup:		
		1.4
		0.4
Parachute (low porosity):		
		1.2

Flow over cylinder and spheres:

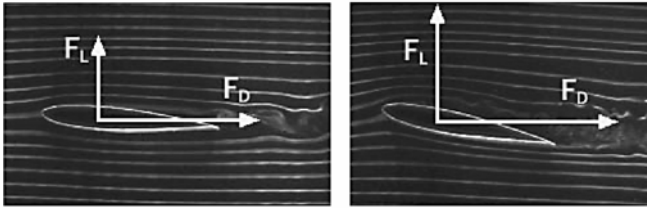
- $Re < 1$: Creeping flow, $C_D = 24/Re$, No-flow separation regime
- $10^5 < Re < 10^6$: boundary layer become turbulent, large reduction in C_D



Lift generation by spinning: Magnus effect



Lift acting on the airfoil;



Minimum flight velocity :

$$V_{\min} = \sqrt{\frac{2W}{\rho C_{L,\max} A}}$$

