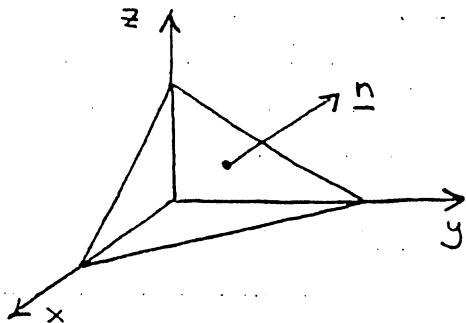


## 5-1. Isotropic Property of Pressure

Show that pressure is an isotropic stress.

Stress tetrahedron:



$S_0$  = area of slanted surface  
(with unit normal  $\underline{n}$ )

$P_i$  = pressure on surface  
normal to  $\underline{e}_i$

$P$  = pressure on slanted  
surface

What is desired is to show that  $P_x = P_y = P_z = P$ .

Start with stress equilibrium, eq. (5.3-16):

$$\lim_{S \rightarrow 0} \frac{1}{S} \int_S \underline{s}(\underline{n}) dS = 0$$

$$S_i = \text{area of surface normal to } \underline{e}_i = (\underline{n} \cdot \underline{e}_i) S_0 \quad (\text{eq. (5.3-19)})$$

$$\lim_{S \rightarrow 0} \frac{S_0}{S} \left[ \underline{s}(\underline{n}) + \sum_i (\underline{n} \cdot \underline{e}_i) \underline{s}(-\underline{e}_i) \right] = 0 \quad (\text{eq. (5.3-20)})$$

With pressure the only stress in a static fluid,

$$\underline{s}(\underline{n}) = -P \underline{n}, \quad \underline{s}(\underline{e}_i) = -P_i \underline{e}_i$$

From eq. (5.3-18),

$$\underline{s}(-\underline{e}_i) = -\underline{s}(\underline{e}_i)$$

$$\begin{aligned}
 0 &= \underline{s}(\underline{n}) + \sum_i (\underline{n} \cdot \underline{e}_i) \underline{s}(-\underline{e}_i) \\
 &= \underline{s}(\underline{n}) - \sum_i (\underline{n} \cdot \underline{e}_i) \underline{s}(\underline{e}_i) \\
 &= \underline{s}(\underline{n}) - \sum_i n_i \underline{s}(\underline{e}_i) \\
 &= -P_{\underline{n}} - \sum_i n_i (-P_i \underline{e}_i)
 \end{aligned}$$

$$P_{\underline{n}} = \sum_i P_i n_i \underline{e}_i$$

$$P \sum_i n_i \underline{e}_i = \sum_i P_i n_i \underline{e}_i$$

This will hold for arbitrary  $\underline{n}$  only if  $P_i = P$ . Q.E.D.

## 5-2. Transport of Vorticity

(a) Starting with the Navier-Stokes eq., show that

$$\frac{D\omega}{Dt} = \underline{\omega} \cdot \nabla \underline{v} + \nabla^2 \underline{\omega} \quad \text{where } \underline{\omega} = \nabla \times \underline{v}.$$

Expanding  $D\underline{v}/Dt$  and dividing by  $\rho$ , the N-S eq. [eq. 5.8-2] is

$$\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} = -\frac{1}{\rho} \nabla P + \nabla^2 \underline{v}$$

Take the curl ( $\nabla \times$ ) of each term:

$$\nabla \times \frac{\partial \underline{v}}{\partial t} = \frac{\partial}{\partial t} (\nabla \times \underline{v}) = \frac{\partial \omega}{\partial t}$$

$$\nabla \times (\underline{v} \cdot \nabla \underline{v}) = ? \quad [\text{see below}]$$

$$\nabla \times \left( \frac{1}{\rho} \nabla P \right) = \frac{1}{\rho} \nabla \times \nabla P = 0 \quad [(7) \text{ of Table A-1}]$$

$$\nabla \times (\nabla^2 \underline{v}) = \nabla \nabla \times (\nabla^2 \underline{v}) = ? \quad [\text{see below}]$$

