

**System Reliability**

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System Reliability is the probability that the system will *not fail* to perform

- within specified limits
- for a specified period of time
- in a specified environment

Define the *random variable*

$$T_{sys} = \text{effective lifetime of system}$$

with *distribution function*

$$F_{sys}(t) = P\{T_{sys} \leq t\}$$

The *reliability* function is the complement of  $F_{sys}$ , i.e.,

$$\begin{aligned} R_{sys}(t) &= 1 - F_{sys}(t) \\ &= P\{T_{sys} > t\} \\ &= P\{\text{system is properly functioning at time } t\} \end{aligned}$$

**System Reliability**

Suppose that we know the reliabilities of the individual components of the system.

*How do we estimate the reliability of the system?*

**System Reliability**

- ☞ Components in Series
- ☞ Components in Parallel (Redundancy)
- ☞ Partially Redundant System (m-out-of-n)
- ☞ Examples: Systems with both series & parallel components

Standby System

- ☞ -with Perfect Switching
- ☞ -with Imperfect Switching
- ☞ -with Failures in Standby Mode
- ☞ - etc.



$$\begin{aligned} R_s(t) &= \text{reliability of device} \\ &= P\{\text{all components survive until time } t\} \\ &= P\{\text{component \#1 survives until time } t\} \times \\ &\quad P\{\text{component \#2 survives until time } t\} \\ &= R_1(t) \times R_2(t) \end{aligned}$$

In general, for n components in series,

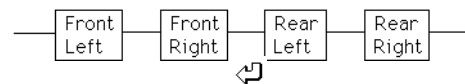
$$R_s(t) = R_1(t) \times R_2(t) \times \dots \times R_n(t)$$

**Series**

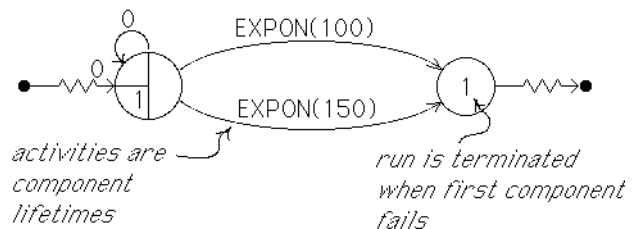
- Any component may fail independently of any other
- When one component fails, the system (device) fails



Example: an automobile "fails" when any one of its tires fail

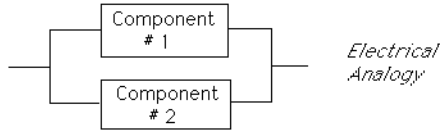


**SLAM model of series system**



**Parallel**

- Components operate simultaneously (*not "standby"*)
- All components must fail in order that the system fails

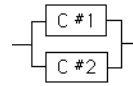


Example: a 2-engine plane fails only if both of its engines fail



Let  $F_i(t) = 1 - R_i(t)$

= P{component #i fails before time t}  
*(cumulative distribution function of the component's lifetime)*



$$F_p(t) = P\{\text{parallel system fails before time } t\}$$

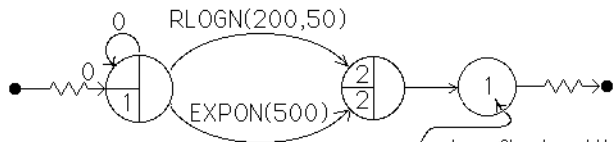
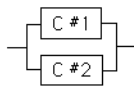
$$= P\{\text{all components fail before time } t\}$$

$$= P\{\text{component \#1 fails before time } t\} \times P\{\text{component \#2 fails before time } t\}$$

$$= F_1(t) \times F_2(t) = [1 - R_1(t)] \times [1 - R_2(t)]$$

So  $R_p(t) = 1 - F_p(t) = 1 - [1 - R_1(t)] \times [1 - R_2(t)]$

**SLAM model of system with parallel components**



*ACCUMULATE node releases entity when both components have failed*

*when first entity arrives, the run is terminated*

**Partially Redundant System**

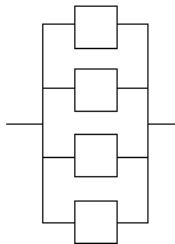
Suppose that **m** out of **n** identical components must function in order for the system to function. This represents "compromise" between the two extremes

