

**56:271 Nonlinear Programming**  
**Quiz #3 – Fall 2003**

Indicate whether true (+) or false (o):

- \_\_\_ 1. A function which has more than one local minimum cannot be convex.
- \_\_\_ 2. The Hessian matrix evaluated at a local minimum must be positive semidefinite.
- \_\_\_ 3. Newton's method for minimization requires the computation of second partial derivatives.
- \_\_\_ 4. The Newton-Raphson method for solving nonlinear equations requires the computation of second partial derivatives.
- \_\_\_ 5. Newton's method with linesearch for minimization requires the computation of second partial derivatives.
- \_\_\_ 6. Quasi-Newton methods for minimization requires the computation of second partial derivatives.
- \_\_\_ 7. Two successive directions used by Newton's method will be orthogonal (perpendicular).
- \_\_\_ 8. Two successive directions used by the steepest descent method will be orthogonal (perpendicular).
- \_\_\_ 9. If minimizing a quadratic function of  $n$  variables, Newton's method will require  $n$  iterations.
- \_\_\_ 10. If minimizing a quadratic function of  $n$  variables, the steepest descent method will require no more than  $n$  iterations.

Match the formula used by the algorithms below for computing the search direction from  $x^t$  at iteration  $t$ .

- \_\_\_ 11. Newton's method
- \_\_\_ 12. Steepest Descent method
- \_\_\_ 13. Conjugate gradient (Fletcher-Powell) method
- \_\_\_ 14. Davidon-Fletcher-Powell (Quasi-Newton) method

a.  $d^t = \nabla f(x^t)$

b.  $d^t = -[\nabla^2 f(x^t)] \nabla f(x^t)$

c.  $d^t = -\nabla f(x^t) + \frac{\|\nabla f(x^t)\|^2}{\|\nabla f(x^{t-1})\|^2} d^{t-1}$

d.  $d^t = [\nabla^2 f(x^t)] \nabla f(x^t)$

e.  $d^t = -[\nabla^2 f(x^t)]^{-1} \nabla f(x^t)$

f.  $d^t = -Q \nabla f(x^t)$

g.  $d^t = -\nabla f(x^t)$

h.  $d^t = \nabla f(x^t) + d^{t-1}$

i.  $d^t = -\frac{\|\nabla f(x^t)\|^2}{\|\nabla f(x^{t-1})\|^2} \nabla f(x^t)$