Evaluation of  $\nabla \times (\underline{v} \cdot \nabla \underline{v})$ :

$$\begin{aligned} \underline{v} \cdot \nabla \underline{v} &= \nabla \left( \frac{\underline{v}^2}{2} \right) - \underline{v} \times (\nabla \times \underline{v}) \\ &= \nabla \left( \frac{\underline{v}^2}{2} \right) - \underline{v} \times \underline{\omega} \end{aligned} \quad \begin{array}{l} [(11) \text{ of Table A-1}, \\ \text{with } \underline{a} = \underline{b} = \underline{v} \end{array}$$

$$\nabla \times (\underline{v} \cdot \nabla \underline{v}) = \nabla \times \nabla \left( \frac{\underline{v}^2}{2} \right) - \nabla \times (\underline{v} \times \underline{\omega})$$

$$\nabla \times (\underline{v} \times \underline{\omega}) = \underline{\omega} \cdot \nabla \underline{v} - \underline{v} \cdot \nabla \underline{\omega} + \underline{v} (\nabla \cdot \underline{\omega}) - \underline{\omega} (\nabla \cdot \underline{v})$$

[(6) of Table A-1]

$$\nabla \cdot \underline{w} = \nabla \cdot (\nabla \times \underline{v}) = 0$$

[9] of Table A-1]

$$\therefore \nabla \times (\underline{v} \cdot \nabla \underline{v}) = \underline{v} \cdot \nabla \underline{w} - \underline{w} \cdot \nabla \underline{v}$$

Evaluation of  $\nabla \times (\nabla^2 \underline{v})$ :

$$\nabla^2 \underline{v} = \nabla \left( \nabla \cancel{\cdot} \underline{v} \right) - \nabla \times \left( \nabla \cancel{\times} \underline{v} \right)$$

[10] of Table A-1]

$$\nabla \times (\nabla^2 \underline{v}) = - \nabla \times (\nabla \times \underline{v})$$

$$= - \nabla \left( \nabla \cancel{\cdot} \underline{v} \right) + \nabla^2 \underline{v}$$

[10] of Table A-1]

$$\therefore \nabla \times (\nabla^2 \underline{v}) = \nabla^2 \underline{v}$$

Collecting all of the terms,

$$\frac{\partial \underline{w}}{\partial t} + \underline{v} \cdot \nabla \underline{w} - \underline{w} \cdot \nabla \underline{v} = \nabla \cdot \nabla^2 \underline{v}$$

$$\text{or } \frac{D \underline{w}}{Dt} = \underline{w} \cdot \nabla \underline{v} + \nabla \cdot \nabla^2 \underline{v} \quad \text{Q.E.D.}$$

(b) Show that for a planar flow, the result in (a) becomes

$$\frac{D\omega}{Dt} = \nu \nabla^2 \omega \quad \text{where } \omega = |\underline{\omega}|.$$

For either kind of planar flow,  $(x, y)$  or  $(r, \theta)$ , this is obtained from the  $\underline{z}$ -component of the eq. in (a):

$$\frac{D\omega}{Dt} = \underline{\omega} \cdot \underline{\nabla} \underline{\omega} + \nu \nabla^2 \underline{\omega} \quad [\text{general}]$$

$$\underline{\omega} = \omega_z \underline{e}_z = \omega \underline{e}_z \quad [\text{planar flow}]$$

$$\begin{aligned} \underline{e}_z \cdot \frac{D\omega}{Dt} &= \frac{D\omega}{Dt} \\ \underline{e}_z \cdot \nabla^2 \underline{\omega} &= \nabla^2 \omega \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad [\underline{e}_z = \text{const.}]$$

$$\underline{e}_z \cdot (\underline{\omega} \cdot \underline{\nabla} \underline{\omega}) = \underline{e}_z \cdot \left( \omega \frac{\partial \underline{\omega}}{\partial z} \right) = 0 \quad \left[ \underline{\omega} = \underline{\omega}(x, y, t) \text{ only} \right]$$

This completes the proof.