- series system, requiring all components
- parallel system, requiring only one component

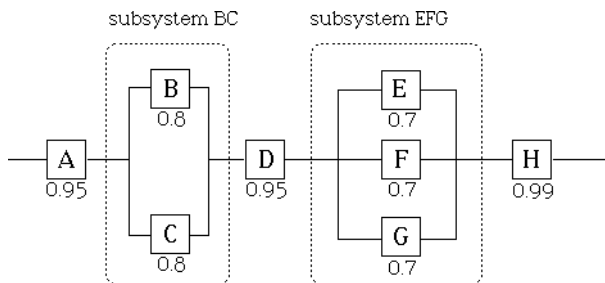
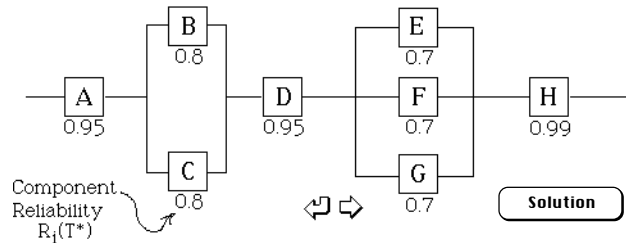


**Example**

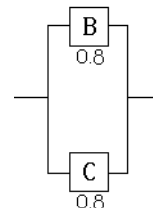
Suppose that the system consists of 4 identical components, and requires 3 of them to function in order for the system to properly function.



*Suppose that a system is designed to fulfill its mission for a planned lifetime T\*. Find the reliability of the system, given the component reliabilities:*



subsystem BC



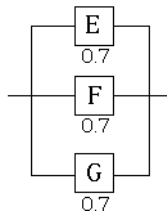
$$R_{BC} = 1 - [1 - R_B] \times [1 - R_C]$$

$$= 1 - 0.2 \times 0.2$$

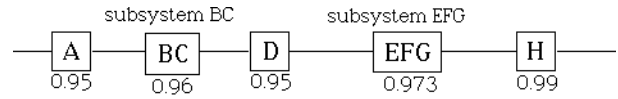
$$= 1 - 0.04$$

$$= 0.96$$

subsystem EFG



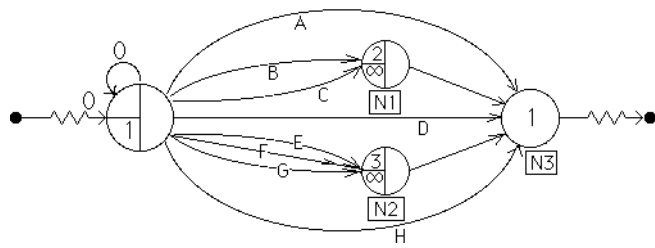
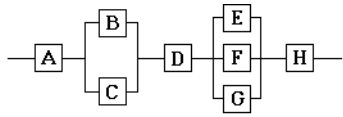
$$\begin{aligned}
 R_{EFG} &= 1 - [1 - R_E] \times [1 - R_F] \times [1 - R_G] \\
 &= 1 - 0.3 \times 0.3 \times 0.3 \\
 &= 1 - 0.027 \\
 &= 0.973
 \end{aligned}$$



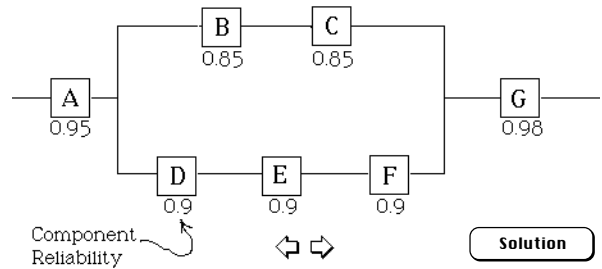
Reliability of series:

$$\begin{aligned}
 R_{system} &= R_A \times R_{BC} \times R_D \times R_{EFG} \times R_H \\
 &= (0.95)(0.96)(0.95)(0.973)(0.99) \\
 &= 0.834577
 \end{aligned}$$

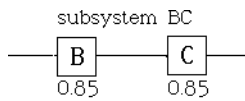
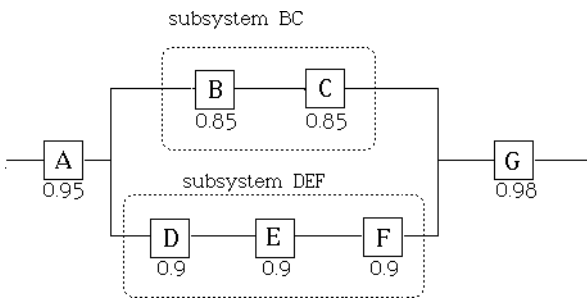
**SLAM model**



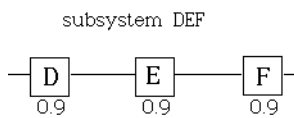
Find the reliability of the system:



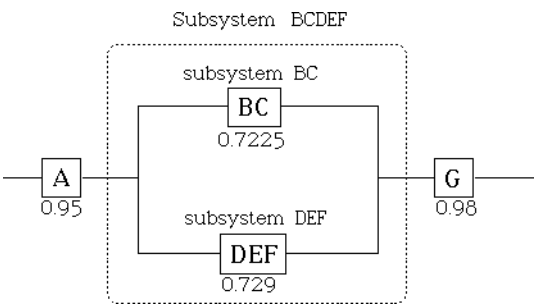
**Solution**



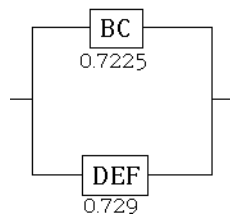
$$\begin{aligned}
 R_{BC} &= R_B \times R_C \\
 &= 0.85 \times 0.85 \\
 &= 0.7225
 \end{aligned}$$



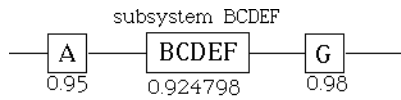
$$\begin{aligned}
 R_{DEF} &= R_D \times R_E \times R_F \\
 &= 0.9 \times 0.9 \times 0.9 \\
 &= 0.729
 \end{aligned}$$



Subsystem BCDEF



$$\begin{aligned}
 R_{BCDEF} &= 1 - [1 - R_{BC}] \times [1 - R_{DEF}] \\
 &= 1 - (1 - 0.7225)(1 - 0.729) \\
 &= 1 - (0.2775)(0.271) \\
 &= 1 - 0.075202 \\
 &= 0.924798
 \end{aligned}$$

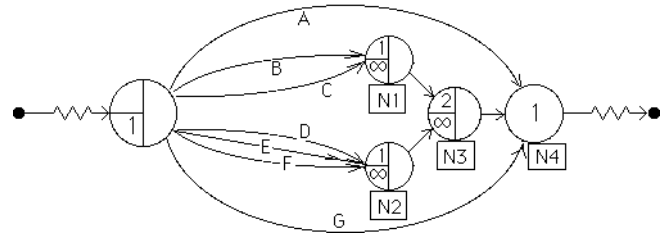
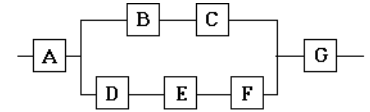