The simplified equation in (b) does not hold for axisymmetric flows because  $\underline{e}_i \neq \text{const.}$  in  $\underline{\omega} = \omega \underline{e}_i$ . That is,  $\underline{e}_i = \underline{e}_\theta$  for the  $(r, z)$  case and  $\underline{e}_i = \underline{e}_\phi$  for the spherical  $(r, \theta)$  case, and  $\underline{e}_\theta$  and  $\underline{e}_\phi$  both depend on position. As a result,  $\underline{\omega} \cdot \underline{\nabla} \underline{\omega} \neq 0$  and  $\underline{e}_i \cdot \nabla^2 \underline{\omega} \neq \nabla^2 \omega_i$ . The correct vorticity eq.s. for the axisymmetric cases are

$$\frac{D\omega_\theta}{Dt} = \frac{\omega_\theta v_r}{r} + \nu \left( \nabla^2 \omega_\theta - \frac{\omega_\theta}{r^2} \right) \quad [\text{cyl. } (r, z)]$$

$$\begin{aligned} \frac{D\omega_\phi}{Dt} &= \frac{\omega_\phi}{r \sin \theta} (v_r \sin \theta + v_\theta \cos \theta) \\ &\quad + \nu \left( \nabla^2 \omega_\phi - \frac{\omega_\phi}{r^2 \sin^2 \theta} \right) \quad [\text{spherical } (r, \theta)] \end{aligned}$$

(c) Derive the result in (b) from the stream function eqs.

From Table 5-11, for the planar  $(x, y)$  case:

$$\frac{\partial}{\partial t} (\nabla^2 \psi) - \left[ \frac{\partial \psi}{\partial x} \frac{\partial(\nabla^2 \psi)}{\partial y} - \frac{\partial \psi}{\partial y} \frac{\partial(\nabla^2 \psi)}{\partial x} \right] = \nu \nabla^4 \psi$$

Also, from the definition of  $\psi$  and from eq. (5.9-13a),

$$\frac{\partial \psi}{\partial x} = -v_y, \quad \frac{\partial \psi}{\partial y} = v_x, \quad \nabla^2 \psi = -w_z = -w$$

Substitute these into the stream function eq.:

$$\frac{\partial}{\partial t} (-w) - \left[ (-v_y) \left( -\frac{\partial w}{\partial y} \right) - v_x \left( -\frac{\partial w}{\partial x} \right) \right] = \nu \nabla^2 (-w)$$

$$\frac{\partial w}{\partial t} + v_x \frac{\partial w}{\partial x} + v_y \frac{\partial w}{\partial y} = \nu \nabla^2 w$$

$\underbrace{v \cdot \nabla w}$

$$\therefore \frac{\partial w}{\partial t} + \underline{v} \cdot \underline{\nabla} w = \frac{Dw}{Dt} = \nu \nabla^2 w.$$

The derivation for the planar  $(r, \theta)$  case is very similar:

$$\frac{\partial}{\partial t} (\nabla^2 \psi) - \frac{1}{r} \left[ \frac{\partial \psi}{\partial r} \frac{\partial(\nabla^2 \psi)}{\partial \theta} - \frac{\partial \psi}{\partial \theta} \frac{\partial(\nabla^2 \psi)}{\partial r} \right] = \nu \nabla^4 \psi$$

$$\frac{\partial \psi}{\partial r} = -v_\theta, \quad \frac{\partial \psi}{\partial \theta} = r v_r, \quad \nabla^2 \psi = -w_z = -w$$

$$\frac{\partial}{\partial t} (-w) - \frac{1}{r} \left[ -v_\theta \left( -\frac{\partial w}{\partial \theta} \right) - r v_r \left( -\frac{\partial w}{\partial r} \right) \right] = \nu \nabla^2 (-w)$$

$$\frac{\partial w}{\partial t} + \underbrace{v_r \frac{\partial w}{\partial r} + \frac{v_\theta}{r} \frac{\partial w}{\partial \theta}}_{\underline{v} \cdot \underline{\nabla} w} = \nabla \cdot \underline{\nabla} w$$

$$\frac{Dw}{Dt} = \nabla \cdot \underline{\nabla} w \quad (\text{as before}).$$

5-3. Velocity and Pressure Calculations

Given:  $u_x(x,y) = Cx^m$  in 2-D flow with  $\rho = \text{const.}$   
 $u_y(x,0) = 0$ ,  $P(0,0) = P_0$ .