$$R_{\text{system}} = R_A \times R_{\text{BCDEF}} \times R_G$$

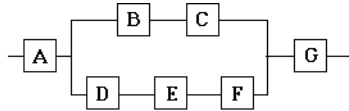
$$= (0.95)(0.924798)(0.98)$$

$$= 0.860987$$

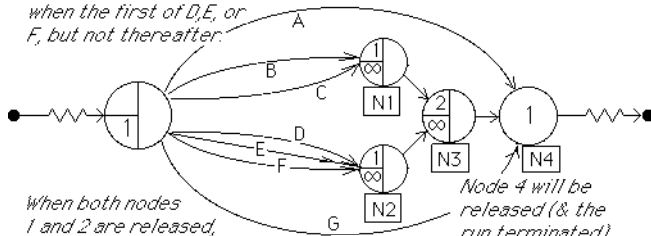
**SLAM model**



Node 1 will be released when the first of B or C fails, but not thereafter.



Node 2 will be released when the first of D, E, or F, but not thereafter.



When both nodes 1 and 2 are released, then node 3 will be released.

Node 4 will be released (& the run terminated) when A or G fail or node 3 is released.

Suppose that the component failure rates are constant, i.e., their lifetimes have exponential distributions:

Component	Mean Lifetime	R(100)
A	1950	95%
B	615	85%
C	615	85%
D	950	90%
E	950	90%
F	950	90%
G	4950	98%

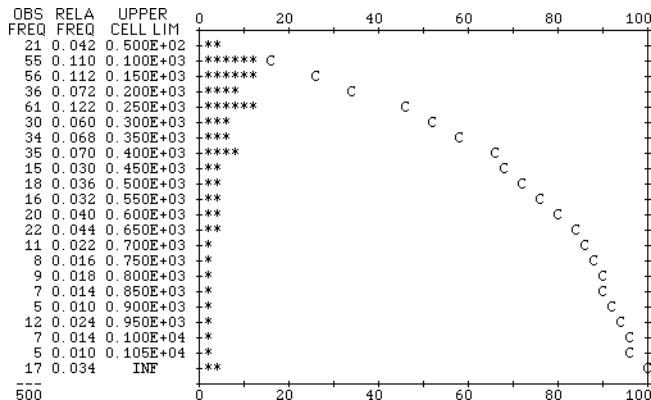
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GEN,BRICKER,SYSTEM RELIABILITY,4/16/92,500, ,NO,
,NO,YES/500,72;
LIM, ,1,10;
INIT, , ,NO;
NETWORK;
CREATE;
ACTIVITY/1,EXPON(1950), ,N4;    COMPONENT A
ACTIVITY/2,EXPON(615), ,N1;    COMPONENT B
ACTIVITY/3,EXPON(615), ,N1;    COMPONENT C
ACTIVITY/4,EXPON(950), ,N2;    COMPONENT D
ACTIVITY/5,EXPON(950), ,N2;    COMPONENT E
ACTIVITY/6,EXPON(950), ,N2;    COMPONENT F
ACTIVITY/7,EXPON(4950), ,N4;   COMPONENT G
N1 ACCUM,1,99;  RELEASE FIRST ARRIVAL ONLY
ACTIVITY, , ,N3;
ACTIVITY, , ,N3;  RELEASE FIRST ARRIVAL ONLY
    