(a) Determine  $u_y(x,y)$ . Use the continuity eq.:

$$\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} = 0$$

$$u_y(x,y) - u_y(x,0) = - \int_0^y \frac{\partial u_x}{\partial x} dy$$

$$\frac{\partial u_x}{\partial x} = Cm x^{m-1}$$

$$u_y = - Cm x^{m-1} y$$

(b) Determine values of  $m$  for which  $\underline{\omega} = 0$ .

$$\underline{\omega} = \nabla \times \underline{v} = \omega_z \underline{e}_z \text{ for } \underline{v}(x,y).$$

$$\omega_z = \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} = - Cm(m-1)x^{m-2}y$$

∴ Flow is irrotational ( $\omega_z = 0$ ) for arbitrary  $x$  and  $y$  only if  $m=0$  or  $m=1$ .

(C) Determine values of  $m$  that satisfy N-S eq. and find  $\Phi(x, y)$ .

Navier - Stokes :

$$\rho \frac{D\bar{v}}{Dt} = - \nabla \Phi + \mu \nabla^2 \bar{v}$$

$$\rho \frac{D\bar{v}}{Dt} = \rho \left( \frac{\partial \bar{v}}{\partial t} + \bar{v} \cdot \nabla \bar{v} \right) = \rho \bar{v} \cdot \nabla \bar{v} \quad \text{for steady flow}$$

$x$ -component :

$$\frac{\partial \Phi}{\partial x} = \mu \nabla^2 v_x - \rho \bar{v} \cdot \nabla v_x$$

$$\nabla^2 v_x = \frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} = C_m(m-1)x^{m-2}$$

$$\bar{v} \cdot \nabla v_x = v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} = (Cx^m)(Cm x^{m-1}) = C^2 m x^{2m-1}$$

$$\frac{\partial \Phi}{\partial x} = \mu C_m(m-1)x^{m-2} - \rho C^2 m x^{2m-1}$$

$$\Phi(x, y) = \mu C_m x^{m-1} - \frac{\rho C^2}{2} x^{2m} + f(y)$$

$y$ -component :

$$\frac{\partial \Phi}{\partial y} = \mu \nabla^2 v_y - \rho \bar{v} \cdot \nabla v_y$$

$$\nabla^2 v_y = \frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} = -C_m(m-1)(m-2)x^{m-3}y$$

5-3 (Cont.)

$$\begin{aligned}
 \underline{u} \cdot \nabla v_y &= u_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} \\
 &= (Cx^m)(-Cm(m-1)x^{m-2}y) + (-Cmx^{m-1}y)(-Cmx^{m-1}) \\
 &= -C^2 m(m-1)x^{2m-2}y + C^2 m^2 x^{2m-2}y \\
 &= C^2 m x^{2m-2}y [m - (m-1)] = C^2 m x^{2m-2}y
 \end{aligned}$$

$$\frac{\partial P}{\partial y} = -\mu C m (m-1)(m-2) x^{m-3} y - \rho C^2 m x^{2m-2} y$$

$$P(x, y) = -\frac{\mu C m (m-1)(m-2)}{2} x^{m-3} y^2 - \frac{\rho C^2 m}{2} x^{2m-2} y^2 + g(x)$$

Comparing the two expressions for  $P(x, y)$ , we conclude that they can be equal only if

$$-\frac{\mu C m (m-1)(m-2)}{2} x^{m-3} y^2 = f_1(y) \quad (i)$$

$$-\frac{\rho C^2 m}{2} x^{2m-2} y^2 = f_2(y) \quad (ii)$$

where  $f(y) = f_1(y) + f_2(y)$ . For (i) to hold we need  $m=0, 1, 2$  or  $3$ ; (ii) holds only if  $m=0$  or  $m=1$ .