```

**SLAM code**

\*\*STATISTICS FOR VARIABLES BASED ON OBSERVATION\*\*

	MEAN VALUE	STANDARD DEVIATION	COEFF. OF VARIATION	MINIMUM VALUE	MAXIMUM VALUE	NO. OF OBS
FAIL TIME	0.374E+03	0.300E+03	0.801E+00	0.579E+01	0.163E+04	500



Using the estimated mean and standard deviation from the simulation runs, we can compute the shape and scale parameters of the Weibull probability distribution:

Mean: 374, Standard deviation: 300  
 Parameters of distribution:  
 u=401.895 (scale), k=1.25471 (shape)

$$F(t) = 1 - e^{-(t/u)^k}$$

$$= 1 - e^{-(t/401.895)^{1.25471}}$$

t	F(t)	1-F(t)
50	0.0705536	0.929446
100	0.160197	0.839803
150	0.252016	0.747984
200	0.340715	0.659285
250	0.423745	0.576255
300	0.49987	0.50013
350	0.568608	0.431392
400	0.629939	0.370061
450	0.684124	0.315876
500	0.7316	0.2684
550	0.772899	0.227101
600	0.808594	0.191406
650	0.83927	0.16073
700	0.865496	0.134504
850	0.922661	0.0773395
1050	0.964444	0.0355564

$$F(t) = 1 - e^{-(t/401.895)^{1.25471}}$$

Next we calculate the probability of an observation falling in each interval, i.e.,

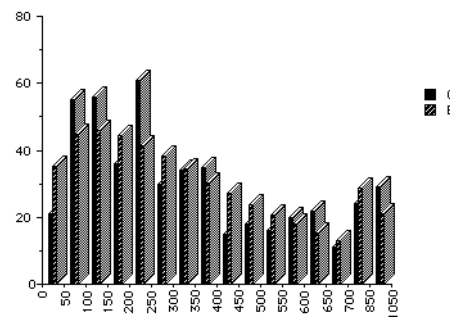
$$P_i = P\{t_{i-1} \leq X \leq t_i\} = F(t_i) - F(t_{i-1})$$

and multiply by N=500 to get the expected number of observations in each cell.

i	upper limit of cell	P <sub>i</sub>	E <sub>i</sub>	O <sub>i</sub>	D <sub>i</sub>
1	50	0.0705	35.2767	21	5.7779
2	100	0.0896	44.8217	55	2.3112
3	150	0.0918	45.9095	56	2.2177
4	200	0.0886	44.3496	36	1.5719
5	250	0.0830	41.5147	61	9.1455
6	300	0.0761	38.0624	30	1.7078
7	350	0.0687	34.3691	34	0.0039
8	400	0.0613	30.6651	35	0.6127
9	450	0.0541	27.0927	15	5.3975
10	500	0.0474	23.7381	18	1.3870
11	550	0.0412	20.6491	16	1.0467
12	600	0.0356	17.8476	20	0.2595
13	650	0.0306	15.3380	22	2.8935
14	700	0.0262	13.1128	11	0.3404
15	850	0.0571	28.5823	24	0.7346
16	1050	0.0417	20.8915	29	3.1470
17	∞	0.0355	17.7781	17	0.0340
SUM		1.000000	500	500	38.5898

$$D_i = \frac{(E_i - O_i)^2}{E_i}$$

Observed and Expected Frequencies



The number of degrees of freedom is

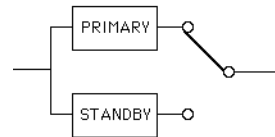
$$\begin{aligned} &17 \text{ cells} \\ &-1 \text{ (dependence on \# runs)} \\ &-2 \text{ (parameters estimated)} \\ \hline &= 14 \end{aligned}$$

The Chi-Square Probability table indicates that  $P\{D \geq 23.685\} = 5\%$ ,  $P\{D \geq 29.141\} = 1\%$ ,  $P\{D \geq 36.123\} = 0.1\%$ , etc.

That is, if the assumed Weibull distribution were valid, there is less than 0.1% probability that we would observe the value  $D=38.5898$ . It is therefore reasonable to reject this distribution!

**Standby System with Perfect Switching**

One or more components are in a standby mode ready to be activated when the operating component fails.



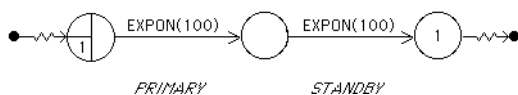
This requires a failure sensing/switching device which will bring the standby unit into operation