Conclusion: The N-S eqn. is satisfied only if  $m=0$  or  $m=1$ ,

(These were also the values of  $m$  found to give irrotational flow.)

5-3 (cont.)

Calculate  $\Phi$  for  $m=0$ :

$$\left. \begin{array}{l} \Phi(x,y) = -\rho \frac{C^2}{2} + f(y) \\ \Phi(x,y) = g(x) \end{array} \right\} \rightarrow f(y) = \text{const.}, \quad g(x) = \text{const.}$$

$$\therefore \Phi(x,y) = \text{const.} = \Phi_0$$

Calculate  $\Phi$  for  $m=1$ :

$$\left. \begin{array}{l} \Phi(x,y) = \mu C - \rho \frac{C^2}{2} x^2 + f(y) \\ \Phi(x,y) = -\rho \frac{C^2}{2} y^2 + g(x) \end{array} \right\} \Rightarrow \begin{array}{l} f(y) = -\rho \frac{C^2}{2} y^2 + \text{const.} \\ g(x) = \mu C - \rho \frac{C^2}{2} x^2 + \text{const.} \end{array}$$

$$\therefore \Phi(x,y) = -\rho \frac{C^2}{2} (x^2 + y^2) + \text{const.}$$

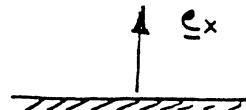
$$= \Phi_0 - \rho \frac{C^2}{2} (x^2 + y^2)$$

### 5-4. Normal Viscous Stress at a Surface

For a Newtonian fluid of const.  $\rho$  at an impermeable solid surface, show that the normal component of the viscous stress is zero.

Approach: Consider planar, cylindrical, and spherical surfaces. Fix coordinates on surface.

Planar:



$$\tau_{xx} = 2\mu \frac{\partial v_x}{\partial x} \quad (\text{Table 5-4})$$

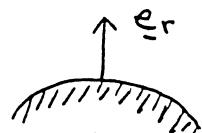
$$\nabla \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0 \quad (\text{continuity})$$

$$\left. \frac{\partial v_x}{\partial x} \right|_s = - \left( \left. \frac{\partial v_y}{\partial y} \right|_s + \left. \frac{\partial v_z}{\partial z} \right|_s \right)$$

$\uparrow$  at surface       $\downarrow$  no slip       $\downarrow$  no slip

$$\therefore \tau_{xx}|_s = 0$$

Cylindrical:



$$\tau_{rr} = 2\mu \frac{\partial v_r}{\partial r} \quad (\text{Table 5-5})$$

$$\nabla \cdot \vec{v} = \frac{1}{r} \frac{\partial}{\partial r} (r v_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} = 0$$

$$\frac{1}{r} \frac{\partial}{\partial r} (r v_r) = \frac{\partial v_r}{\partial r} + \frac{v_r}{r}$$

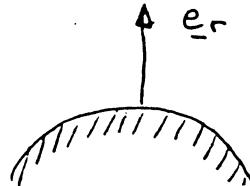
$$\frac{\partial v_r}{\partial r} \Big|_s = - \left( \frac{v_r}{r} \right) \Big|_s - \left( \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} \right) \Big|_s - \frac{\partial v_z}{\partial z} \Big|_s = 0$$

↓                      ↓                      ↓  
 0                      0                      0  
 no penetration      no slip      no slip

$$\therefore \tau_{rr} \Big|_s = 0$$

Spherical :

$$\tau_{rr} = 2\mu \frac{\partial v_r}{\partial r} \quad (\text{Table 5-6})$$



$$\nabla \cdot \underline{\underline{\sigma}} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

$$= 0$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) = \frac{\partial v_r}{\partial r} + \frac{2v_r}{r}$$

$$\frac{\partial v_r}{\partial r} \Big|_s = - \left( \frac{2v_r}{r} \right) \Big|_s - \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) - \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

↓                      ↓                      ↓  
 0                      0                      0  
 no penetration      no slip      no slip

$$\therefore \tau_{rr} \Big|_s = 0$$