*Assume this device does not fail!*

**SLAM model**

Suppose both the primary and standby component have lifetimes with

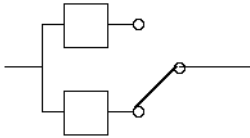
exponential distribution, with expected time of failure of 100 days.



*In this instance, the lifetime of the system is the sum of the lifetimes of the two units, which (because the sum of two exponentially distributed random variables has Erlang-2 distribution) is easily determined, and a simulation model may have little utility.*

*However, in most cases, it is quite difficult to determine the distribution of the sum of two random lifetime distributions, and simulation may be extremely useful!*

**Standby System with Imperfect Switching**

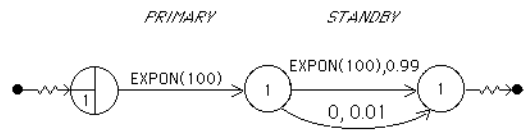


One or more components are in a standby mode ready to be activated when the operating component fails. This requires a failure sensing/switching device which will bring the standby unit into operation. Suppose that this device fails to detect the failure with probability  $p_s$



**SLAM model**

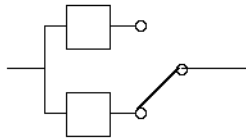
Suppose the switch fails with probability  $p_s = 1\%$



With 1% probability, the entity arriving at the GOON node will exit via the activity with zero duration, and the simulation will immediately terminate!

**Standby System with Failures in Standby Mode**

Suppose that while in standby mode, the components may also fail



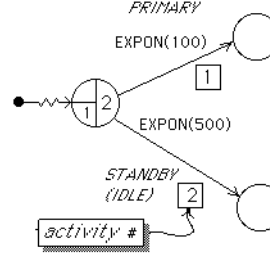
$R_1(t)$  = reliability of first component  
 $R_2^1(t)$  = reliability of standby unit while idle  
 $R_2^0(t)$  = reliability of standby unit in operation



**SLAM model**

Suppose expected lifetime while idle is 500 days:

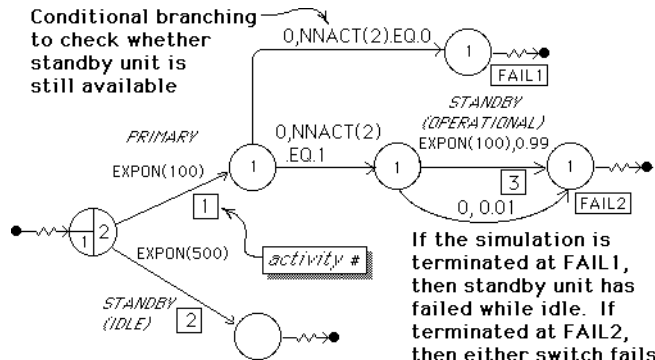
Initially, both activity 1 (representing lifetime of primary component) and activity 2 (representing idle lifetime of the standby unit) begin.



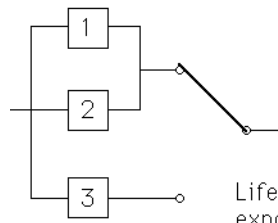
If activity 1 is completed (i.e., primary component dies) before activity 2 is completed, then the standby unit will be available for use.

If activity 2 is completed before activity 1, then when activity 1 is completed, there is no standby unit available & system fails.

**Conditional branching to check whether standby unit is still available**



If the simulation is terminated at FAIL1, then standby unit has failed while idle. If terminated at FAIL2, then either switch fails or standby unit while in use.



Suppose that components 1 & 2 operate as the primary system, with #3 used as a standby to be used when both #1 & #2 have failed. The switching device is 99% reliable.

Lifetimes of the components have exponential distribution, with failure rates  $\lambda_o = 0.01/\text{hr}$  for #1, 2, & 3 in operation, and  $\lambda_i = 0.001$  per hour for #3 when idle.

